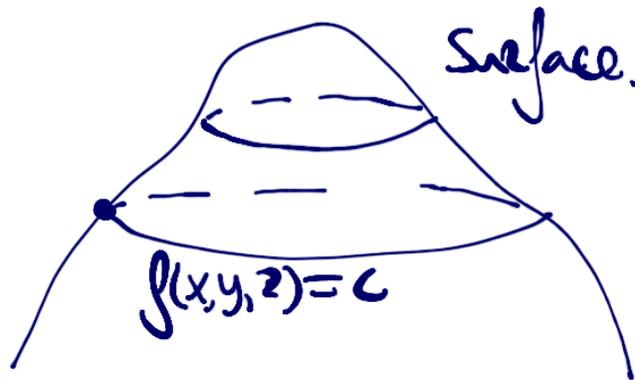


Proposition $f: \mathbb{R}^n \rightarrow \mathbb{R}$ diff. at x_0
 $\nabla f(x_0) \perp$ level curve of f at x_0 , $f(x) = f(x_0)$

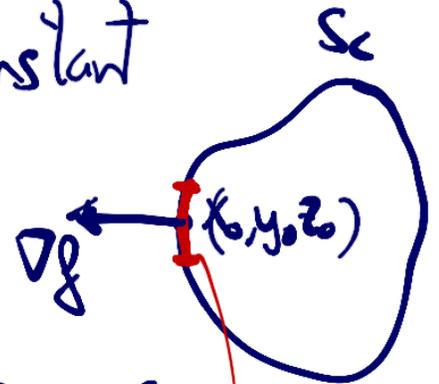
In \mathbb{R}^3 , $\nabla f(x, y, z) \neq (0, 0, 0)$



level curve

$S_c: f(x, y, z) = c$, $c \equiv \text{constant}$

Differentiating at (x_0, y_0, z_0)



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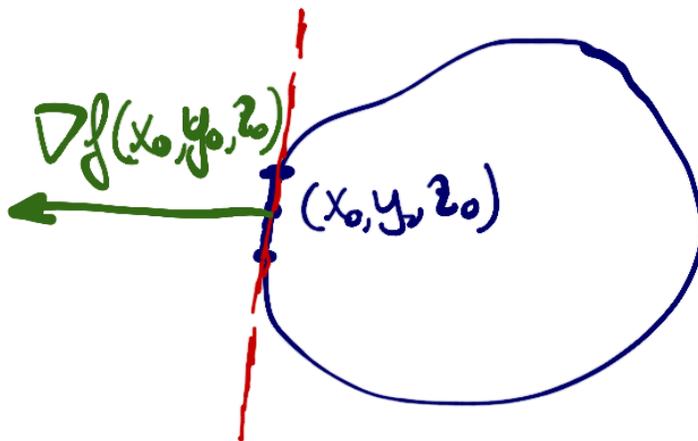
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are close to the curve S_c

To construct the tangent plane
to the surface
 $f(x, y, z)$
(two vectors or normal vector)

∇f is orthogonal to the level curve.
and if we are very close to (x_0, y_0, z_0)



we might construct
a vector on the
tangent plane. taking
two points

(x_0, y_0, z_0) and any arbitrary point
on the plane (x, y, z)

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Problem 11

iv) $\boxed{e^{xyz} = 1}$ at $(x_0, y_0, z_0) = (1, 2, 0)$

Tangent plane. $f(x, y, z) = e^{xyz}$

$$\nabla f(x, y, z) = (yz e^{xyz}, xz e^{xyz}, xy e^{xyz})$$

$$\nabla f(1, 2, 0) = (0, 0, 2)$$

Tangent plane to the surface

$$f(x, y, z) = e^{xyz}$$

at the level curve $f(x, y, z) = 1$

will be

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xx

yy

zz

$$2z = 0 \Rightarrow \boxed{z = 0}$$

Formula for a tangent plane of a function

$$f(x,y)$$

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

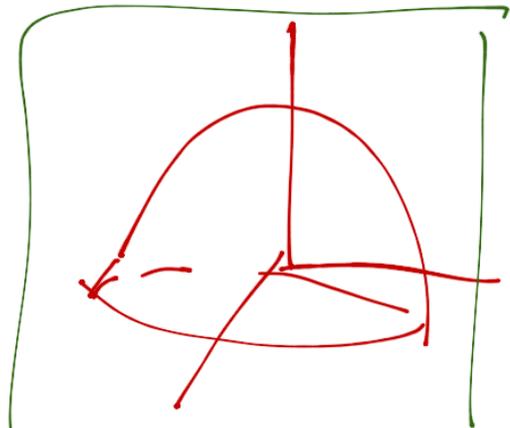
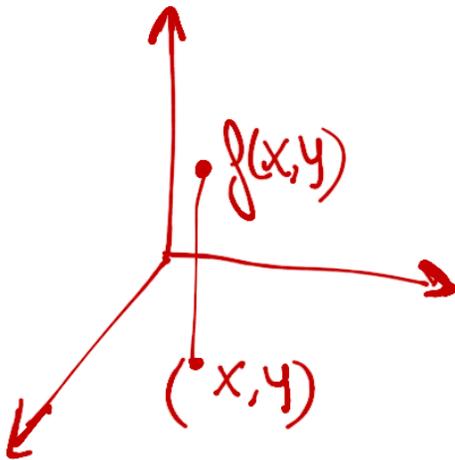
$$(x,y) \rightarrow f(x,y)$$

~

$$\boxed{z = f(x,y)}$$

surface.

Formula for the surface.



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Example: $f(x,y) = x^2 + y^2$ function.

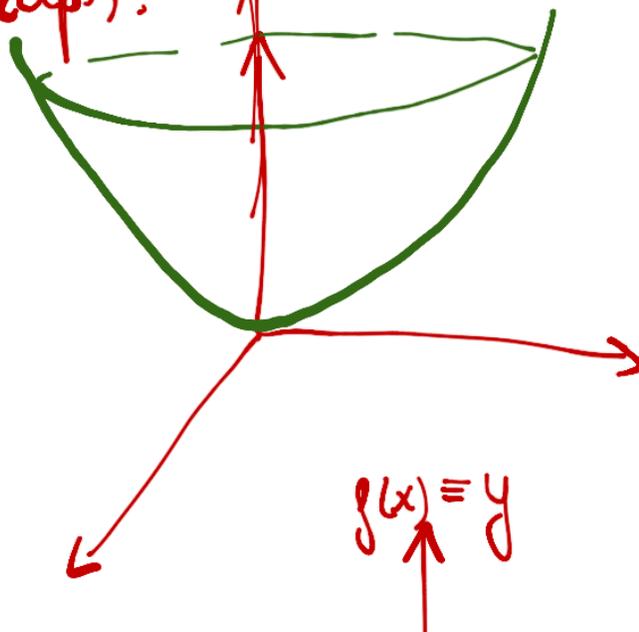
$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$(x,y) \rightarrow x^2 + y^2 = f(x,y)$$

Formula for the surface

$$z = f(x,y) = x^2 + y^2$$

Graph. $z = f(x,y) = z$



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$$z = f(x_0, y_0) + \frac{\partial f(x_0, y_0)}{\partial x} (x - x_0) + \frac{\partial f(x_0, y_0)}{\partial y} (y - y_0)$$

formula for a tangent plane to a function $f(x, y)$ at (x_0, y_0)

If $f(x, y) = z$

$f(x, y) - z = g(x, y, z)$ | surface.

$\nabla g(x, y, z) = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, -1 \right)$

at $(x_0, y_0, f(x_0, y_0))$ the tangent plane to the surface.

$\nabla g(x_0, y_0, f(x_0, y_0)) \cdot \begin{pmatrix} x - x_0 \\ y - y_0 \end{pmatrix} = 0$

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f differentiable, if (f is a function)
Tangent plane.

$$0 = \lim_{(x,y) \rightarrow (x_0,y_0)} \frac{f(x,y) - f(x_0,y_0) - \frac{\partial f(x_0,y_0)}{\partial x}(x-x_0) - \frac{\partial f(x_0,y_0)}{\partial y}(y-y_0)}{\|(x,y) - (x_0,y_0)\|}$$

Then, f is very close to the tangent plane at
 (x_0, y_0)

Theorem

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m, x_0 \in \mathbb{R}^n$$

f differentiable at $x_0 \Rightarrow f$ is continuous at x_0

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Theorem

$$\Lambda \subset \mathbb{R}^N, x_0 \in \Lambda, f: \Lambda \rightarrow \mathbb{R}$$

$$\left. \begin{array}{l} \text{a) } \exists \frac{\partial f}{\partial x_i} \text{ for any } i \\ \text{b) } \frac{\partial f}{\partial x_i} \text{ continuous at } x_0 \end{array} \right\} \Rightarrow f \text{ is diff. at } x_0.$$

Example: $f(x,y) = \frac{\cos x + e^{xy}}{x^2 + y^2}$ f differentiable at any point?

$$\frac{\partial f(x,y)}{\partial x} = \frac{(x^2 + y^2)(-\sin x + ye^{xy}) - (\cos x + e^{xy})2x}{(x^2 + y^2)^2}$$

$$\frac{\partial f(x,y)}{\partial y} = \frac{(x^2 + y^2)xe^{xy} - (\cos x + e^{xy})2y}{(x^2 + y^2)^2}$$

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because $\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}$ are not 0 at $(x,y) \neq (0,0)$

Proposition

$f, g: \Lambda \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$, $x_0 \in \Lambda$, $\lambda \in \mathbb{R}$.

diff.

Linearity for the private.

a) $\lambda f(x)$ diff. at x_0 and $D(\lambda f(x_0)) = \lambda Df(x_0)$

b) $f(x) + g(x)$ diff. at x_0 and
 $D(f(x_0) + g(x_0)) = Df(x_0) + Dg(x_0)$

c) $D(fg)(x_0) = Df(x_0)g(x_0) + f(x_0)Dg(x_0)$

d) $D\left(\frac{f}{g}\right)(x_0) = \frac{g(x_0)Df(x_0) - f(x_0)Dg(x_0)}{(g(x_0))^2}$

$g(x_0) \neq 0$

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Proposition - Chain rule

Let $f: \mathbb{R}^N \rightarrow \mathbb{R}^M$, $g: \mathbb{R}^M \rightarrow \mathbb{R}^K$

$$\mathbb{R}^N \xrightarrow{f} \mathbb{R}^M \xrightarrow{g} \mathbb{R}^K$$

$\xrightarrow{g \circ f}$

$$(g \circ f)(x) = g(f(x))$$

$$x_0 \in \mathbb{R}^N, f(x_0) \in \mathbb{R}^M$$

and $g \circ f$ differentiable at x_0

$$D(g \circ f)(x_0) = Dg(f(x_0)) \cdot Df(x_0)$$

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Example: Trajectory.

$$g: \mathbb{R} \rightarrow \mathbb{R}^3$$
$$t \rightarrow g(t) = (x(t), y(t), z(t))$$

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$\text{and } h(t) = \underbrace{f(g(t))}_{= f(x(t), y(t), z(t))}, \quad \frac{dh}{dt} ?$$

$$\frac{dh(t)}{dt} = \frac{\partial f}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt}$$

$$= Df(g(t)) \cdot \underbrace{g'(t)}_{\left(\frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt} \right)}$$

Example: $a(x,y) = (x^2 + 1, y^2)$ $g: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

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$\nabla g(x,y) = \text{matrix}$, $\nabla f(x,y,z) = \text{matrix}$

$$Df(u, v) = Jf(u, v) = \begin{pmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} \\ \frac{\partial f_3}{\partial u} & \frac{\partial f_3}{\partial v} \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 2v \end{pmatrix}$$

$$Dg(x, y) = Jg(x, y) = \begin{pmatrix} 2x & 0 \\ 0 & 2y \end{pmatrix}$$

at $(x, y) = (1, 1)$, $g(1, 1) = \underline{(2, 1)}$

$$\begin{aligned} D(f \circ g)(1, 1) &= Jf(g(1, 1)) \cdot Jg(1, 1) \\ &= Jf(2, 1) \cdot Jg(1, 1) \end{aligned}$$

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Chapter 2 - Local extrema

Higher-order derivatives

Partial derivatives of higher-order

$$\frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right)$$

$$\frac{\partial^2 f}{\partial y^2} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right)$$

Crossing derivatives

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right), \quad \frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right)$$

In general, $\frac{\partial^k f}{\partial x^k}$

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• We can say that $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is of class C^k if f and all its partial derivatives of order $i=1, \dots, k$ are continuous

If f is of class C^∞ , f is of class C^k for any $k \in \mathbb{N}$.
analytic functions.
 (exponentials, cosines, sines)

Example: $f(x, y, z) = e^{xy} + z \cos x$

$$\frac{\partial f}{\partial x} = y e^{xy} - z \sin x$$

$$\Rightarrow \frac{\partial^2 f}{\partial x^2} = y^2 e^{xy} - z \cos x$$

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∂^2

∂^2

$$\frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = xy e^{xy} + e^{xy}$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) = e^{xy} + xy e^{xy}$$

$$\frac{\partial^2 f}{\partial x \partial z} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial z} \right) = -\sin x$$

$$\frac{\partial^2 f}{\partial z \partial x} = \frac{\partial}{\partial z} \left(\frac{\partial f}{\partial x} \right) = -\sin x$$

Crossing derivatives are the same

This is due to equality of the first derivatives

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Schwarz's Theorem

regularity condition

$f: A \rightarrow \mathbb{R}^M$ and $A \subset \mathbb{R}^N$, $f \in C^1$

Then, if the second order derivatives exist we have that

$$\frac{\partial^2 f}{\partial x_i \partial x_j} = \frac{\partial^2 f}{\partial x_j \partial x_i} \quad \text{for any } 1 \leq i, j \leq N$$

$$x = (x_1, \dots, x_i, \dots, x_j, \dots, x_N)$$

• In $2D$ $f(x, y)$, $f \in C^1$ so $\frac{\partial f}{\partial x}$, $\frac{\partial f}{\partial y}$ cont.

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Local extrema

First we define what is a local maximum and minimum.

Definition - local extrema

Let $\mathcal{X} \subset \mathbb{R}^n$ be a set in \mathbb{R}^n such that

$x_0 \in \mathcal{X}$ and $f: \mathcal{X} \rightarrow \mathbb{R}$.

We say that f reaches its local maximum at x_0 in \mathcal{X} if there exists a neighborhood of x_0 , Ω such that

$$f(x) \leq f(x_0) \text{ for any } x \in \Omega \setminus \{x_0\}$$

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Definition

$\Omega \subset \mathbb{R}^N$, $x_0 \in \Omega$, $f: \Omega \rightarrow \mathbb{R}$.

We say that $x_0 \in \Omega$ is a stationary point or critical point

for f if

$$\frac{\partial f(x_0)}{\partial x_i} = 0 \quad \text{for any } 1 \leq i \leq N$$

In other words

$$\nabla f(x_0) = 0$$

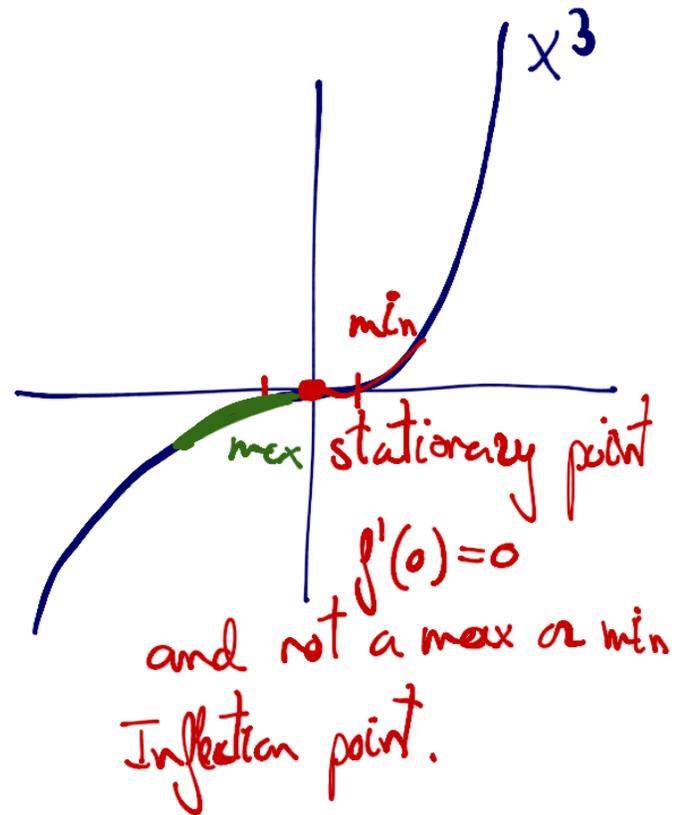
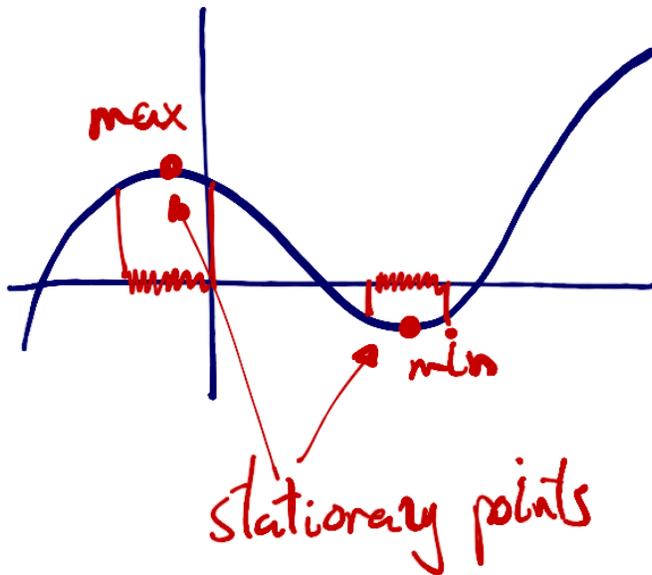
Remark

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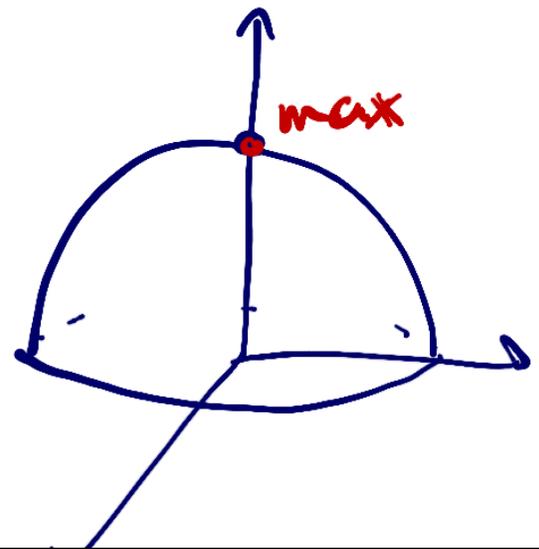
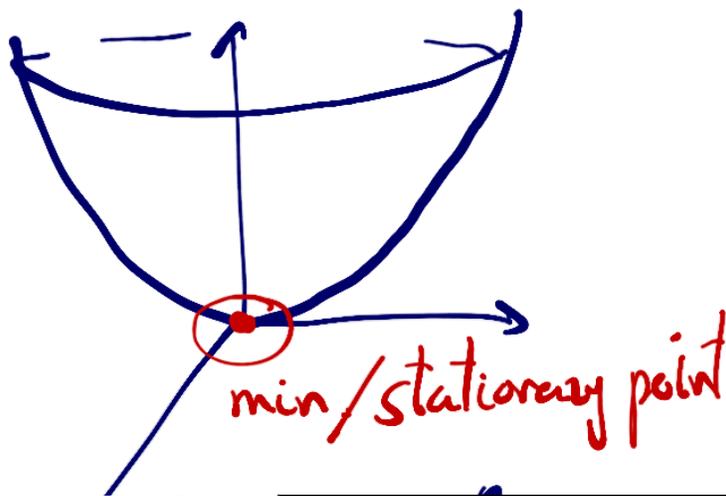
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In one variable:



In several dimensions:



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