

Sec. 7.5 / Vortex Lattice Method

$$+ \frac{1.0}{y_{1n} - y_m} \left[1.0 + \frac{x_m - x_{1n}}{\sqrt{(x_m - x_{1n})^2 + (y_m - y_{1n})^2}} \right] \\ - \frac{1.0}{y_{2n} - y_m} \left[1.0 + \frac{x_m - x_{2n}}{\sqrt{(x_m - x_{2n})^2 + (y_m - y_{2n})^2}} \right]$$

Summing the contributions of all the vortices to the downwash at the the m th panel,

$$w_m = \sum_{n=1}^{2N} w_{m,n}$$

Let us now apply the tangency requirement defined by equations (7.43). Since we are considering a planar wing in this section, $(dz/dx)_m = 0$ and $\phi = 0$. The component of the free-stream velocity perpendicular to the chord is zero, so the normal component of the free-stream velocity is also zero at any point on the wing. Thus, the resultant flow will be tangent to the chord at the control point of the m th panel, which implies that $w_m = 0$. This means that using equation (7.45) balances the normal component of the free-stream velocity at the control point.

$$w_m + U_\infty \sin \alpha = 0$$

For small angles of attack,

$$w_m = -U_\infty \alpha$$

In Example 7.2, we will solve for the aerodynamic coefficients for a relatively simple planform and an uncambered section. The vortex lattice method can be applied using only a single lattice element in the chordwise direction if the chordwise subdivision of the wing is sufficiently fine. Applying the boundary condition that the free-stream velocity passes through the wing at only one point in the chordwise direction is reasonable for a relatively simple planform such as a rectangular or semi-elliptical plate wing. However, it would not be adequate for a wing with camber or for a wing with deflected flaps.

EXAMPLE 7.2: Use the vortex lattice method (VLM) to calculate the aerodynamic coefficients for a swept wing

Let us use the relations developed in this section to calculate the aerodynamic coefficients for a swept wing. So that the calculation procedures can be followed, let us consider a wing that has a relatively simple geometry (the planform is illustrated in Fig. 7.31). The wing has an aspect ratio of 5, a root chord equal to the tail height (*i.e.*, $c_r = c_t$), and an uncambered section (*i.e.*, it is a flat plate). If the taper ratio is unity, the leading edge, the quarter-chord point, the mid-chord point, the quarter-chord line, and the trailing edge all have the same spanwise coordinate.

$$AR = 5 = \frac{b^2}{S}$$

and since for a swept, untapered wing

$$S = bc$$

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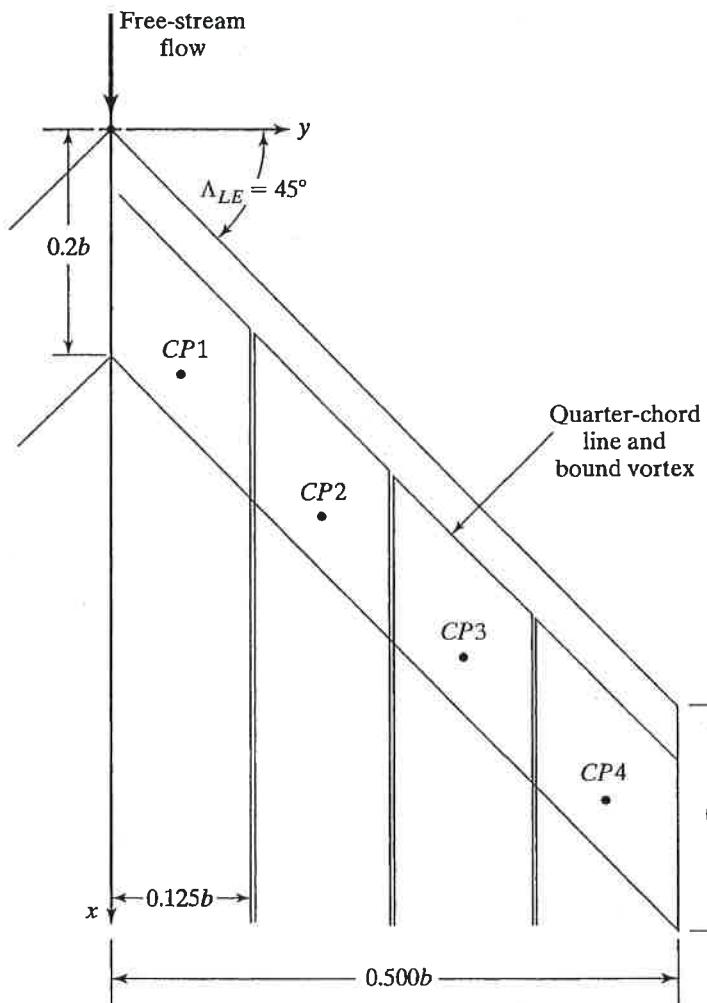


Figure 7.31 Four-panel representation of a swept planar wing, taper ratio of unity, AR = 5, $\Lambda = 45^\circ$.

it is clear that $b = 5c$. Using this relation, it is possible to calculate the necessary coordinates in terms of the parameter b . Therefore, it does not require that we know the physical dimensions of the wing.

Solution: The flow field under consideration is symmetric with respect to the (xz) plane; that is, there is no yaw. Thus, the lift force acting at a point on the starboard wing ($+y$) is equal to that at the corresponding point on $(-y)$. Because of symmetry, we need only to solve for the strengths of the vortices of the starboard wing. Furthermore, we need to apply the tangential condition [i.e., equation (7.47)] only at the control points of the starboard wing. However, we must remember to include the contributions of the vortices of the port wing to the velocities induced at these control points (on the starboard wing). Thus, for this planar symmetric flow, equation (7.47) becomes

$$w_m = \sum_{n=1}^N w_{m,ns} + \sum_{n=1}^N w_{m,np}$$

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where the symbols s and p represent the starboard and port wings, respectively.

The planform of the starboard wing is divided into four panels extending from the leading edge to the trailing edge. In order to reduce the number of panels to only four spanwise panels, we can calculate the horseshoe vortices using only a pocket electronic calculator. It is easier to more easily see how the terms are to be evaluated. As before, the portion of each horseshoe vortex coincides with the quarter-panel and the trailing vortices are in the plane of the wing, x_1 axis. The control points are designated by the solid symbols. Recall that $(x_m, y_m, 0)$ are the coordinates of a given control point and $(x_{1n}, y_{1n}, 0)$ and $(x_{2n}, y_{2n}, 0)$ are the coordinates of the bound-vortex filament AB . The coordinates for a 4×1 lattice (four spanwise divisions and one chordwise division) for the starboard wing are summarized in Table 7.2.

Using equation (7.44) to calculate the downwash velocity at panel 1 (of the starboard wing) induced by the horseshoe vortices of the starboard wing,

$$w_{1,1s} = \frac{\Gamma_1}{4\pi} \left\{ \frac{1.0}{(0.1625b)(-0.0625b) - (0.0375b)(0.0625b)} \right. \\ \left[\frac{(0.1250b)(0.1625b) + (0.1250b)(0.0625b)}{\sqrt{(0.1625b)^2 + (0.0625b)^2}} \right. \\ \left. - \frac{(0.1250b)(0.0375b) + (0.1250b)(-0.0625b)}{\sqrt{(0.0375b)^2 + (-0.0625b)^2}} \right. \\ \left. + \frac{1.0}{-0.0625b} \left[1.0 + \frac{0.1625b}{\sqrt{(0.1625b)^2 + (0.0625b)^2}} \right] \right. \\ \left. - \frac{1.0}{0.0625b} \left[1.0 + \frac{0.0375b}{\sqrt{(0.0375b)^2 + (-0.0625b)^2}} \right] \right\} \\ = \frac{\Gamma_1}{4\pi b} (-16.3533 - 30.9335 - 24.2319)$$

TABLE 7.2 Coordinates of the Bound Vortices and of the Control Points of the Starboard (Right) Wing

Panel	x_m	y_m	x_{1n}	y_{1n}	x_{2n}
1	$0.2125b$	$0.0625b$	$0.0500b$	$0.0000b$	$0.1750b$
2	$0.3375b$	$0.1875b$	$0.1750b$	$0.1250b$	$0.3000b$
3	$0.4625b$	$0.3125b$	$0.3000b$	$0.2500b$	$0.4250b$
4	$0.5875b$	$0.4375b$	$0.4250b$	$0.3750b$	$0.5500b$

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Note that, as one would expect, each of the vortex elements inductive (downward) component of velocity at the control point should visualize the flow induced by each segment of the horseshoe vortex. It is also important to verify that a negative value for each of the components is incorrect. In addition, the velocity induced by the vortex trailing from panel 1 is greatest in magnitude. Adding the components together, we find

$$w_{1,1s} = \frac{\Gamma_1}{4\pi b} (-71.5187)$$

The downwash velocity at the CP of panel 1 (of the starboard wing) induced by the horseshoe vortex of panel 1 of the port wing is

$$\begin{aligned} w_{1,1p} &= \frac{\Gamma_1}{4\pi} \left\{ \frac{1.0}{(0.0375b)(0.0625b) - (0.1625b)(0.1875b)} \right. \\ &\quad \left[\frac{(-0.1250b)(0.0375b) + (0.1250b)(0.1875b)}{\sqrt{(0.0375b)^2 + (0.1875b)^2}} \right. \\ &\quad \left. - \frac{(-0.1250b)(0.1625b) + (0.1250b)(0.0625b)}{\sqrt{(0.1625b)^2 + (0.0625b)^2}} \right] \\ &\quad + \frac{1.0}{-0.1875b} \left[1.0 + \frac{0.0375b}{\sqrt{(0.0375b)^2 + (0.1875b)^2}} \right] \\ &\quad - \frac{1.0}{-0.0625b} \left[1.0 + \frac{0.1625b}{\sqrt{(0.1625b)^2 + (0.0625b)^2}} \right] \\ &= \frac{\Gamma_1}{4\pi b} [-6.0392 - 6.3793 + 30.9335] \\ &= \frac{\Gamma_1}{4\pi b} (18.5150) \end{aligned}$$

Similarly, using equation (7.44) to calculate the downwash velocity at the CP of panel 2 induced by the horseshoe vortex of panel 1 of the starboard wing, we obtain

$$\begin{aligned} w_{2,4s} &= \frac{\Gamma_4}{4\pi} \left\{ \frac{1.0}{(-0.0875b)(-0.3125b) - (-0.2125b)(-0.1875b)} \right. \\ &\quad \left[\frac{(0.1250b)(-0.0875b) + (0.1250b)(-0.1875b)}{\sqrt{(-0.0875b)^2 + (-0.1875b)^2}} \right. \\ &\quad \left. - \frac{(0.1250b)(-0.2125b) + (0.1250b)(-0.3125b)}{\sqrt{(-0.2125b)^2 + (-0.3125b)^2}} \right] \end{aligned}$$

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$$\begin{aligned}
 & + \frac{1.0}{0.1875b} \left[1.0 + \frac{-0.0875b}{\sqrt{(-0.0875b)^2 + (-0.1875)^2}} \right] \\
 & - \frac{1.0}{0.3125b} \left[1.0 + \frac{-0.2125b}{\sqrt{(-0.2125b)^2 + (-0.3125)^2}} \right] \\
 & = \frac{\Gamma_4}{4\pi b} [-0.60167 + 3.07795 - 1.40061] \\
 & = \frac{\Gamma_4}{4\pi b} (1.0757)
 \end{aligned}$$

Again, the student should visualize the flow induced by each segment. Note that the signs and the relative magnitudes of the components are indicated.

Evaluating all of the various components (or influence coefficients) we find that at control point 1

$$\begin{aligned}
 w_1 = \frac{1}{4\pi b} [& (-71.5187\Gamma_1 + 11.2933\Gamma_2 + 1.0757\Gamma_3 + 0.3775\Gamma_4) \\
 & + (+18.5150\Gamma_1 + 2.0504\Gamma_2 + 0.5887\Gamma_3 + 0.1875\Gamma_4)
 \end{aligned}$$

At CP 2,

$$\begin{aligned}
 w_2 = \frac{1}{4\pi b} [& (+20.2174\Gamma_1 - 71.5187\Gamma_2 + 11.2933\Gamma_3 + 1.0757\Gamma_4) \\
 & + (+3.6144\Gamma_1 + 1.1742\Gamma_2 + 0.4903\Gamma_3 + 0.1875\Gamma_4)
 \end{aligned}$$

At CP 3,

$$\begin{aligned}
 w_3 = \frac{1}{4\pi b} [& (+3.8792\Gamma_1 + 20.2174\Gamma_2 - 71.5187\Gamma_3 + 11.2933\Gamma_4) \\
 & + (+1.5480\Gamma_1 + 0.7227\Gamma_2 + 0.3776\Gamma_3 + 0.1875\Gamma_4)
 \end{aligned}$$

At CP 4,

$$\begin{aligned}
 w_4 = \frac{1}{4\pi b} [& (+1.6334\Gamma_1 + 3.8792\Gamma_2 + 20.2174\Gamma_3 - 71.5187\Gamma_4) \\
 & + (+0.8609\Gamma_1 + 0.4834\Gamma_2 + 0.2895\Gamma_3 + 0.1875\Gamma_4)
 \end{aligned}$$

Since it is a planar wing with no dihedral, the no-flow condition (7.47) requires that

$$w_1 = w_2 = w_3 = w_4 = -U_\infty \alpha$$

Thus

$$\begin{aligned}
 -53.0037\Gamma_1 + 13.3437\Gamma_2 + 1.6644\Gamma_3 + 0.6434\Gamma_4 = -U_\infty \alpha \\
 +23.8318\Gamma_1 - 70.3445\Gamma_2 + 11.7836\Gamma_3 + 1.3260\Gamma_4 = -U_\infty \alpha
 \end{aligned}$$

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$$+5.4272\Gamma_1 + 20.9401\Gamma_2 - 71.1411\Gamma_3 + 11.5112\Gamma_4 = -4$$

$$+2.4943\Gamma_1 + 4.3626\Gamma_2 + 20.5069\Gamma_3 - 71.3351\Gamma_4 = -4$$

Solving for $\Gamma_1, \Gamma_2, \Gamma_3$, and Γ_4 , we find that

$$\Gamma_1 = +0.0273(4\pi b U_\infty \alpha)$$

$$\Gamma_2 = +0.0287(4\pi b U_\infty \alpha)$$

$$\Gamma_3 = +0.0286(4\pi b U_\infty \alpha)$$

$$\Gamma_4 = +0.0250(4\pi b U_\infty \alpha)$$

Having determined the strength of each of the vortices under the boundary conditions that the flow is tangent to the surface at control points, the lift of the wing may be calculated. For wings with dihedral over any portion of the wing, all the lift is generated by stream velocity crossing the spanwise vortex filament, since there are no wash or backwash velocities. Furthermore, since the panels extend from the leading edge to the trailing edge, the lift acting on the n th panel is

$$l_n = \rho_\infty U_\infty \Gamma_n$$

which is also the lift per unit span. Since the flow is symmetric for the wing is

$$L = 2 \int_0^{0.5b} \rho_\infty U_\infty \Gamma(y) dy$$

or, in terms of the finite-element panels,

$$L = 2\rho_\infty U_\infty \sum_{n=1}^4 \Gamma_n \Delta y_n$$

Since $\Delta y_n = 0.1250b$ for each panel,

$$\begin{aligned} L &= 2\rho_\infty U_\infty 4\pi b U_\infty \alpha (0.0273 + 0.0287 + 0.0286 + 0.0250) \\ &= \rho_\infty U_\infty^2 b^2 \pi \alpha (0.1096) \end{aligned}$$

To calculate the lift coefficient, recall that $S = bc$ and b is the chord length of the wing. Therefore,

$$C_L = \frac{L}{q_\infty S} = 1.096\pi\alpha$$

Furthermore,

$$C_{L,\alpha} = \frac{dC_L}{d\alpha} = 3.443 \text{ per radian} = 0.0601 \text{ per degree}$$

Comparing this value $C_{L,\alpha}$ with that for an unswept wing (such as that presented in Fig. 7.14), it is apparent that an effect of sweepback is to increase the lift-curve slope.

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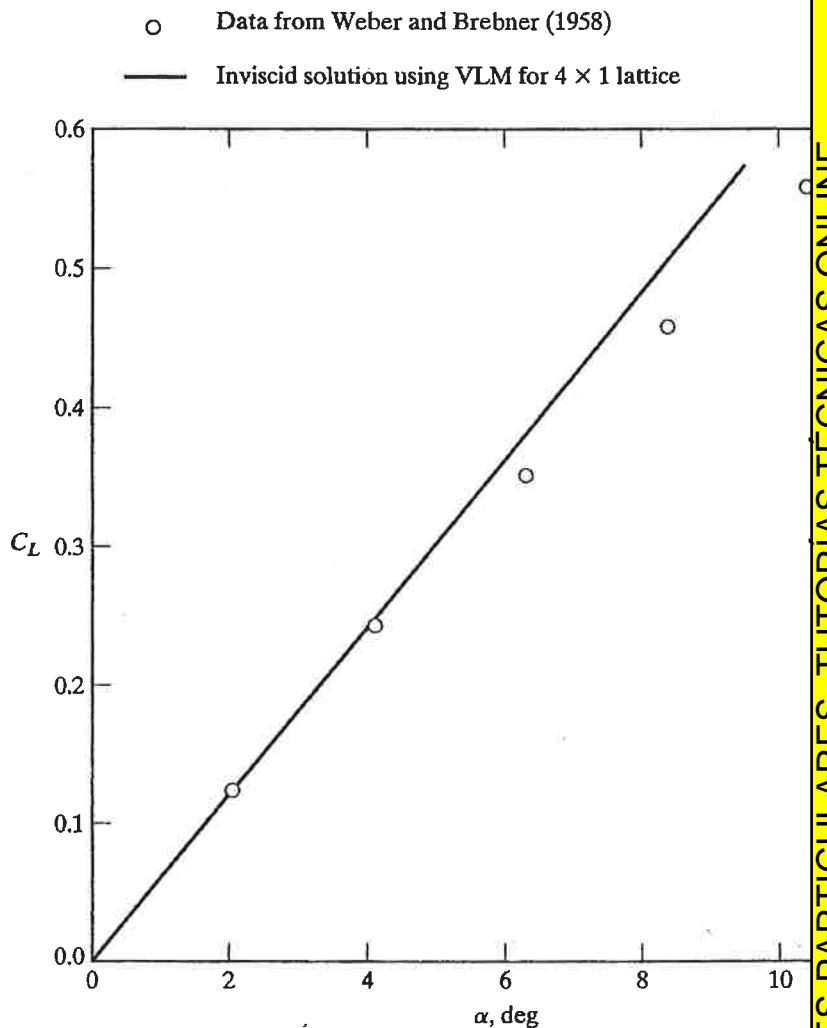


Figure 7.32 Comparison of the theoretical and the experimental lift coefficients for the swept wing of Fig. 7.31 in a subsonic stream.

The theoretical lift curve generated using the VLM is shown in Fig. 7.32 with experimental results reported by Weber and Brebner. The wing has a constant chord and of constant section, which was swept 45° at the trailing edge, with an aspect ratio of 5. The theoretical lift coefficients are in good agreement with the experimental values.

Since the lift per unit span is given by equation (7.49), the section lift coefficient for the n th panel is

$$C_{l(n\text{th})} = \frac{l_n}{\frac{1}{2}\rho_\infty U_\infty^2 c_{av}} = \frac{2\Gamma}{U_\infty c_{av}}$$

When the panels extend from the leading edge to the trailing edge, so that $c_{av} = c$, for the 4×1 lattice shown in Fig. 7.31, the value of Γ given in equation

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