

# Retake Exam

## Mathematical Methods of Bioengineering Ingeniería Biomédica - INGLÉS

21 of June 2019

*The maximum time to make the exam is 3 hours. You are allowed to use a calculator and two sheets with annotations. IMPORTANT: Question 2 A is only for “alumnos nuevo ingreso” and question 2 B is only for “alumnos veteranos”.*

### Problems

1. Consider the surface  $z = x^2 - 6x + y^3$ .
  - (a) (1 point) Find the tangent plane at the origin.
  - (b) (1 point) Find the point/s on the surface, where the tangent plane are parallel to the plane  $\pi : 4x - 12y + z = 7$ .

### SOLUTION

- (a) The formula for the tangent plane of a (explicit) function is:

$$z = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$$

Substituting at the origin,  $(a, b) = (0, 0)$ , we simplify to:

$$z = 0 + f_x(0, 0)(x - 0) + f_y(0, 0)(y - 0)$$

Now computing the partial derivative we get  $f_x(x, y) = 2x - 6$  and  $f_y(x, y) = 3y^2$ . So evaluating it at the origin,

$$z = 0 - 6(x - 0) + 0(y - 0) = -6x \quad (1)$$

$$z = -6x \quad (2)$$

- (b) We write the tangent plane formula in the same form as  $\pi$ :

$$\begin{aligned} -f_x(a, b)x - f_y(a, b)y + z &= D, & D &= f(a, b) - af_x(a, b) - bf_y(a, b) \\ 4x - 12y + z &= 7 \end{aligned}$$

Because the planes are parallel we conclude that,

$$\begin{aligned} 4 &= -f_x(a, b) = -(2a - 6) \rightarrow a = 1 \\ -12 &= -f_y(a, b) = -(3b^2) \rightarrow b = \pm\sqrt{4} = \pm 2 \end{aligned}$$

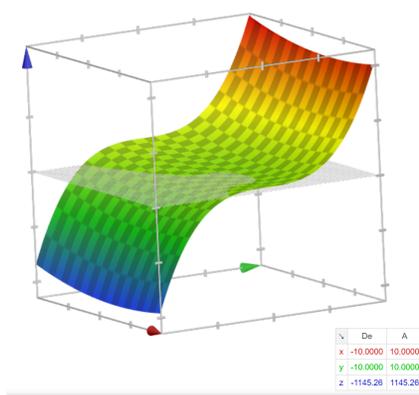


Figure 1: Surface from ex. 1.

2. **A.** Consider the function  $f(x, y) = \frac{\sin \pi x}{1 + y^2}$ .

- (a) **(1 point)** Find the critical points of  $f$ .  
 (b) **(1 point)** Find the extrema nature of the critical point  $(\frac{1}{2}, 0)$ .

**SOLUTION**

(a) We compute the gradient and find when it becomes  $\vec{0}$ .

$$\nabla f(x, y) = \left( \frac{\pi \cos \pi x}{1 + y^2}, \frac{-2y \sin \pi x}{(1 + y^2)^2} \right)$$

The denominator is always positive so the vector will be zero when the numerator is. For the first component,

$$\pi \cos \pi x = 0 \iff \cos \pi x = 0 \iff x = \frac{1}{2} + k, k \in \mathbb{Z}$$

For the second component,

$$-2y \sin \pi x = 0 \iff y = 0 \text{ or } \sin \pi x = 0$$

But  $\sin \pi x = \sin \pi(\frac{1}{2} + k) = \pm 1$  so to annul the first and second component of  $\nabla f$  at the same time,  $y = 0$ . So, there are infinite critical points of the form:

$$P_k = (\frac{1}{2} + k, 0), k \in \mathbb{Z}$$

(b) We need to compute the Hessian Matrix and apply the criterion. For that we compute the second order derivatives.

- $f_{xx} = \frac{-\pi^2 \sin \pi x}{1 + y^2}$
- $f_{xy} = \frac{-2\pi y \cos \pi x}{(1 + y^2)^2}$
- $f_{yy} = \frac{-2 \sin \pi x (1 + y^2)^2 - 2(1 + y^2)2y \cdot (-2y \sin \pi x)}{(1 + y^2)^4} = \dots = \frac{\sin \pi x [-2 + 6y^2]}{(1 + y^2)^3}$

Then,

$$H_f(x, y) = \begin{pmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{pmatrix} = \begin{bmatrix} \frac{-\pi^2 \sin \pi x}{1 + y^2} & \frac{-2\pi y \cos \pi x}{(1 + y^2)^2} \\ \frac{-2\pi y \cos \pi x}{(1 + y^2)^2} & \frac{\sin \pi x [-2 + 6y^2]}{(1 + y^2)^3} \end{bmatrix}.$$

At the given point,

$$H_f(1/2, 0) = \begin{pmatrix} -\pi^2 & 0 \\ 0 & -2 \end{pmatrix}.$$

Because  $d_1 = -\pi^2 < 0$  and  $d_2 = |H| = -\pi^2(-2) = 2\pi^2 > 0$  we conclude that is a local maximum.

**B.** An engineering is working with two mechanical arms with movements in a plane. To make a labor minimising the effort, he found that the optimal trajectories of the arm hands are  $\mathbf{m}_1(t) = (t^2 - 2, \frac{t^2}{2} - 1)$  and  $\mathbf{m}_2(t) = (t, 5 - t^2)$ , where  $t$  represents time measured in seconds. Before running the experiment, he simulated the trajectories and found out that collide.

- (a) (1 point) When and where do the arms collide?  
 (b) (1 point) What is the angle formed by the paths of the arms at the collision point?

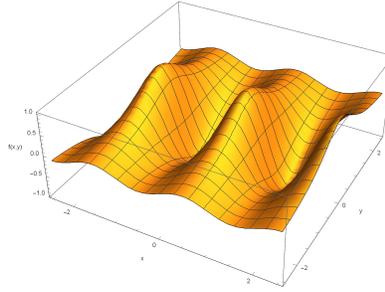


Figure 2: Function  $f(x, y) = \frac{\sin \pi x}{1 + y^2}$  from 2 A.

## SOLUTION

- (a) We have to intersect both paths to find the collision point,  $\mathbf{m}_1(t) = \mathbf{m}_2(t)$ . This yields in the following equations:

$$\begin{cases} t & = t^2 - 2 & \rightarrow t^2 - t - 2 = 0 & \rightarrow t = 2 \text{ or } -1 \\ 5 - t^2 & = \frac{t^2}{2} - 1 & \rightarrow 3t^2 = 12 & \rightarrow t = \pm 2 \end{cases}$$

So the only solution for both equations is  $t = 2$  s. Then the collision point is  $\mathbf{m}_1(2) = \mathbf{m}_2(2) = (2, 1)$ .

- (b) The direction of the path is given by the velocity vector (vector tangent to the path). At the collision point, this vectors are:

$$\begin{cases} \mathbf{m}_1'(t) = (2t, t) & \rightarrow \mathbf{m}_1'(2) = (4, 2) \\ \mathbf{m}_2'(t) = (1, -2t) & \rightarrow \mathbf{m}_2'(2) = (1, -4) \end{cases}$$

On the other hand, the dot product between two vectors is  $\langle a, b \rangle = \|a\| \|b\| \cos \theta$ . So,

$$\cos \theta = \frac{\langle a, b \rangle}{\|a\| \|b\|} = \frac{4 - 8}{\sqrt{20} \sqrt{17}} = -0.2169 \rightarrow \theta \approx 1.78 \text{ rad} \approx 102.52^\circ$$

3. (2 points) Suppose you are working doing artificial organs/tissues and you have a method to print in 3D materials with varying density. For a first test you decide to print a tissues that is modelled as the solid bounded by the surface  $z = 1 - x^2$  and the planes  $z = 0$ ,  $y = 1$  and  $y = -1$ , as shown in the next figure.

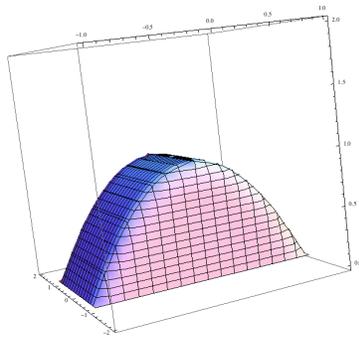


Figure 3: Artificial tissue.

Suppose also that the density is varying according to the function  $g(x, y, z) = z(x + 2)$ . Compute the total mass of the tissue.

### SOLUTION

We have to integrate the density function over the tissue region to get the total mass. The tissue is a region of type 1 in  $\mathbb{R}^3$ . It is delimited in the  $xy$ -plane (projection), as the statement says, by  $-1 \leq y \leq 1$  and  $x$  limits have to be found. Because, when making  $z = 0$  we get that  $0 = 1 - x^2 \rightarrow x = \pm 1$ ,  $x$  is also in  $[-1, 1]$ .

So the integration region is,

$$W = \{(x, y, z) \in \mathbb{R}^3 : -1 \leq x \leq 1, -1 \leq y \leq 1, 0 \leq z \leq 1 - x^2\}$$

Now we compute the mass,

$$\begin{aligned} M &= \iiint_W g \, dW = \int_{-1}^1 \int_{-1}^1 \left( \int_0^{1-x^2} z(x+2) \, dz \right) dy dx \\ &= \int_{-1}^1 \int_{-1}^1 \frac{(1-x^2)^2}{2} (x+2) \, dy dx = \dots = \frac{32}{15} \end{aligned}$$

4. (2 points) Evaluate  $\oint_C (x^4 y^5 - 2y) dx + (3x + x^5 y^4) dy$ , where  $C$  is the oriented curve pictured below.

### SOLUTION

Because is a closed curve in a vector field of class  $C^1$  we can apply the Green theorem. We note that the curve is oriented on the opposite sense of the Green theorem, so we have to add a minus in the equality.

We see that  $M(x, y) = x^4 y^5 - 2y$  and  $N(x, y) = 3x + x^5 y^4$ , so  $M_y = 5x^4 y^4 - 2$  and  $N_x = 3 + 5x^4 y^4$ . Let  $D$  be the region enclosed by the closed curve  $C$ . Then,

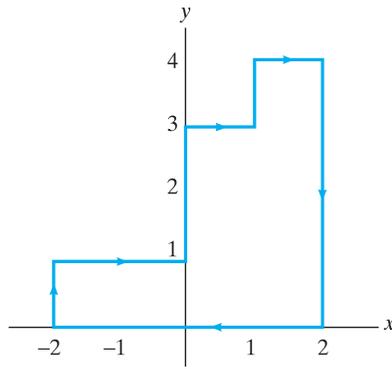


Figure 4: Oriented curve  $C$ .

$$\begin{aligned} \oint M dx + N dy &= - \iint_D (N_x - M_y) dx dy = - \iint_D (3 + 5x^4 y^4) - (5x^4 y^4 - 2) dx dy = \\ &= - \iint_D 5 dx dy = -5 \cdot \text{Area}(D) = -5(2 + 3 + 4) = -45 \end{aligned}$$

5. Consider the curve  $r(t) = (\cos t, \sin t, (a \cos t + b \sin t))$  with  $0 \leq t \leq 2\pi$ , where  $a, b \in \mathbb{R}$  are constants.
- (a) **(1 point)** Compute the work done by the vector field  $\mathbf{F} = (y, z - x, -y)$  in a particle moving along  $r$ .
- (b) **(1 point)** Compute the values of  $a, b$  such that the work done is null. Does this mean that the vector field is conservative? Reasonate the answer.

### SOLUTION

- (a) The work is,

$$\begin{aligned} W &= \int_r \mathbf{F} ds = \int_0^{2\pi} F(r(t)) \cdot r'(t) dt = \\ &= \int_0^{2\pi} (\sin t, a \cos t + b \sin t - \cos t, -\sin t) \cdot (-\sin t, \cos t, -a \sin t + b \cos t) dt = \\ &= \int_0^{2\pi} -\sin^2 t + a \cos^2 t + b \sin t \cos t - \cos^2 t + a \sin^2 t - b \sin t \cos t dt = \\ &= \int_0^{2\pi} a(\cos^2 t + \sin^2 t) - 1 dt = \int_0^{2\pi} a - 1 dt = 2\pi(a - 1) \end{aligned}$$

- (b)  $W = 0 \iff a = 1, b \in \mathbb{R}$ . It just mean that the work is zero over that path. To check that is conservative we may calculate the rotational,  $\text{rot}(\mathbf{F}) = (-2, 0, -2)$ . Because the rotational is not zero the vector field is not conservative.