

CONVEX HULL IN 2D

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CONVEX HULL IN 2D

xtreme points

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CONVEX HULL IN 2D

Extreme points

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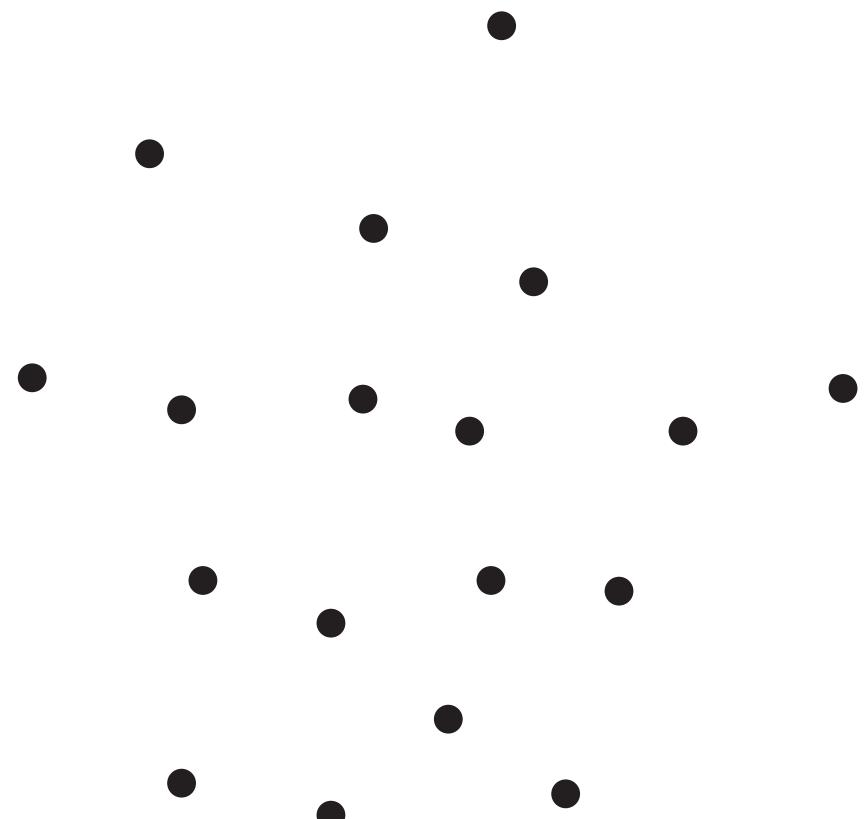
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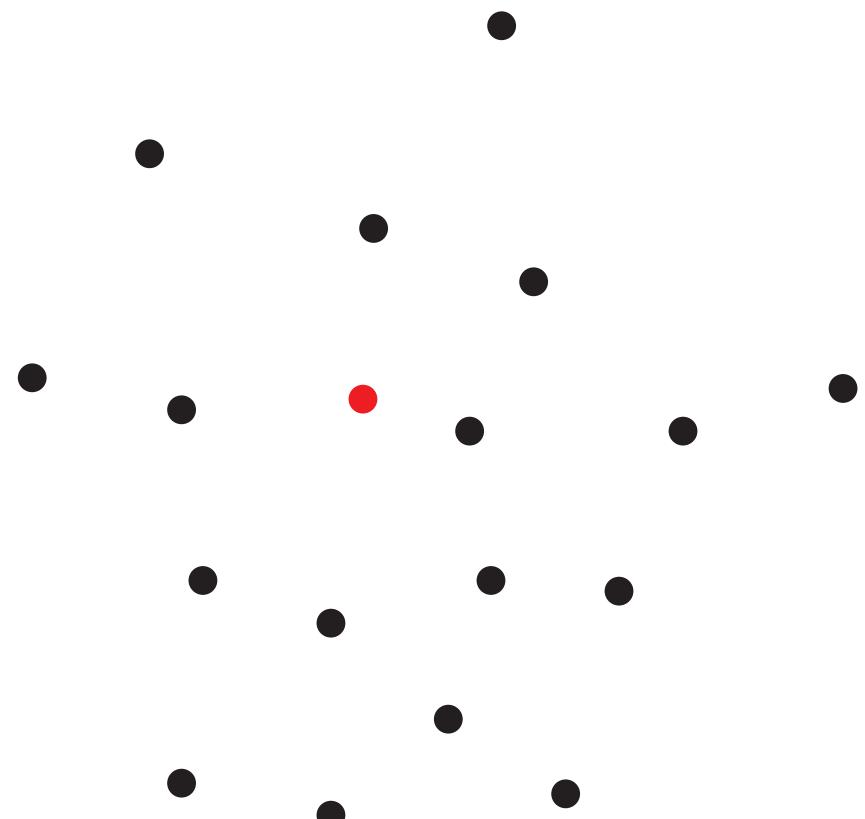
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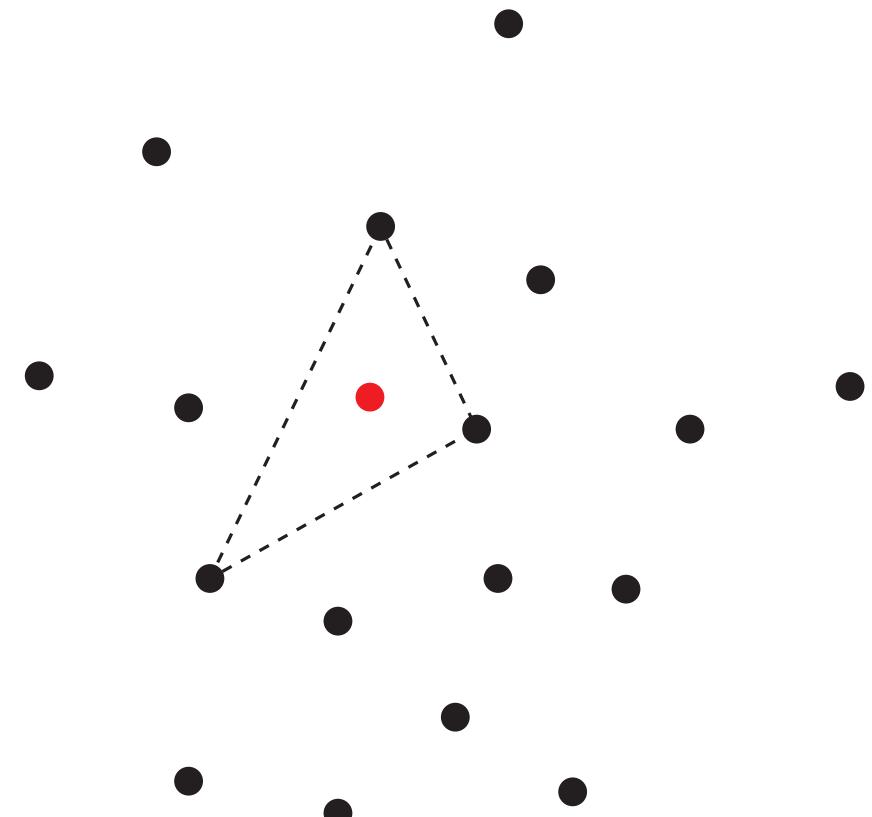
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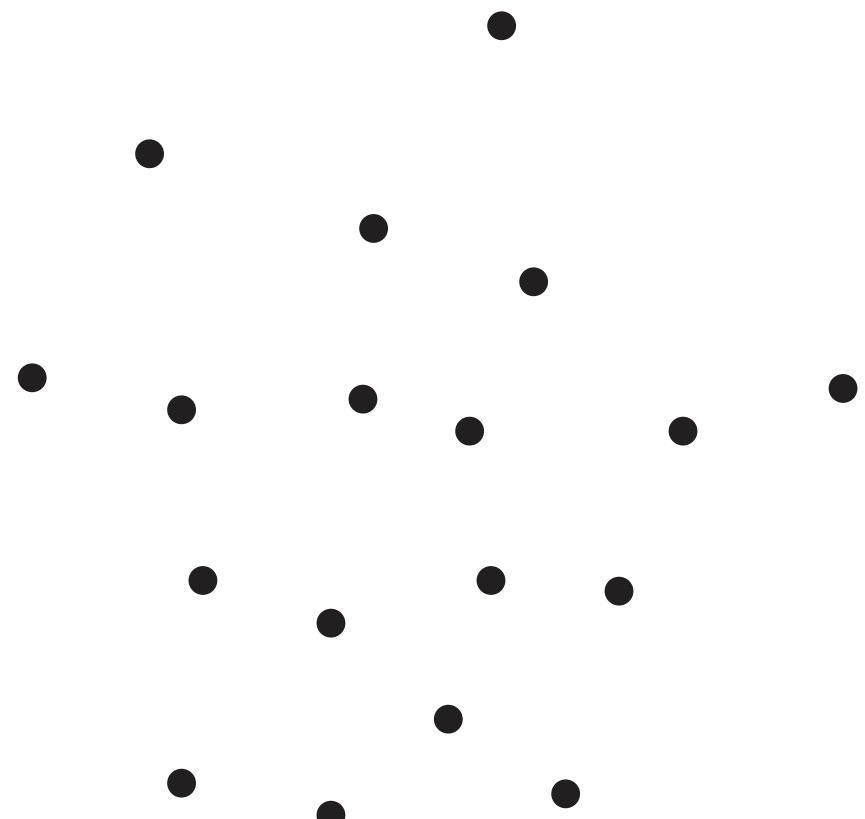
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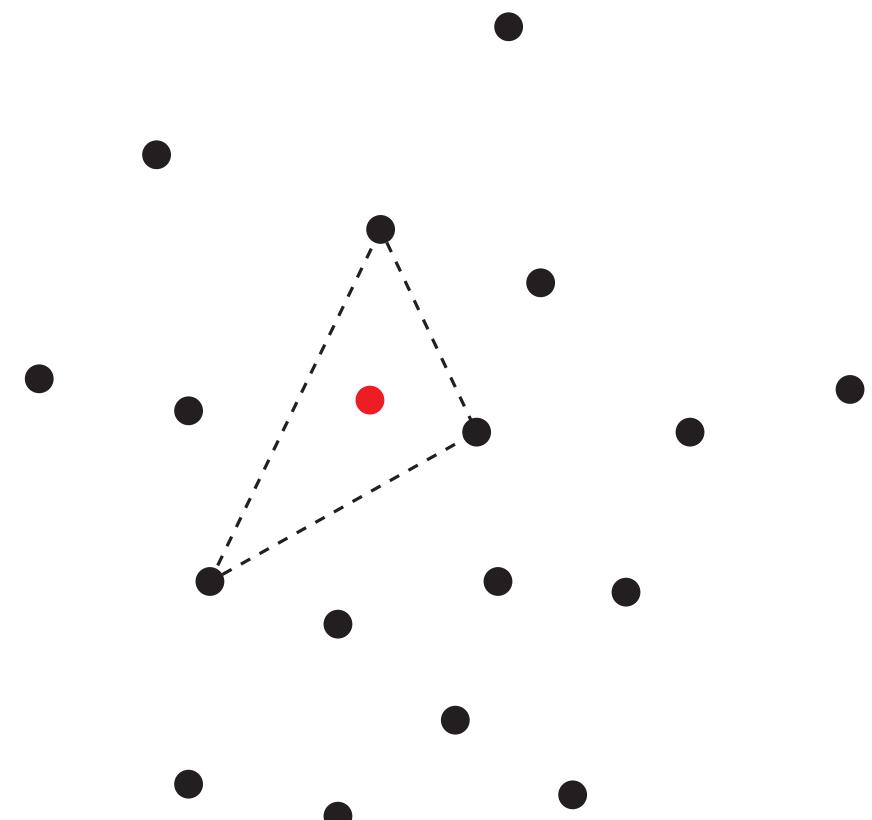
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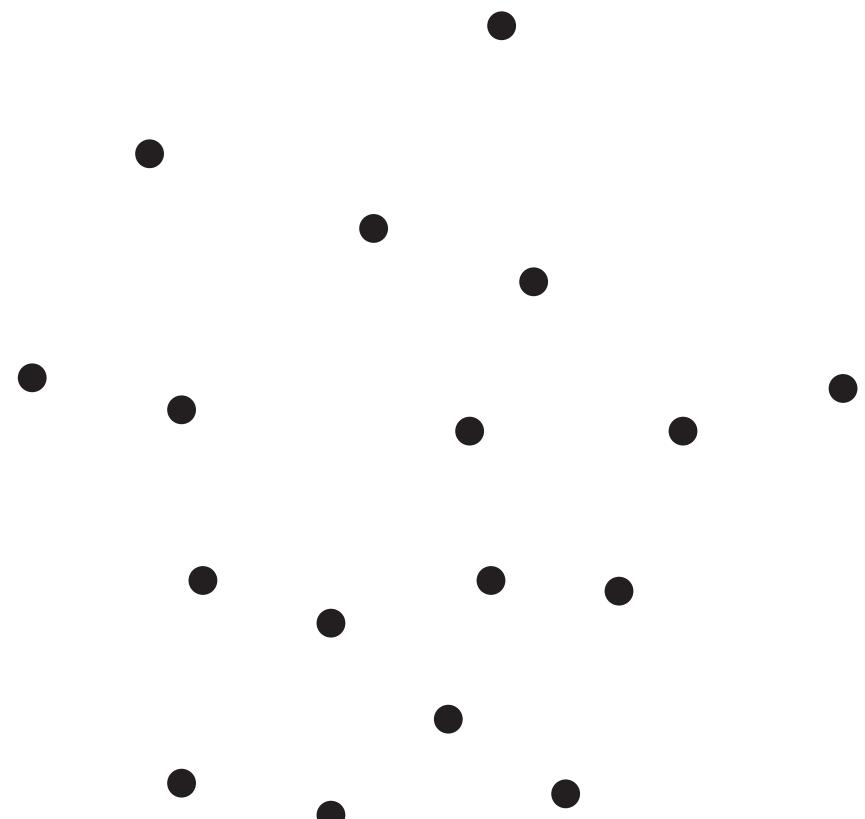
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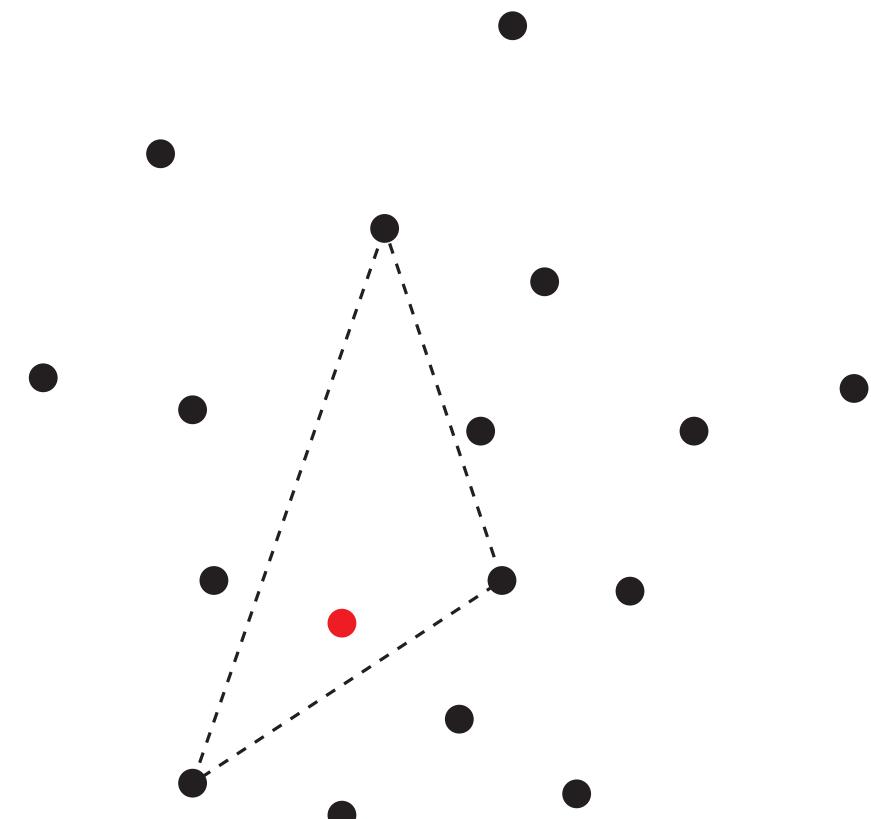
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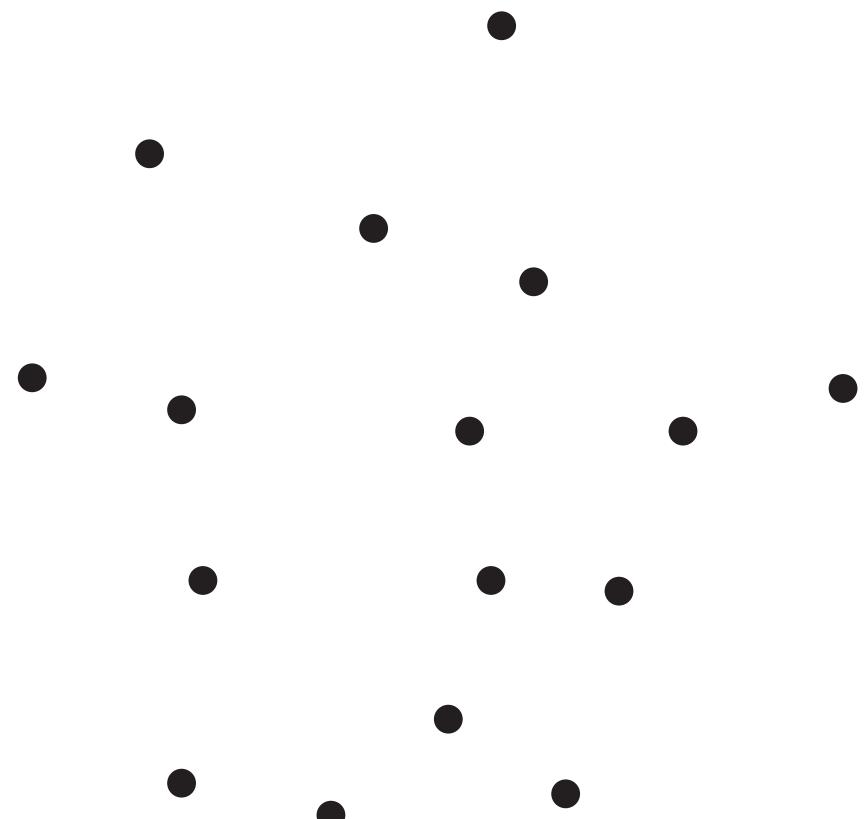
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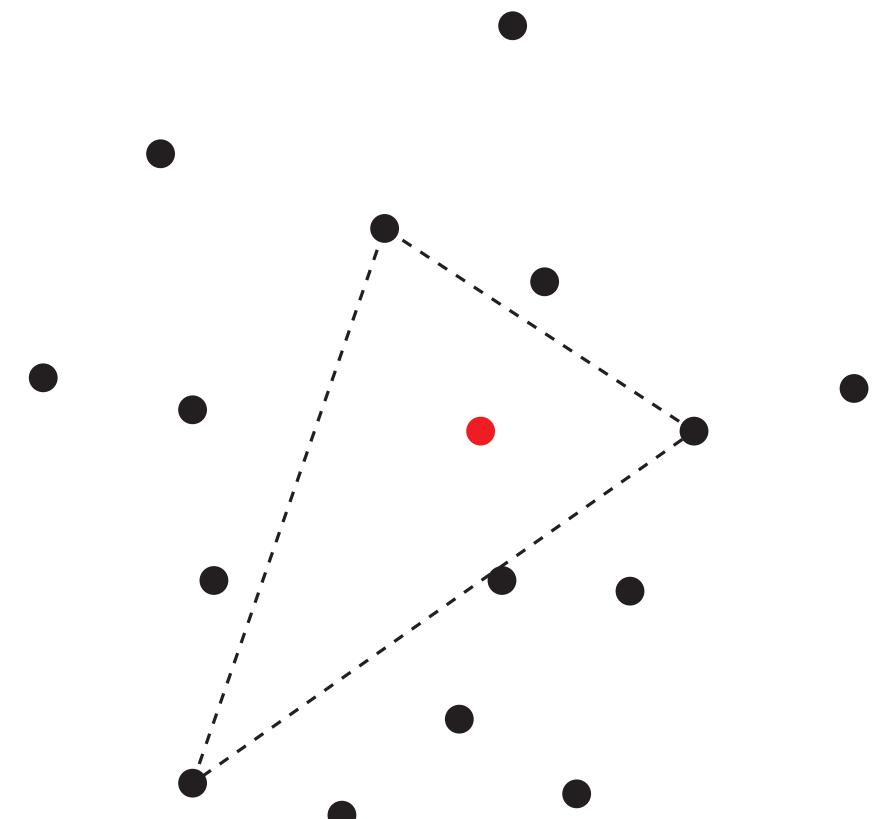
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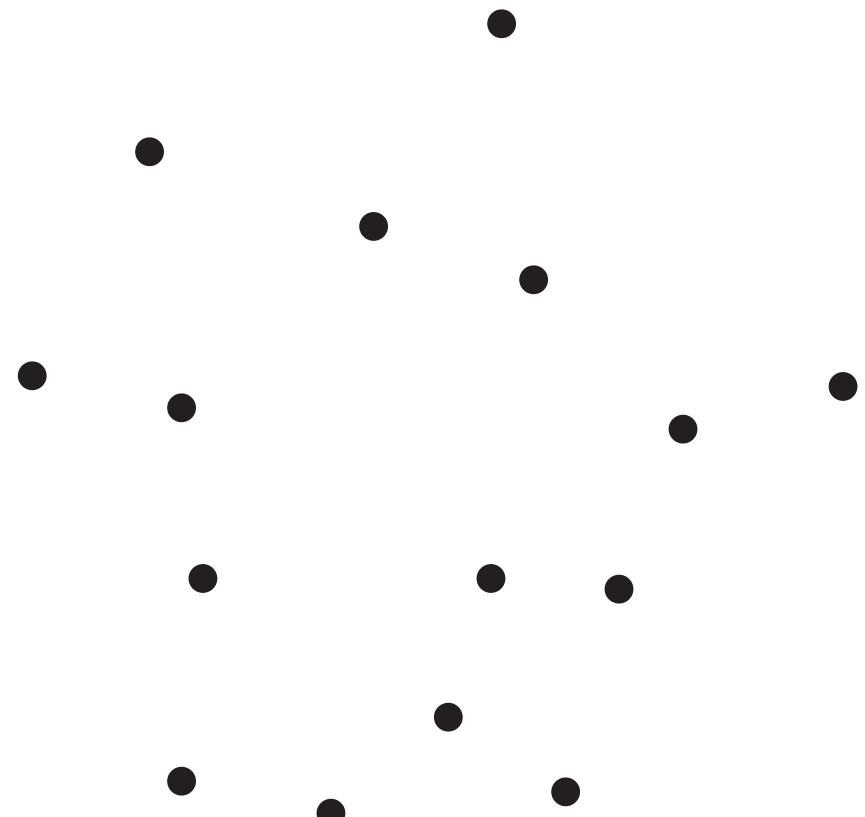
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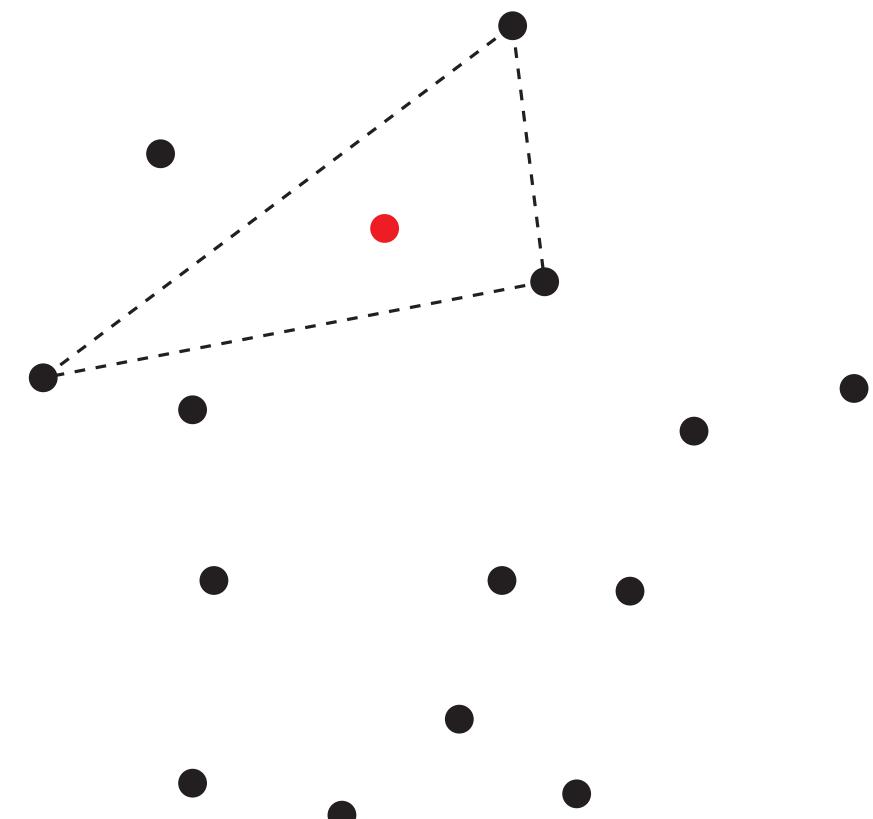
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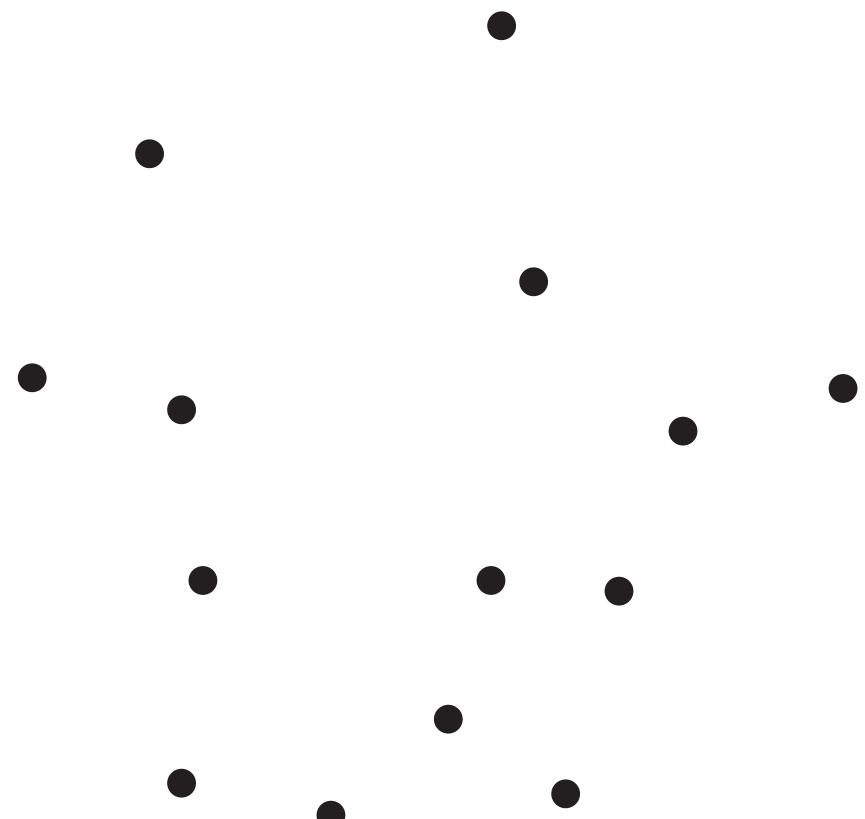
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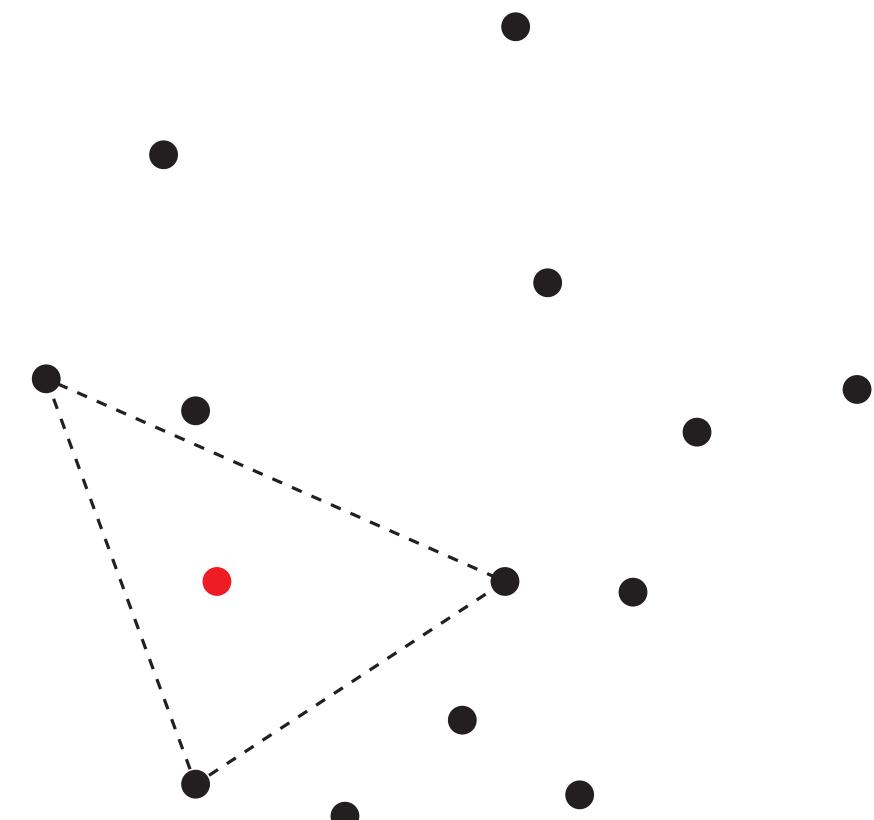
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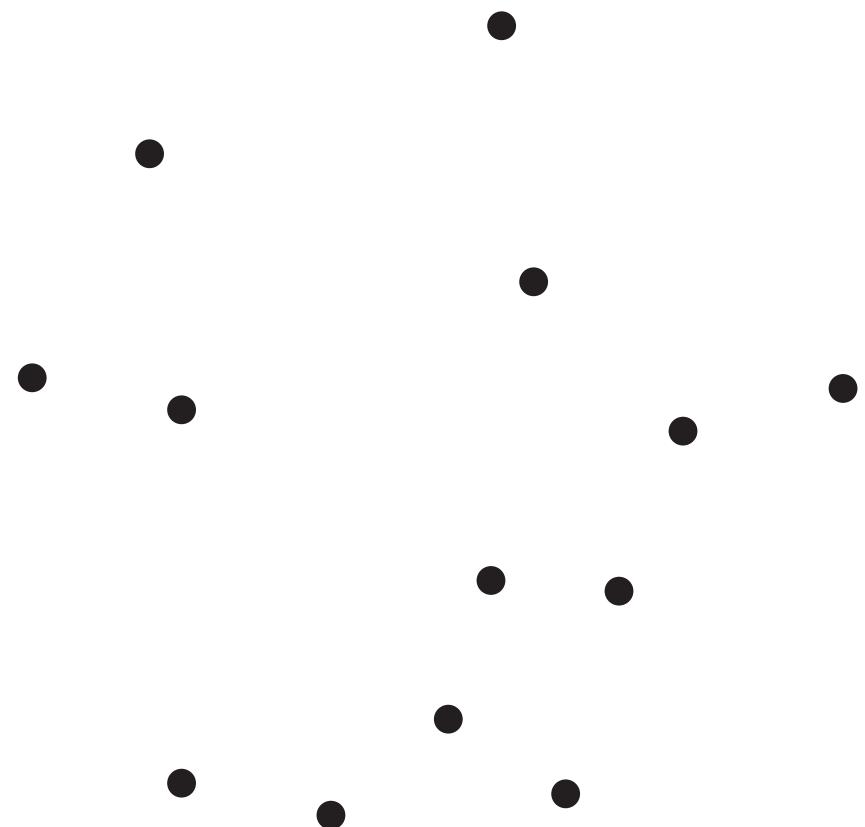
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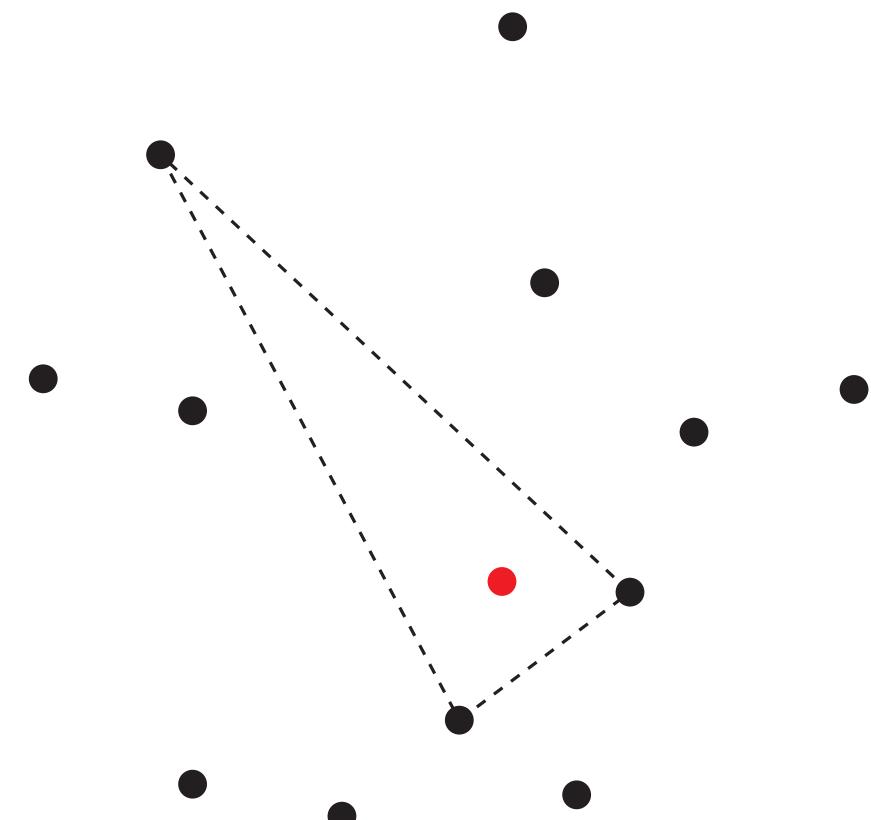
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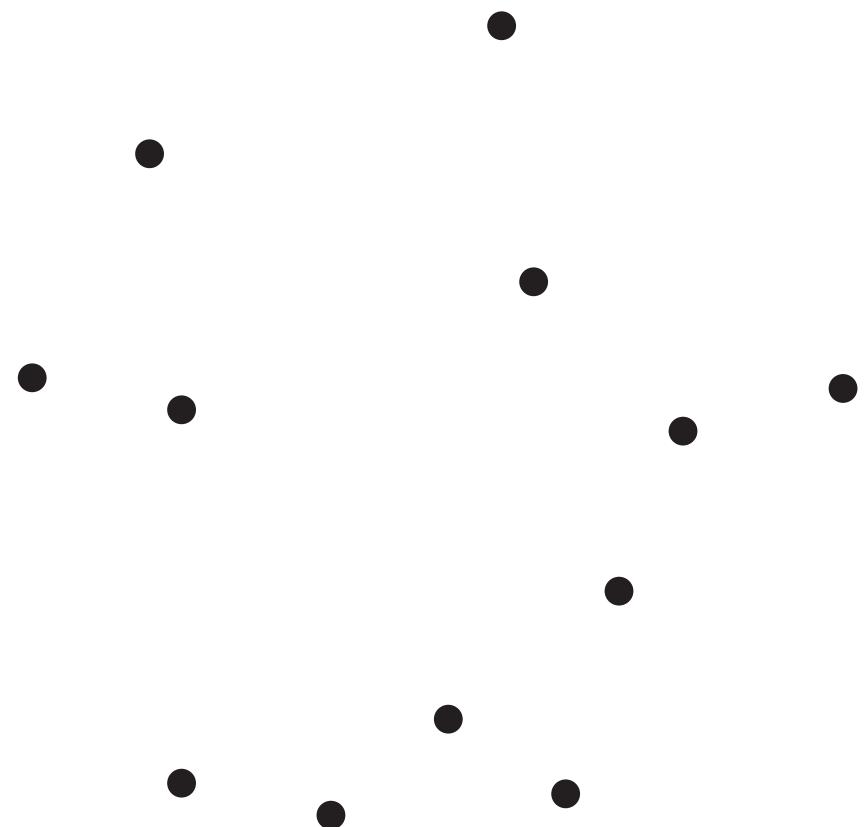
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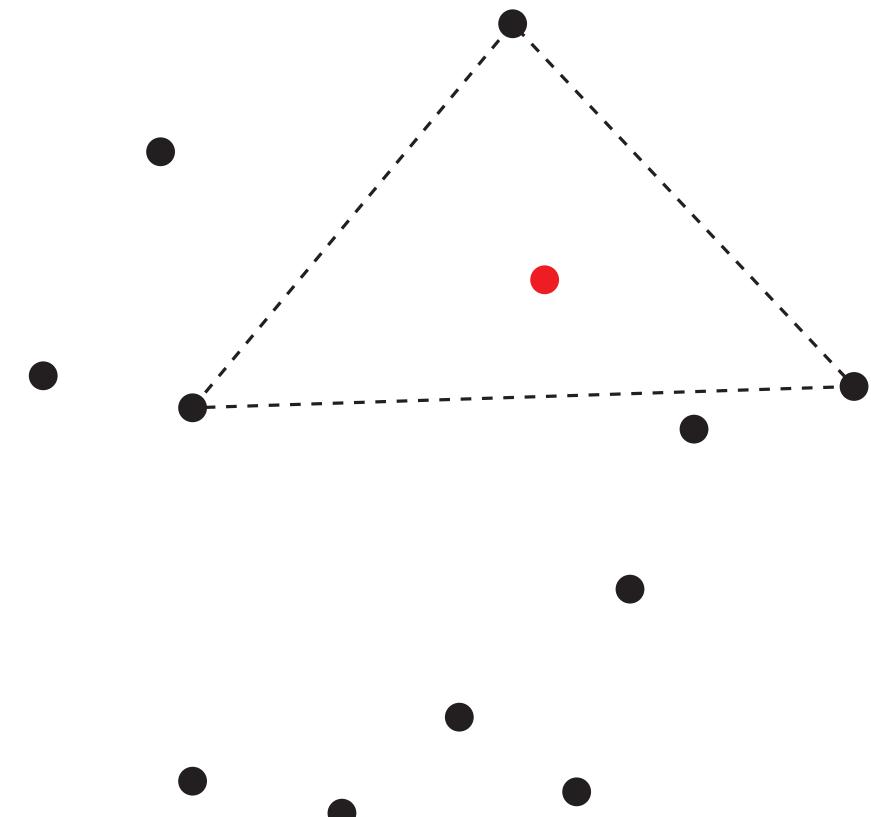
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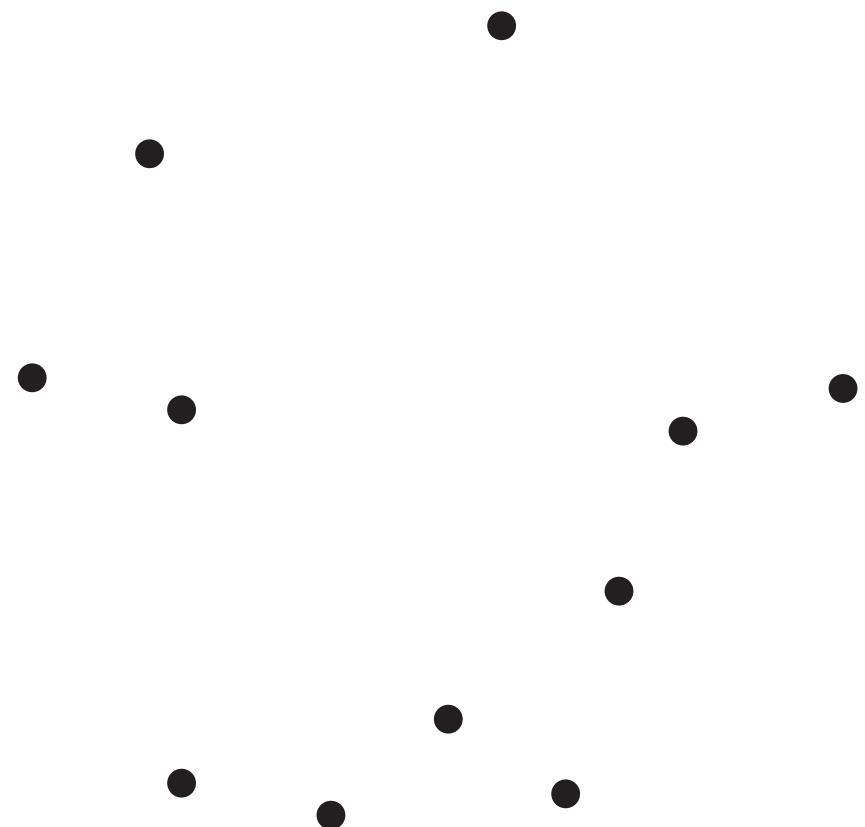
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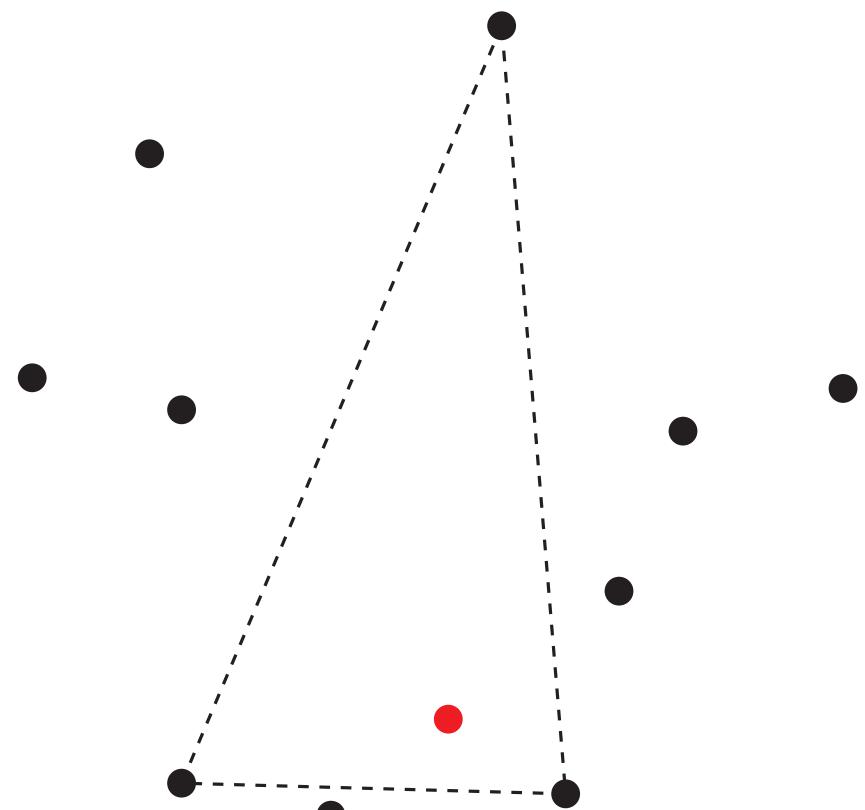
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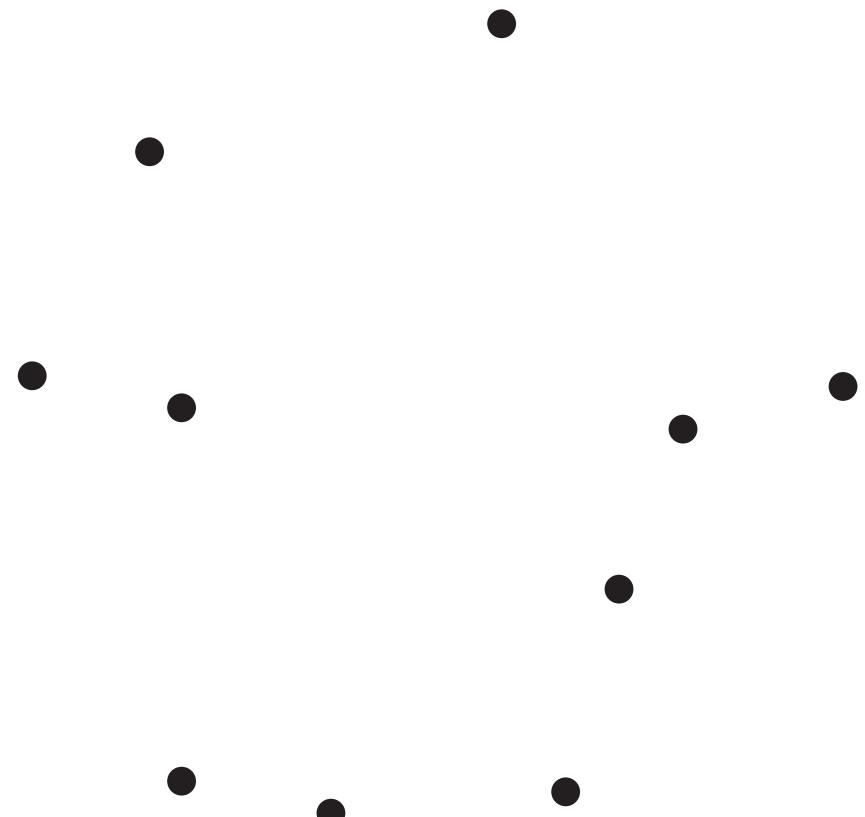
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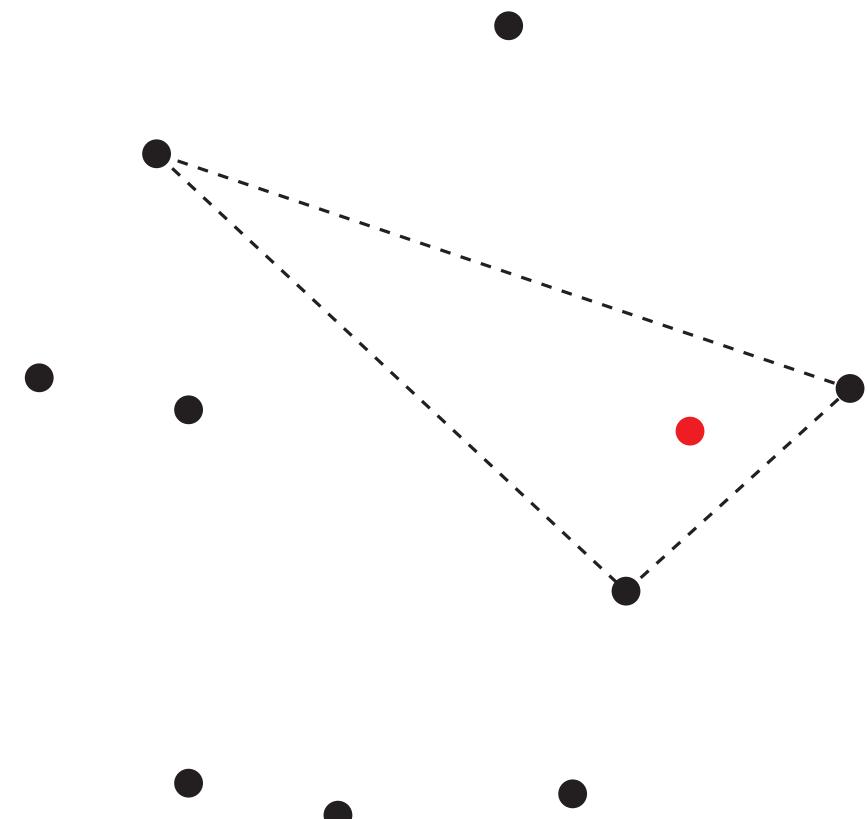
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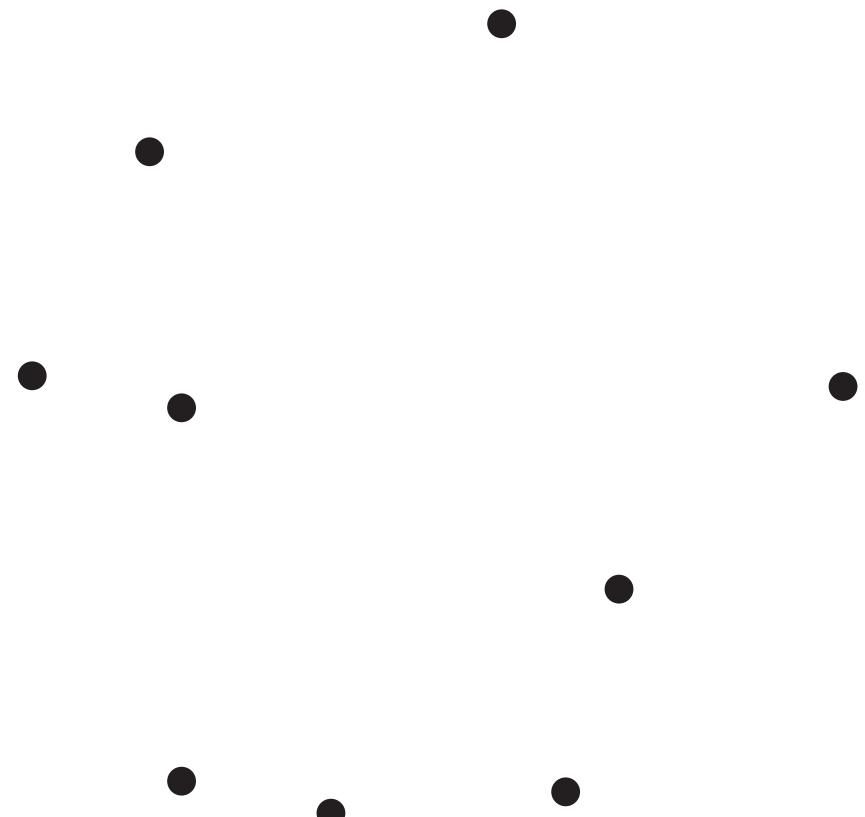
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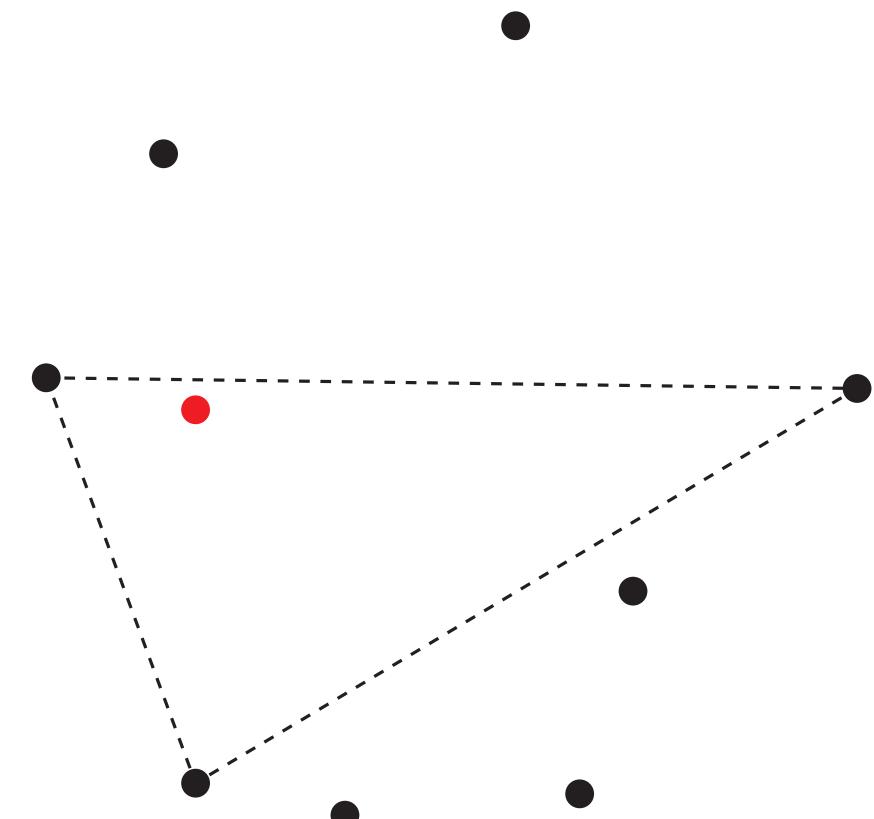
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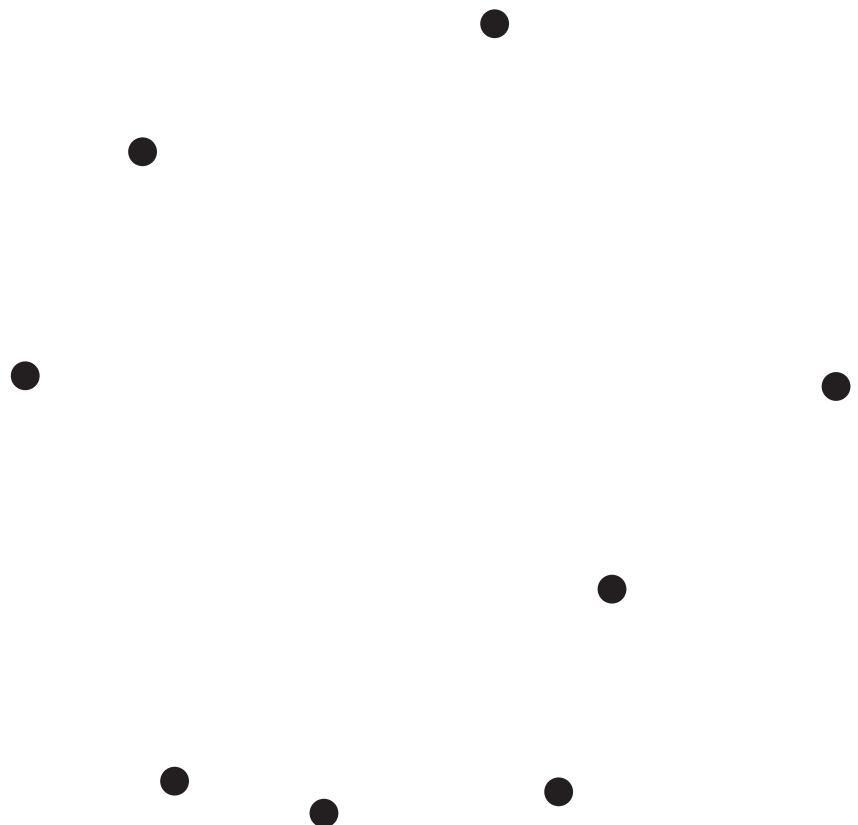
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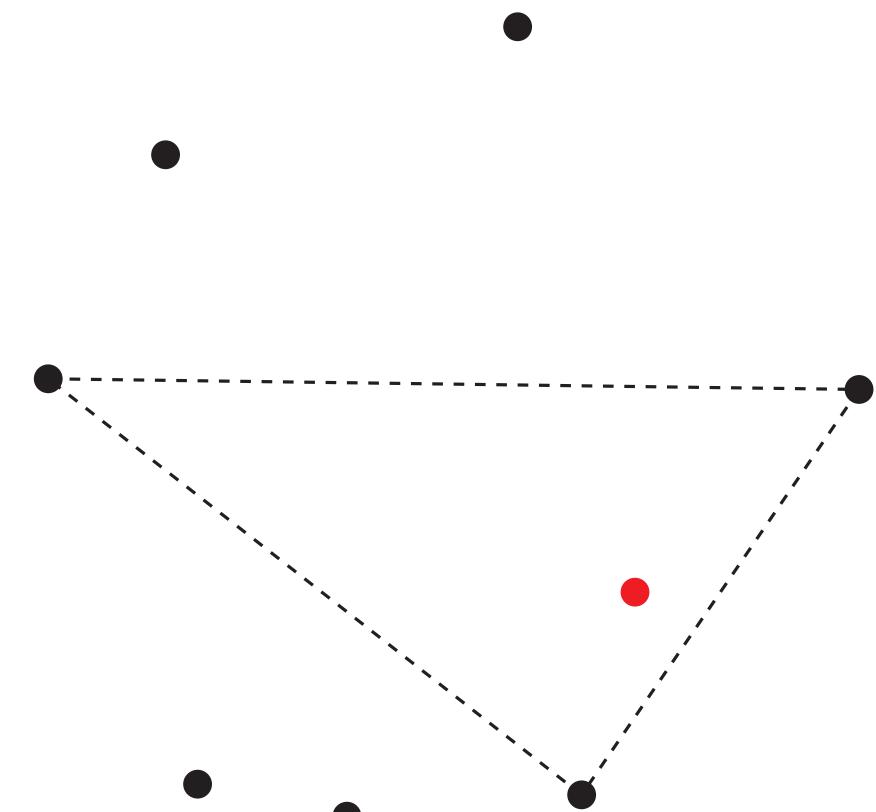
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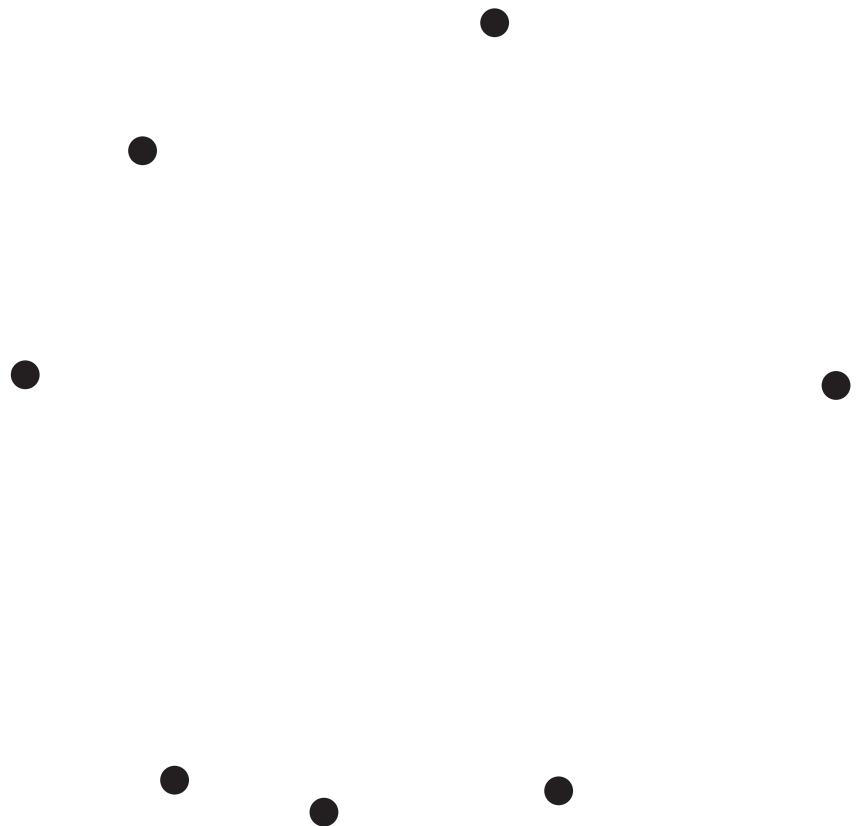
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$\Theta(n^4)$

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xtreme segments

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extreme segments

$\dots, p_n\}$, the segment p_ip_j is an extreme segment if and only if all the points p_k in the set $\{p_i, p_j, \dots, p_n\}$ lie in the same halfplane defined by the line p_ip_j .

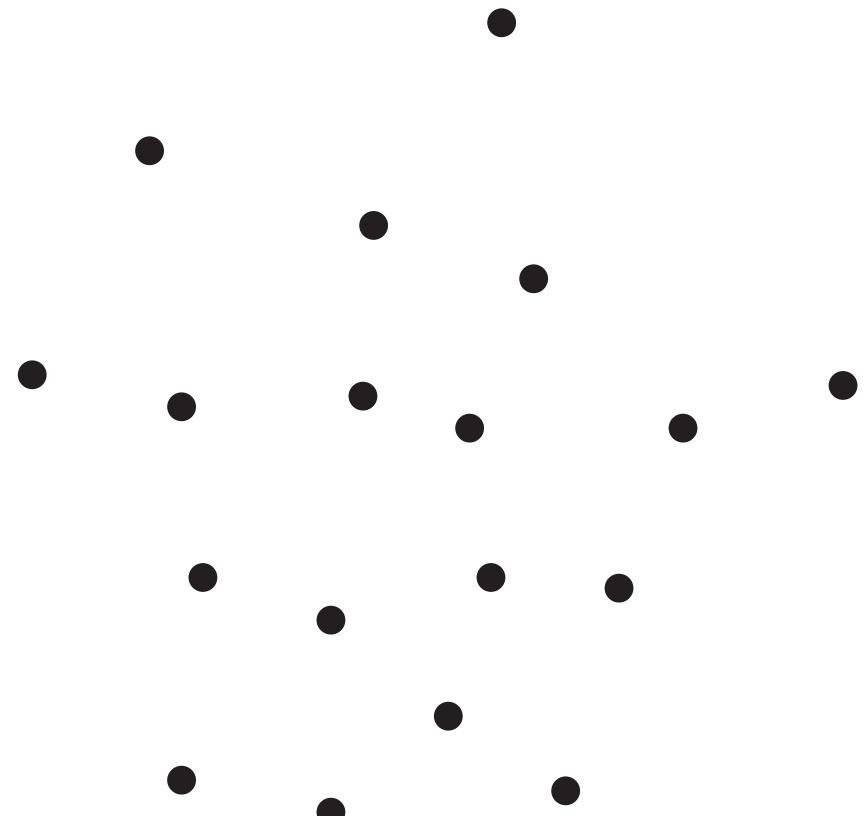
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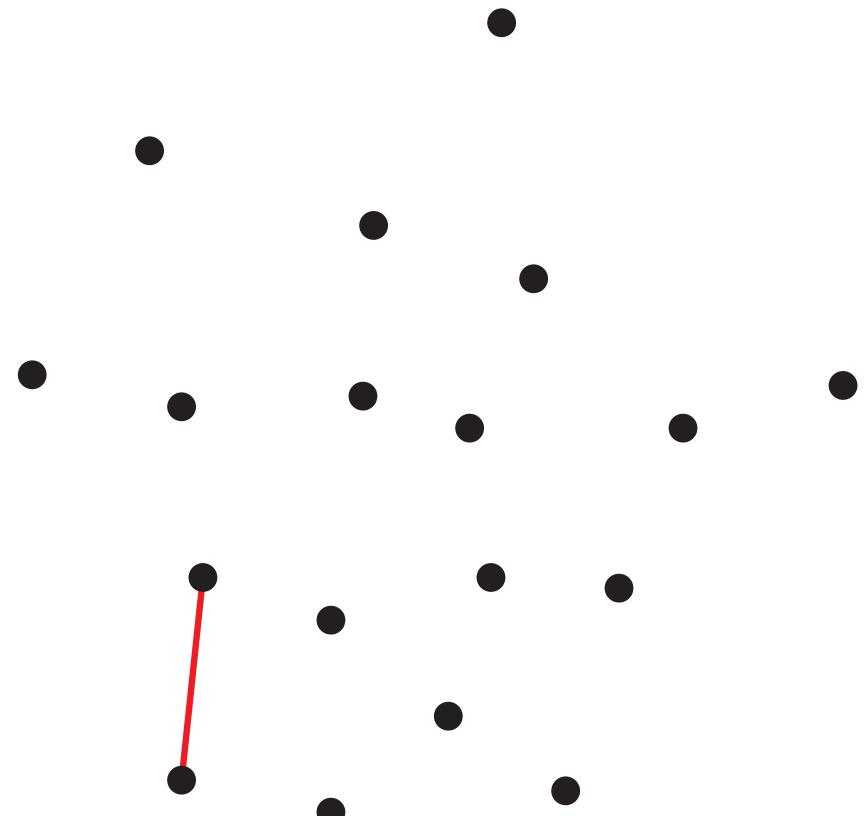
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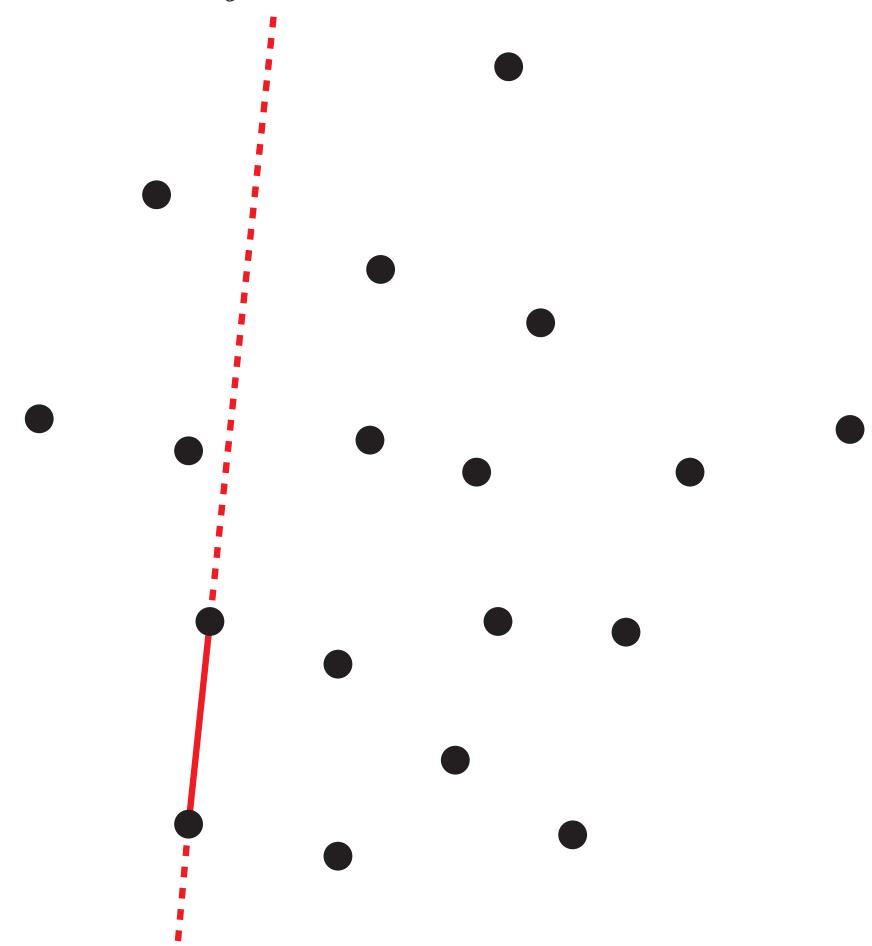
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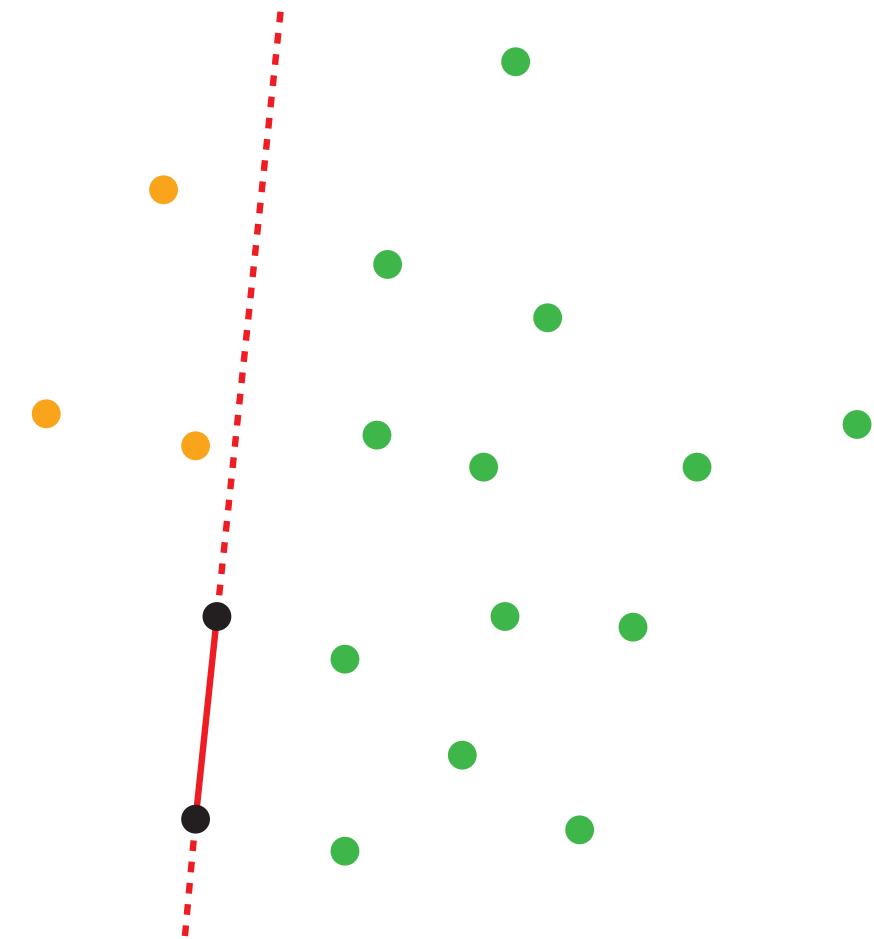
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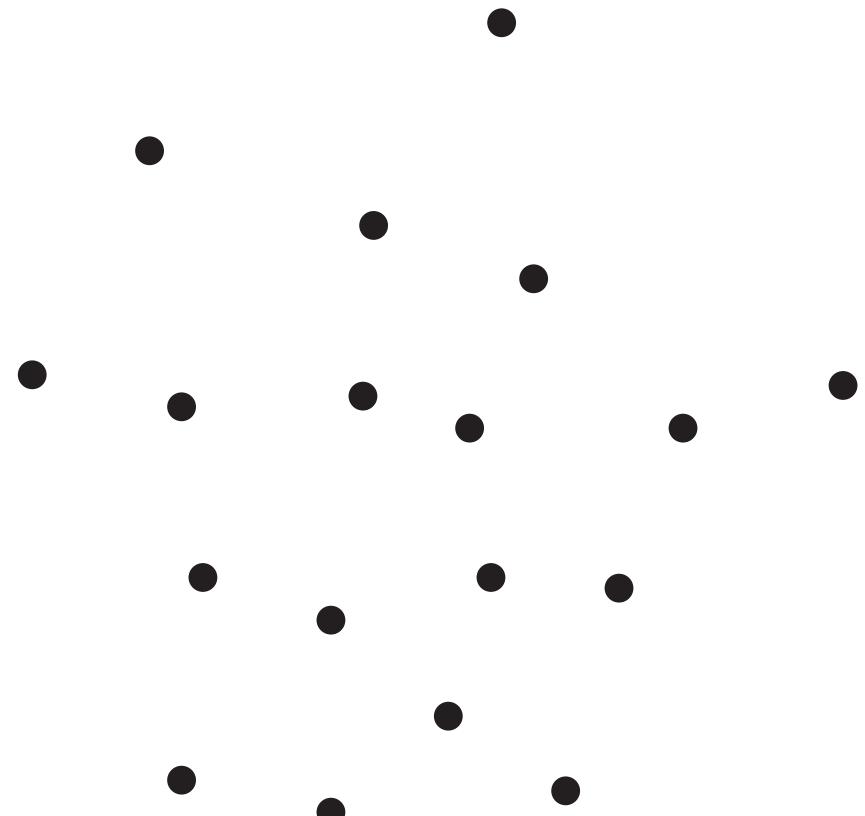


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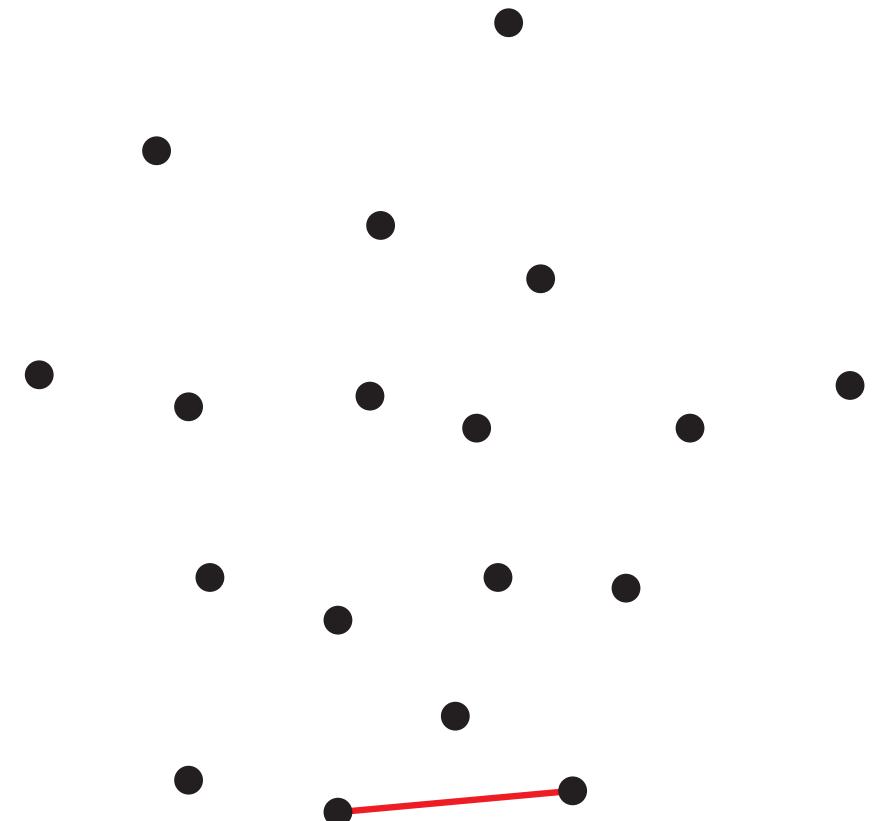
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CONVEX HULL IN 2D

extreme segments

$\dots, p_n\}$, the segment p_ip_j is an extreme segment if and only if all the points p_k in the set $\{p_i, p_j, \dots, p_n\}$ lie in the same halfplane defined by the line p_ip_j .



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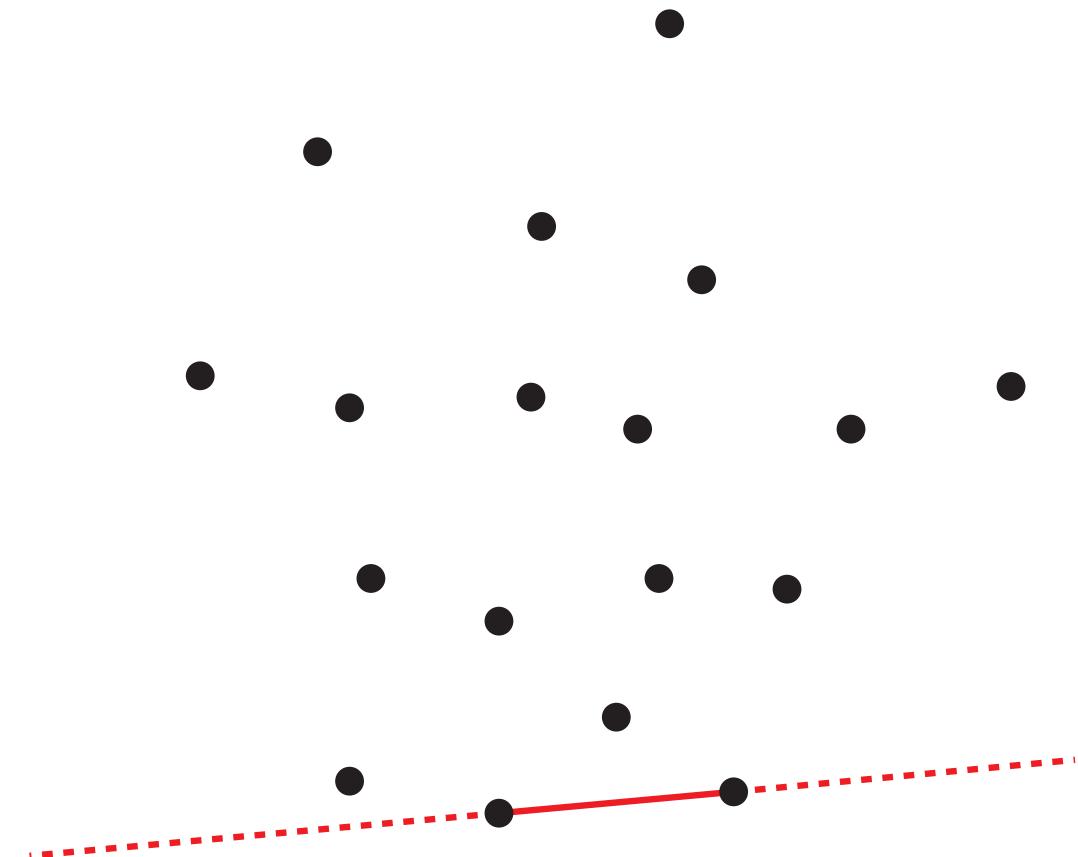
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CONVEX HULL IN 2D

extreme segments

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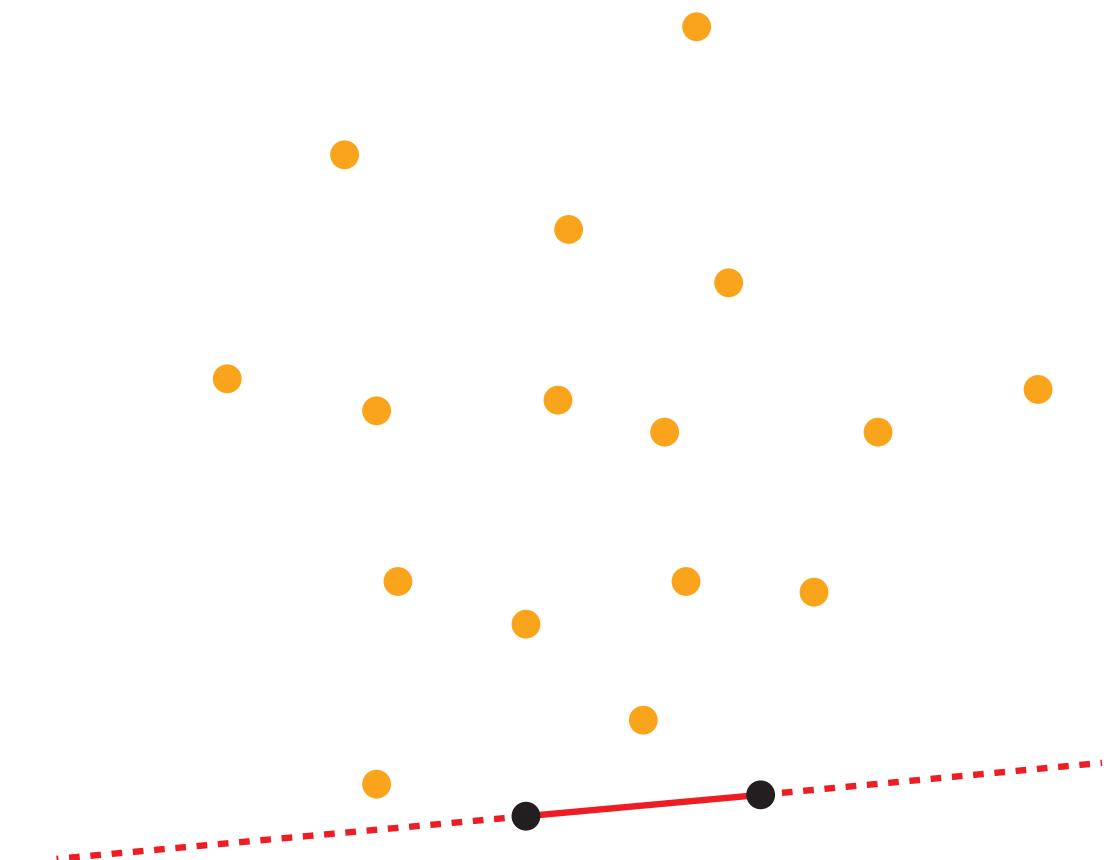


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CONVEX HULL IN 2D

extreme segments

$\dots, p_n\}$, the segment p_ip_j is an extreme segment if and only if all the points p_k in the set are in the same halfplane defined by the line p_ip_j .



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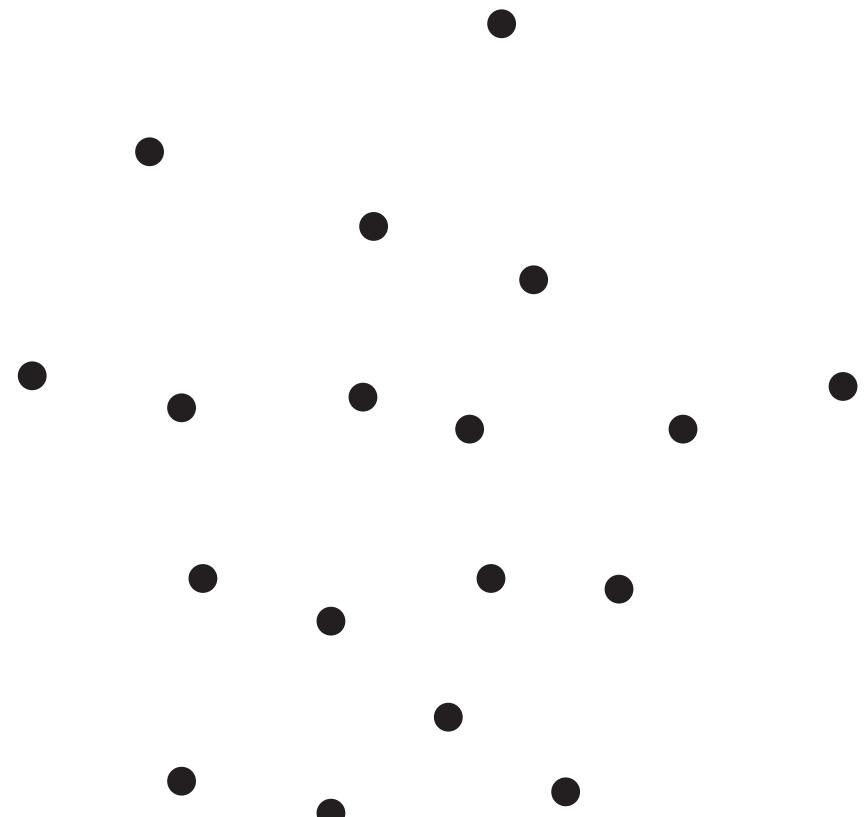
CONVEX HULL IN 2D

extreme segments

$\dots, p_n\}$, the segment $p_i p_j$ is an extreme segment if and only if all the points p_k with $k \neq i, j$ lie in the same halfplane defined by the line $p_i p_j$.

extreme segments

For all p_k with $k \neq i, j$ if p_k lies in the halfplane defined by $p_i p_j$. Otherwise, return the segment $p_i p_j$.



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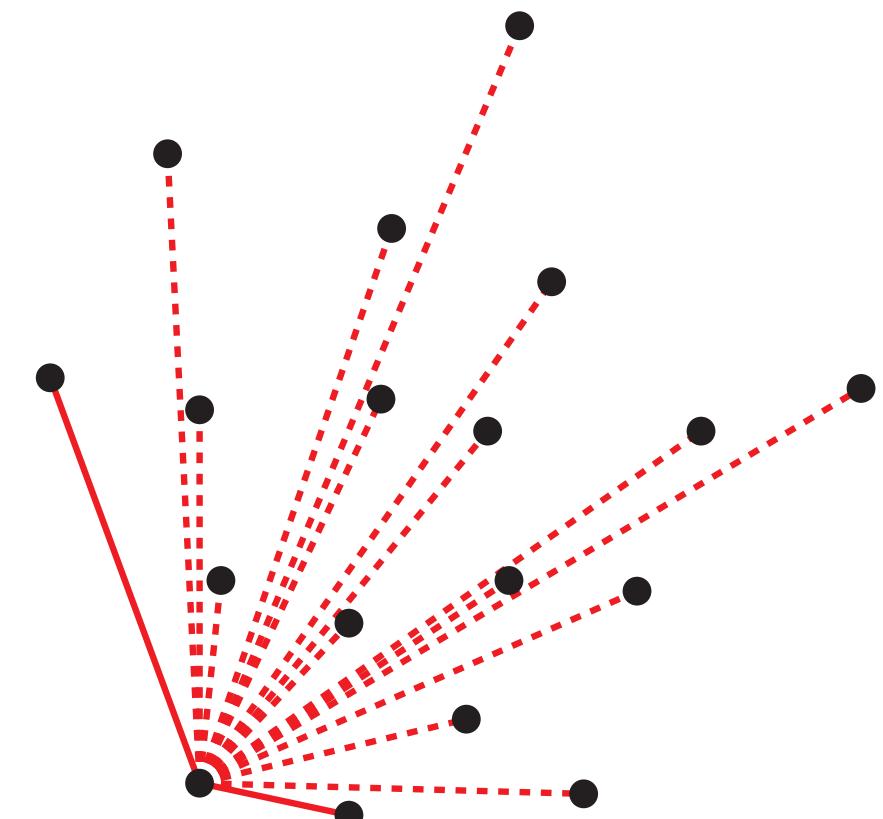
CONVEX HULL IN 2D

extreme segments

$\dots, p_n\}$, the segment $p_i p_j$ is an extreme segment if and only if all the points p_k with $k \neq i, j$ lie in the same halfplane defined by the line $p_i p_j$.

extreme segments

For all p_k with $k \neq i, j$ such that p_k lies in the halfplane defined by $p_i p_j$. In this case, return the segment $p_i p_j$.



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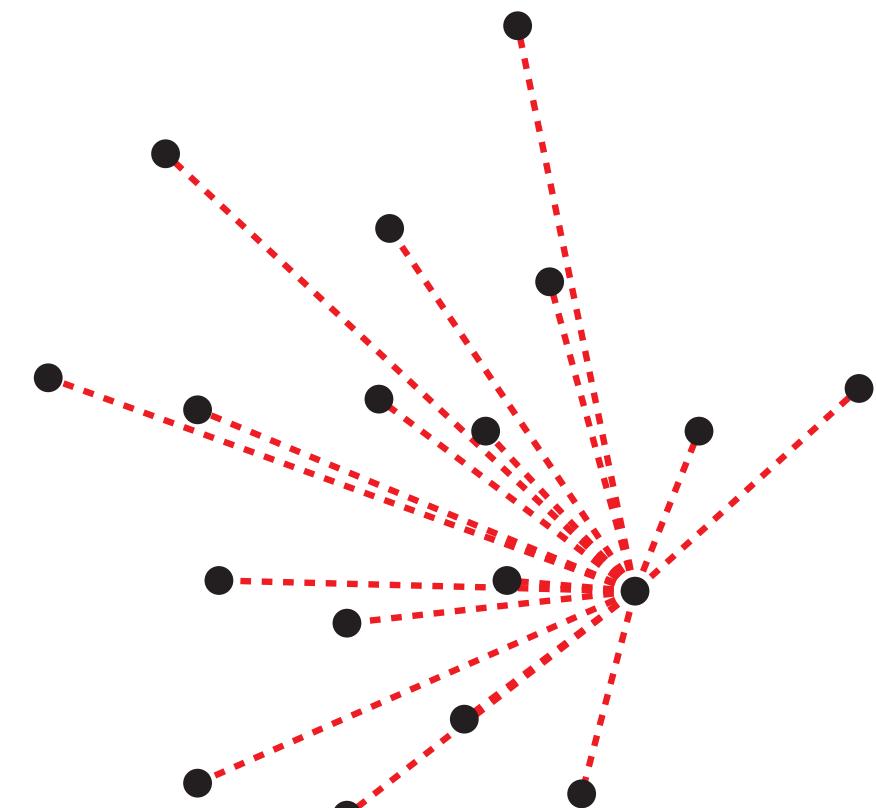
CONVEX HULL IN 2D

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extreme segments

For all p_k with $k \neq i, j$ such that p_k lies in the halfplane defined by $p_i p_j$. In this case, return the segment $p_i p_j$.



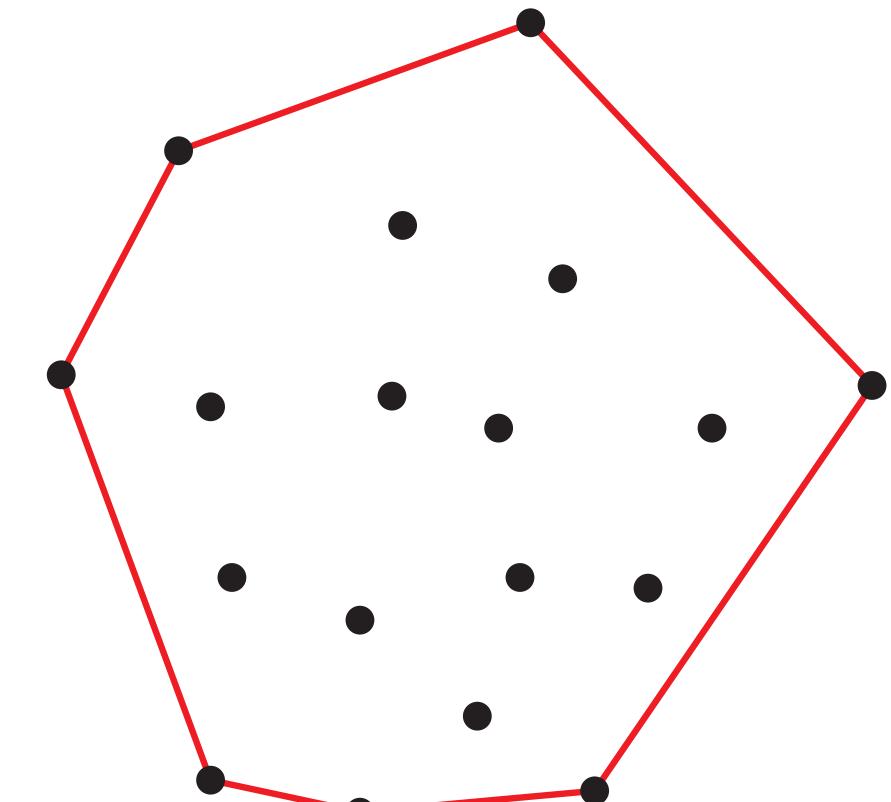
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CONVEX HULL IN 2D

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extreme segments



for all p_k with $k \neq i, j$ lie in the same halfplane defined by $p_i p_j$. In this case, return the segment $p_i p_j$.

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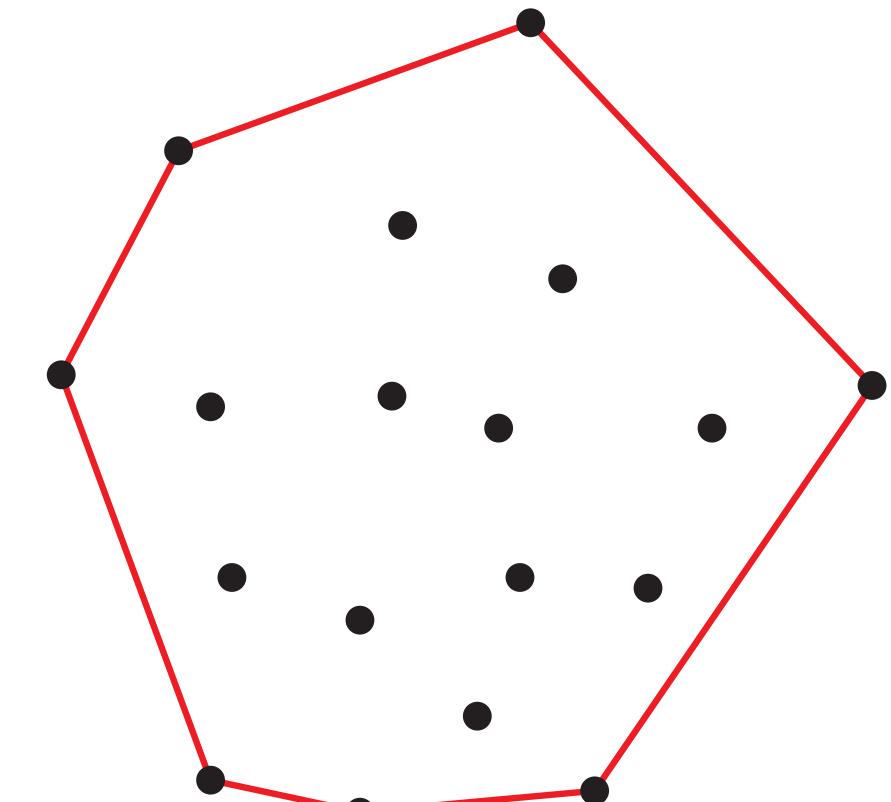
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CONVEX HULL IN 2D

extreme segments

$\dots, p_n\}$, the segment p_ip_j is an extreme segment if and only if all the points p_k with $k \neq i, j$ lie in the same halfplane defined by the line p_ip_j .

extreme segments



for all p_k with $k \neq i, j$ lie in the same halfplane defined by p_ip_j . In this case, return the segment p_ip_j .

$\Theta(n^3)$

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CONVEX HULL IN 2D

onvex hull

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CONVEX HULL IN 2D

onvex hull

(sorted list of its vertices)

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CONVEX HULL IN 2D

onvex hull

$\dots, p_n \} \subset \mathbb{R}^2$ a set of n points in the plane

of the vertices of $ch(P)$ sorted in counterclockwise order

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CONVEX HULL IN 2D

convex hull

$\dots, p_n \} \subset \mathbb{R}^2$ a set of n points in the plane

of the vertices of $ch(P)$ sorted in counterclockwise order

$\dots, p_n \}$, the segment $p_i p_j$ is an edge of the convex hull of X if and only if all $k \neq i, j$ lie to the left of the oriented line $p_i p_j$.

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CONVEX HULL IN 2D



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CONVEX HULL IN 2D

x of $ch(P)$ (for example, the lexicographically smaller point $p_i \in P$) and add it to l

last(l) \neq First(l), do:

the angularly rightmost point $p_j \in P$
with respect to v .

to l

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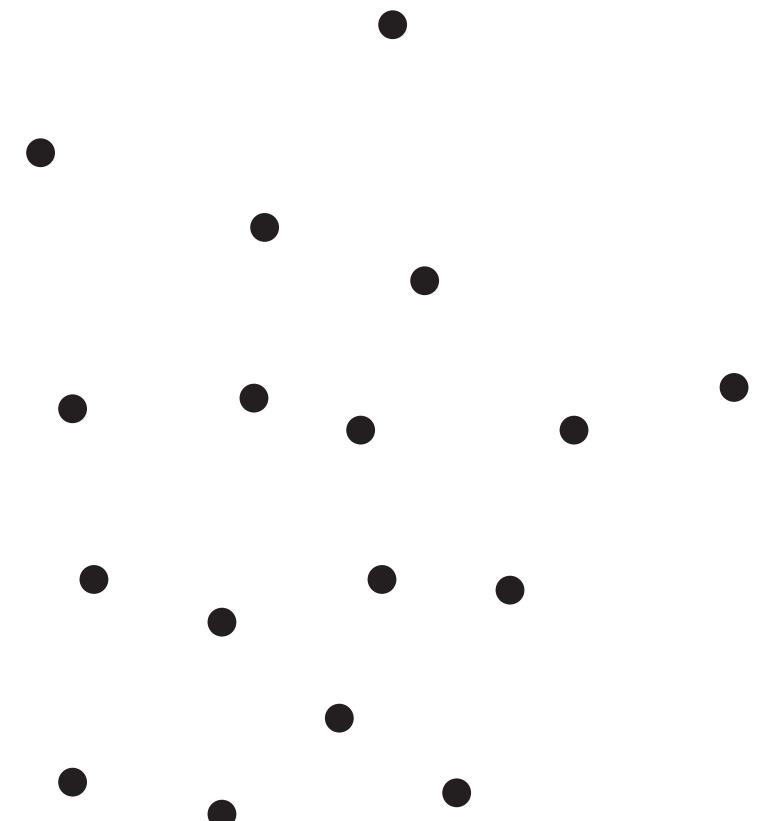
CONVEX HULL IN 2D

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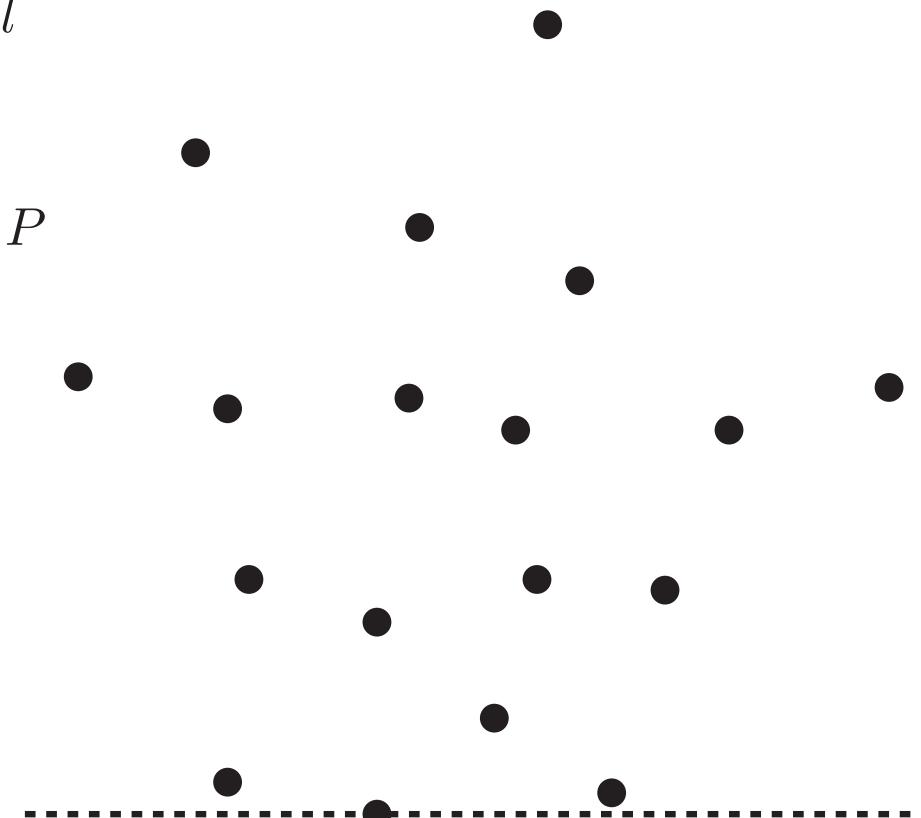
CONVEX HULL IN 2D

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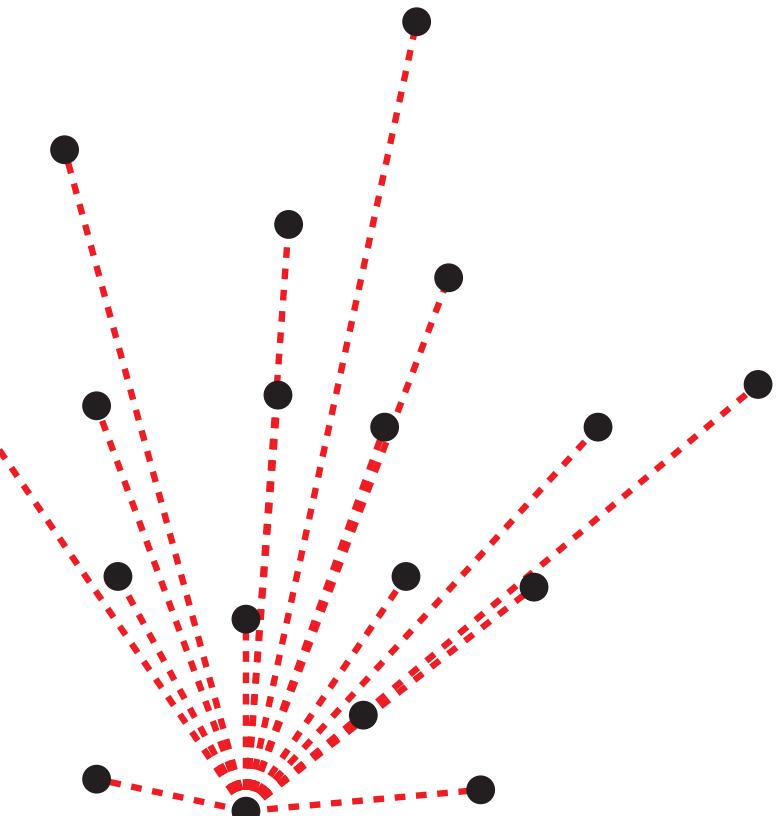
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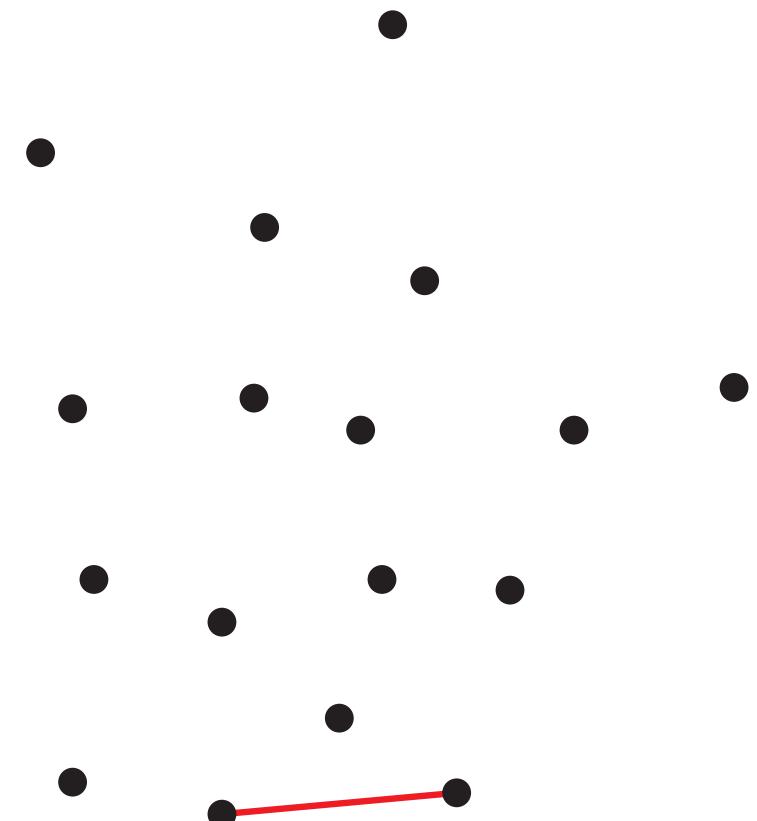
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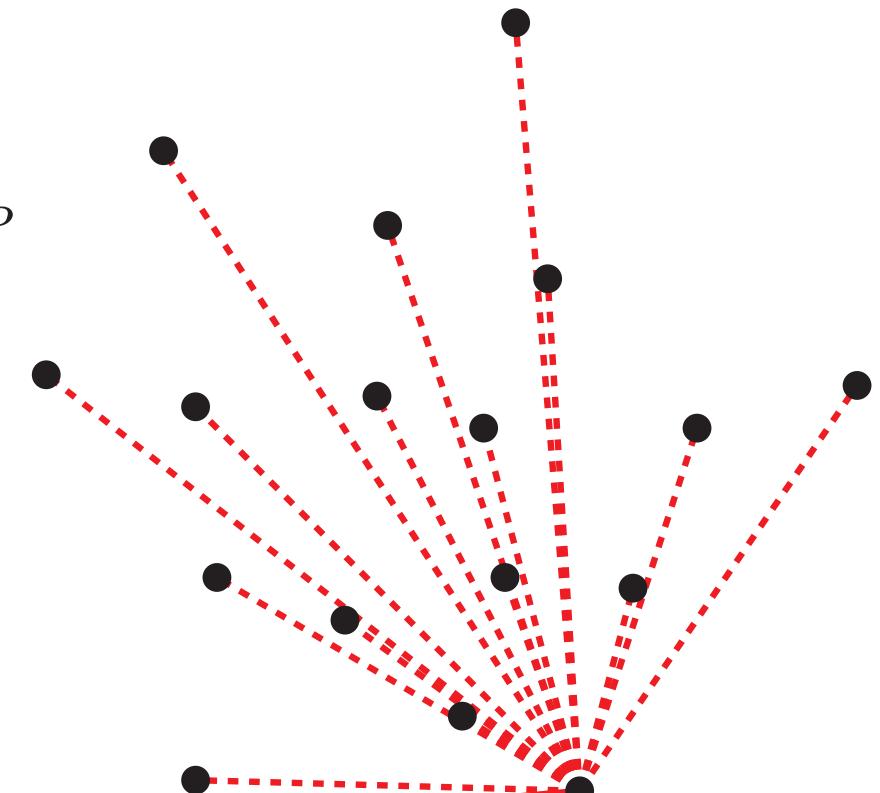
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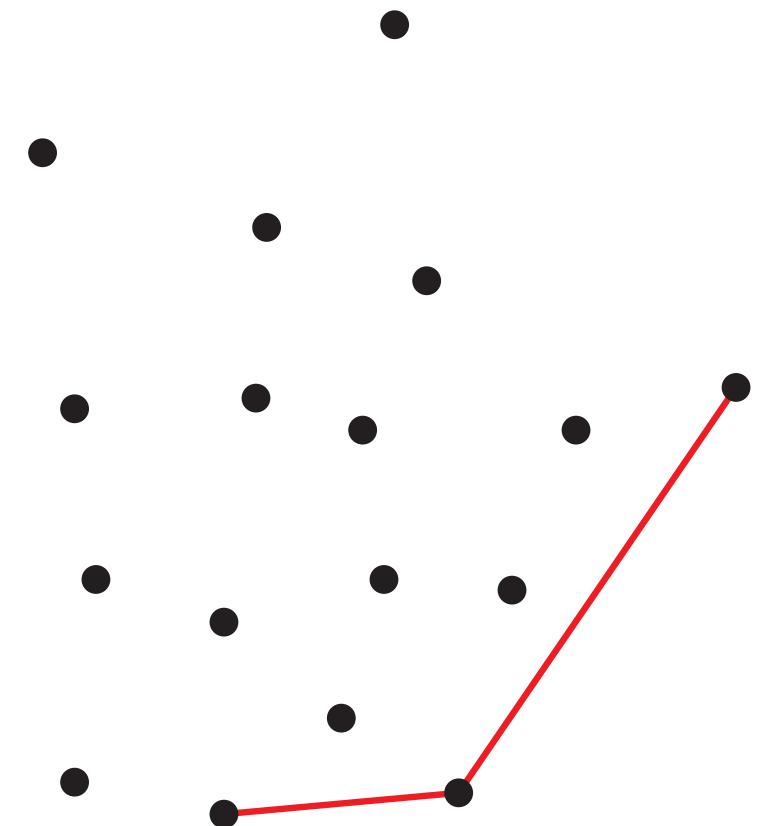
CONVEX HULL IN 2D

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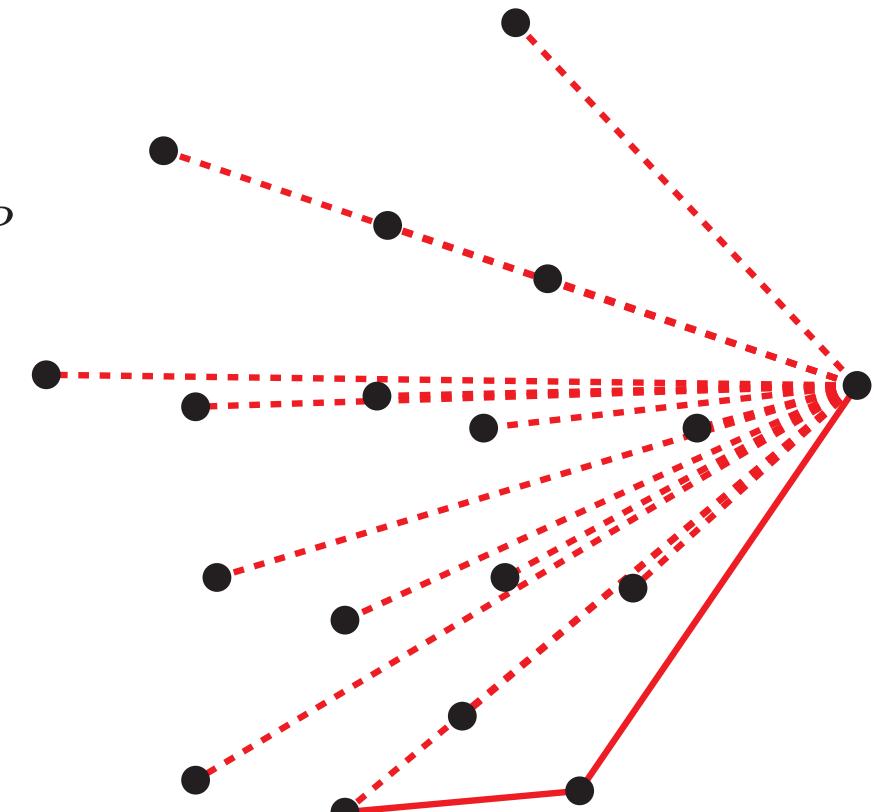
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to l



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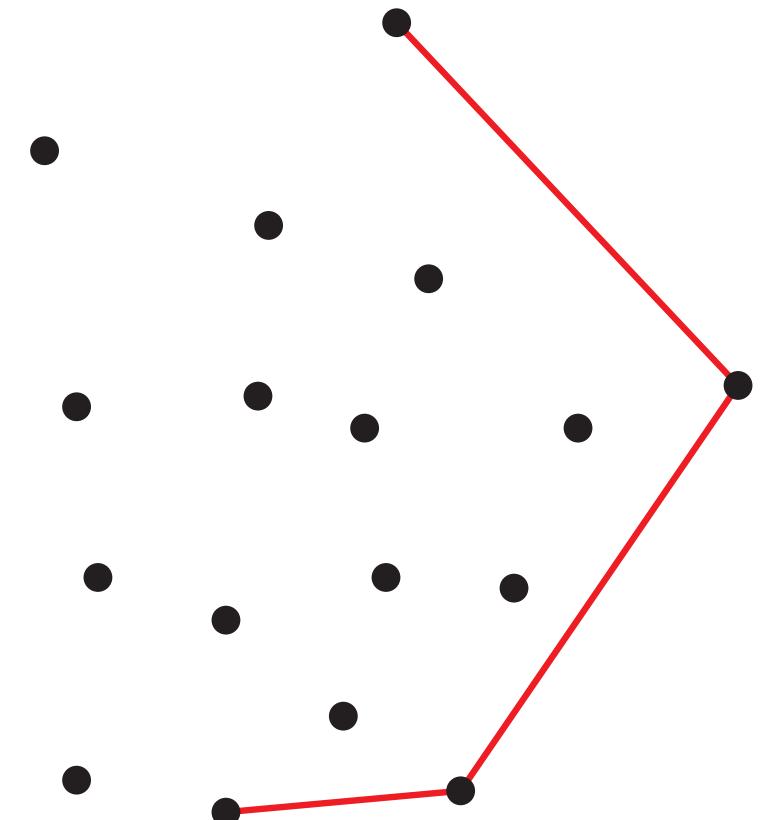
CONVEX HULL IN 2D

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last(l) \neq First(l), do:

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with respect to v .

to l



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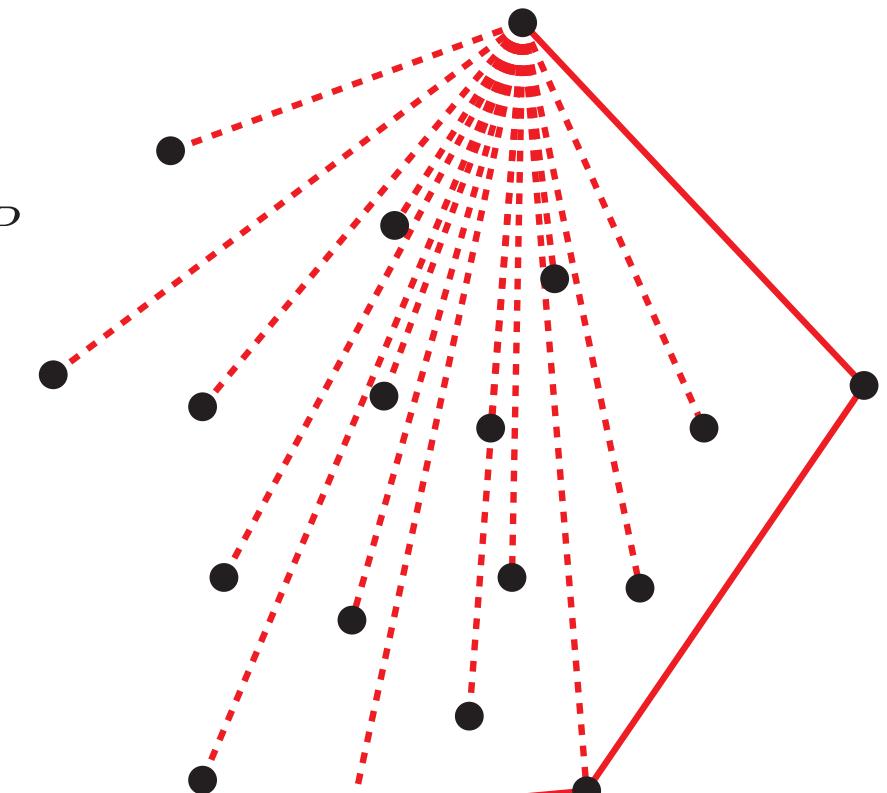
the angularly rightmost point $p_j \in P$
with respect to v .

to l

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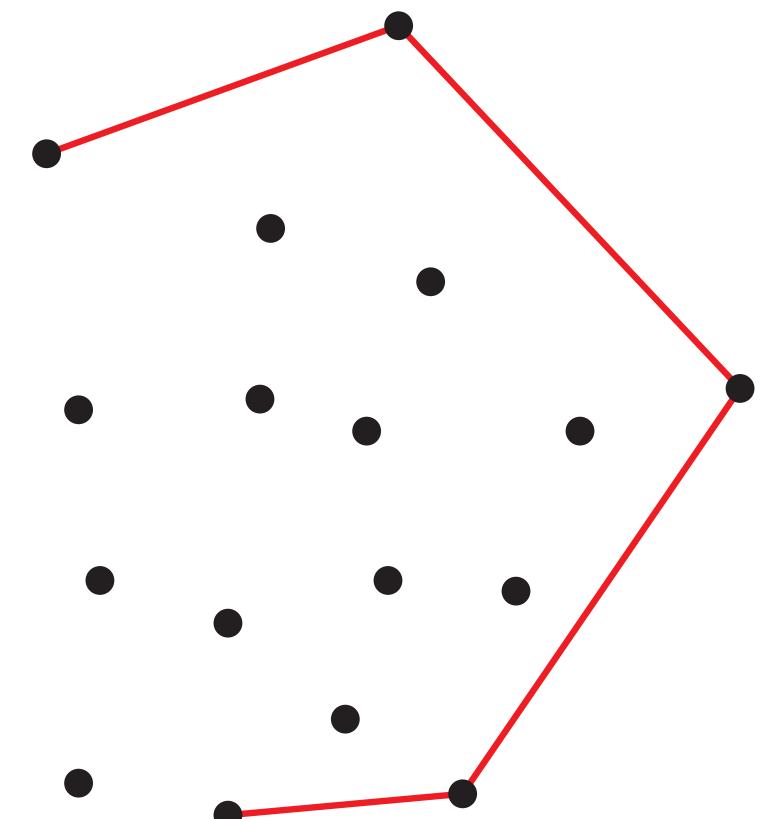
CONVEX HULL IN 2D

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last(l) \neq First(l), do:

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to l



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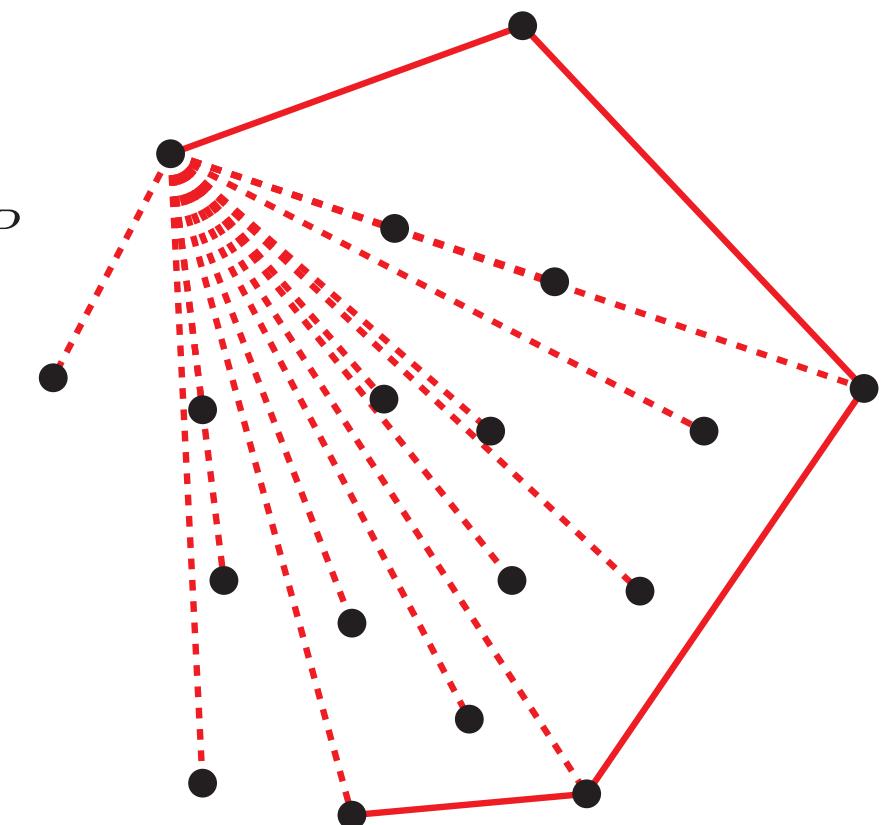
x of $ch(P)$ (for example, the lexicographically smaller point $p_i \in P$) and add it to l

last(l) \neq First(l), do:

the angularly rightmost point $p_j \in P$
with respect to v .

to l

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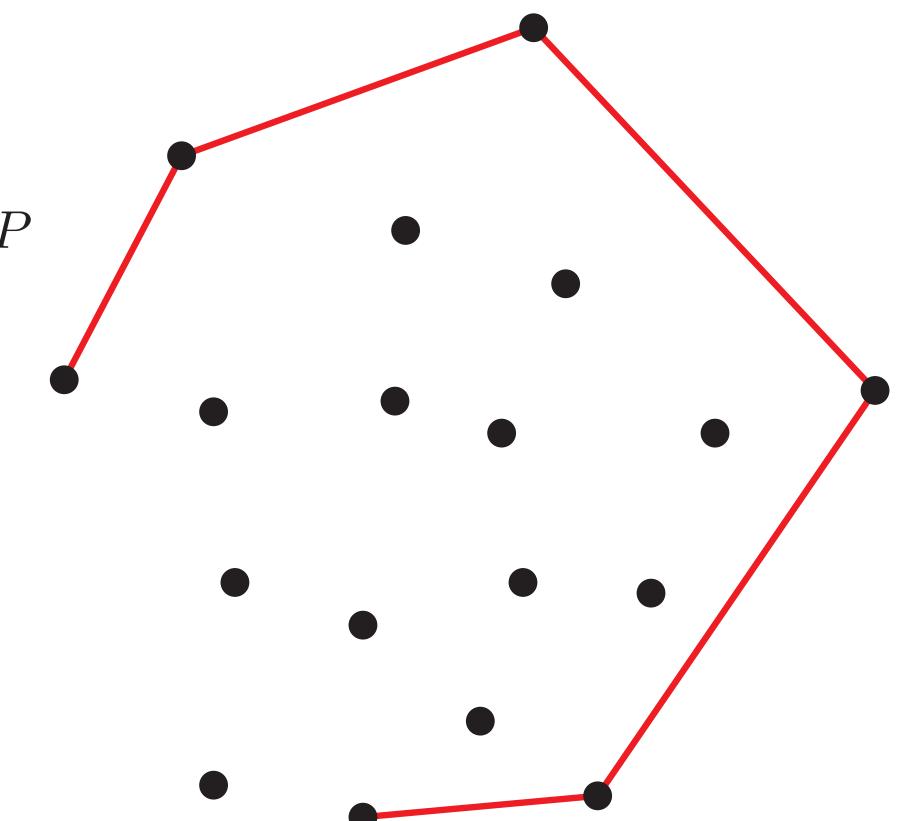
CONVEX HULL IN 2D

x of $ch(P)$ (for example, the lexicographically smaller point $p_i \in P$) and add it to l

last(l) \neq First(l), do:

the angularly rightmost point $p_j \in P$
with respect to v .

to l



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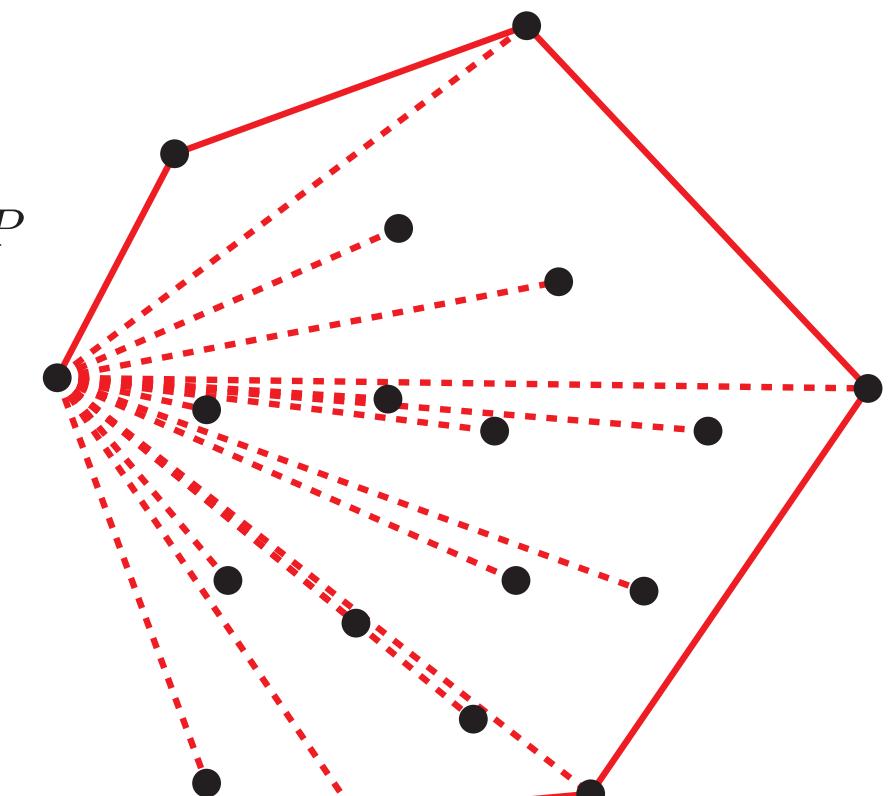
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x of $ch(P)$ (for example, the lexicographically smaller point $p_i \in P$) and add it to l

$\text{ast}(l) \neq \text{First}(l)$, do

the angularly rightmost point $p_j \in L$ with respect to v .

to



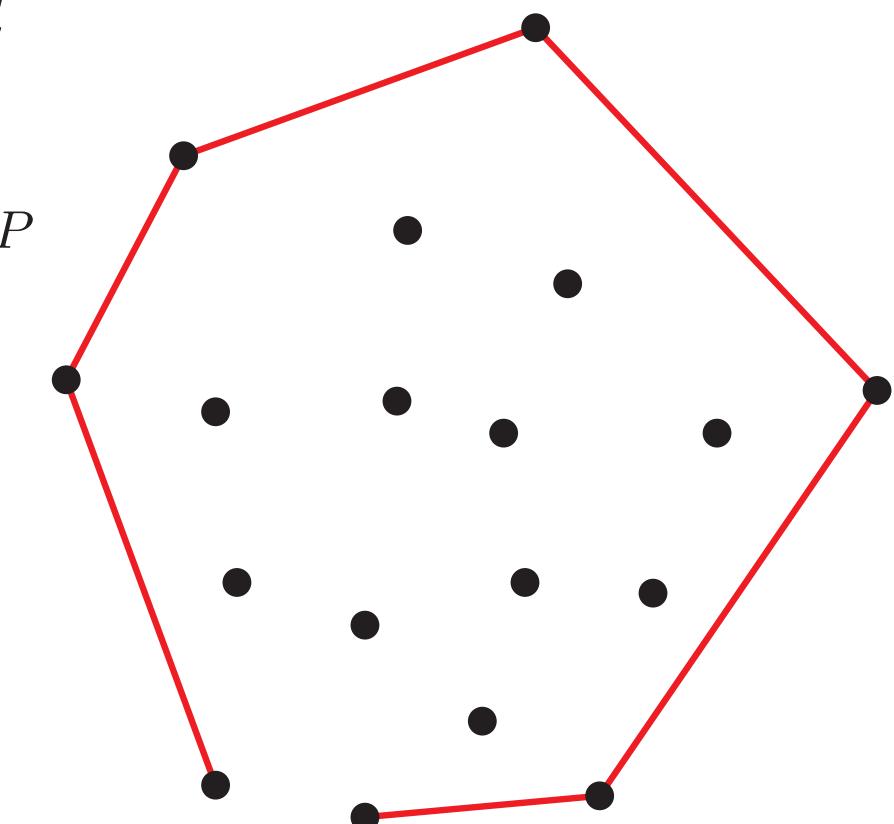
CONVEX HULL IN 2D

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last(l) \neq First(l), do:

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to l



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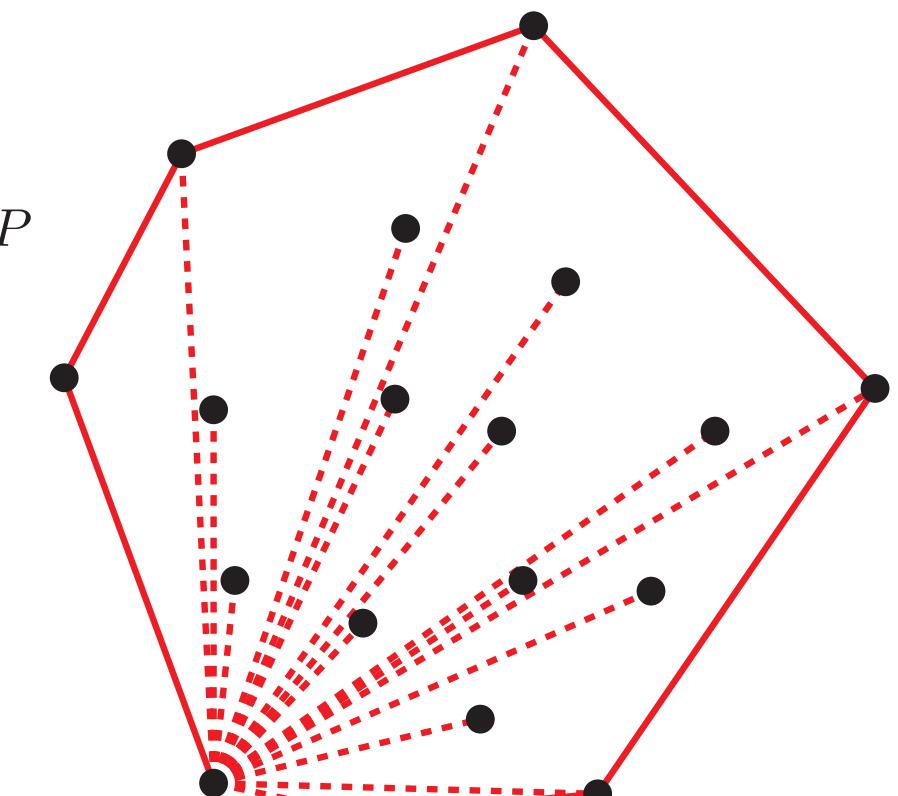
CONVEX HULL IN 2D

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the angularly rightmost point $p_j \in P$
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to l



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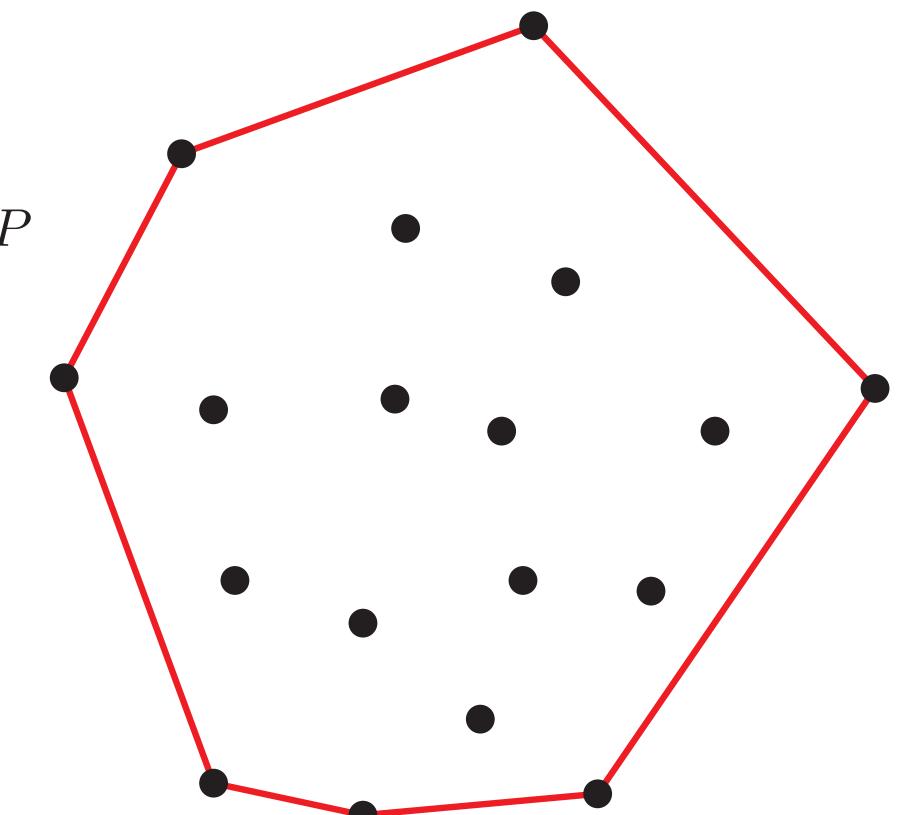
CONVEX HULL IN 2D

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to l



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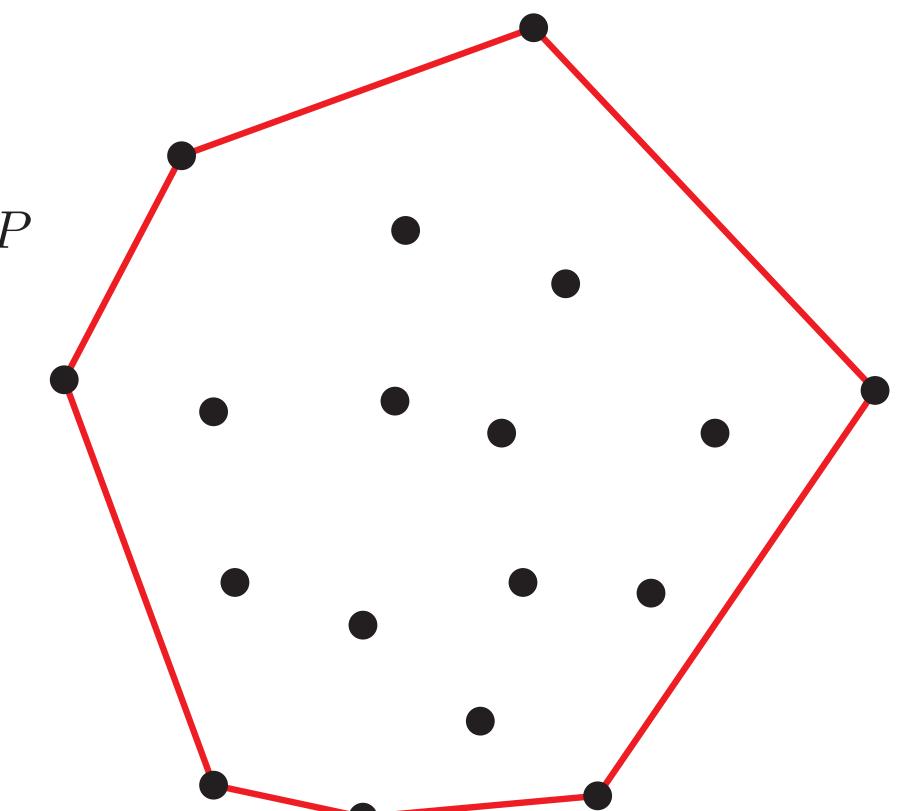
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last(l) \neq First(l), do:

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with respect to v .

to l

$$n) = O(n^2)$$



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CONVEX HULL IN 2D

hm (by prune-and-search)



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CONVEX HULL IN 2D

hm (by prune-and-search)

extreme points in the horizontal and vertical directions.

the convex hull of these (between 2 extreme points).

remaining points, and classify them according to their position (NE, SE, SW, NW) and remove them if they lie in the interior.

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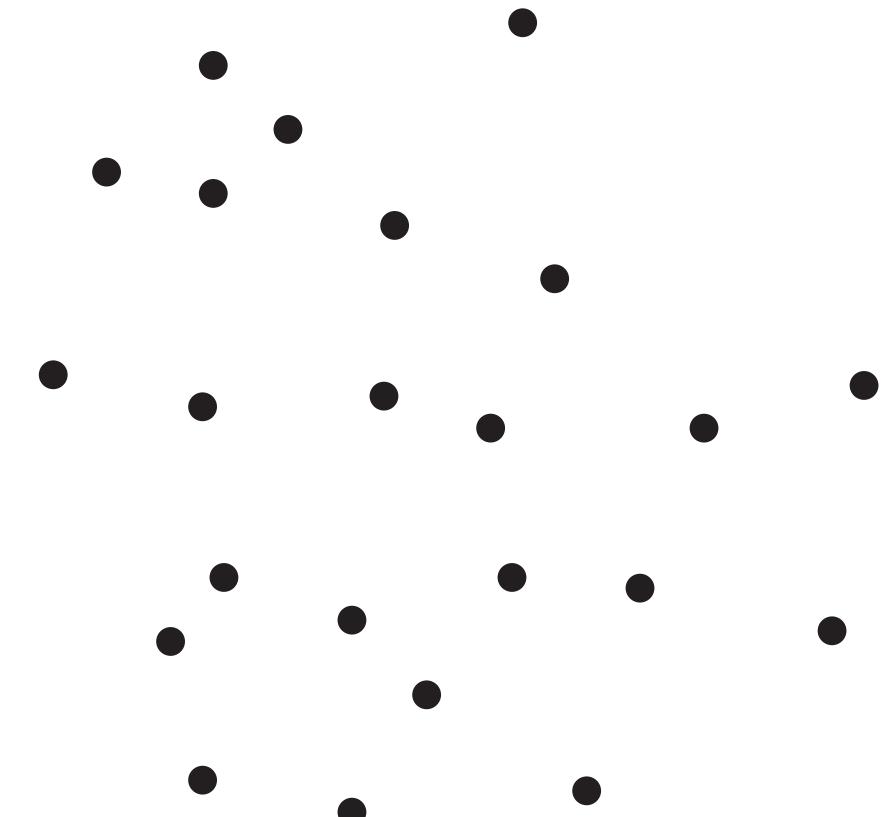
CONVEX HULL IN 2D

hm (by prune-and-search)

extreme points in the horizontal and vertical directions.

the convex hull of these (between 2 points).

remaining points, and classify them according to their position (NE, SE, SW, NW) and update the hull with them if they lie in the interior.



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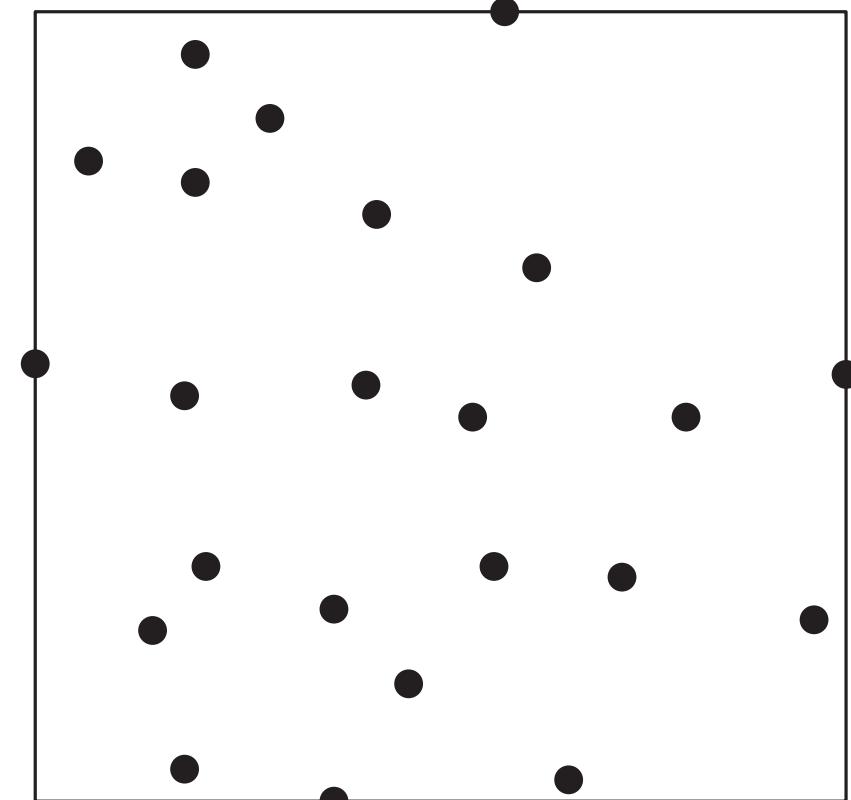
CONVEX HULL IN 2D

hm (by prune-and-search)

extreme points in the horizontal and vertical directions.

the convex hull of these (between 2 extreme points).

remaining points, and classify them according to their position (NE, SE, SW, NW) relative to the hull, and repeat them if they lie in the interior.



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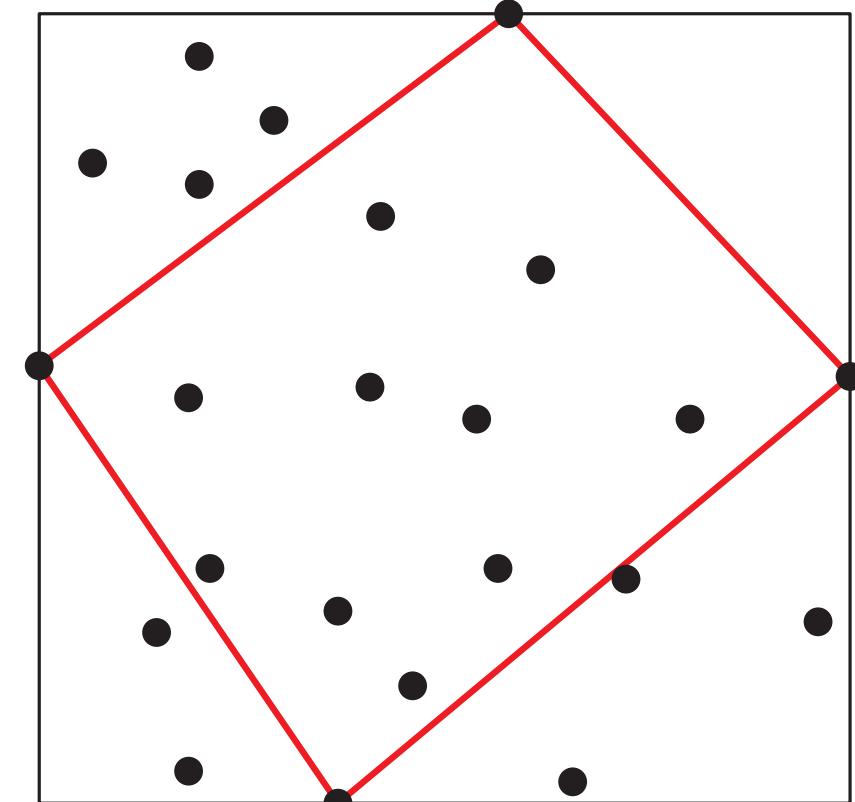
CONVEX HULL IN 2D

hm (by prune-and-search)

extreme points in the horizontal and vertical directions.

Find the convex hull of these (between 2 and 4 points).

Find the remaining points, and classify them according to their position (NE, SE, SW, NW) relative to the hull, and repeat them if they lie in the interior.



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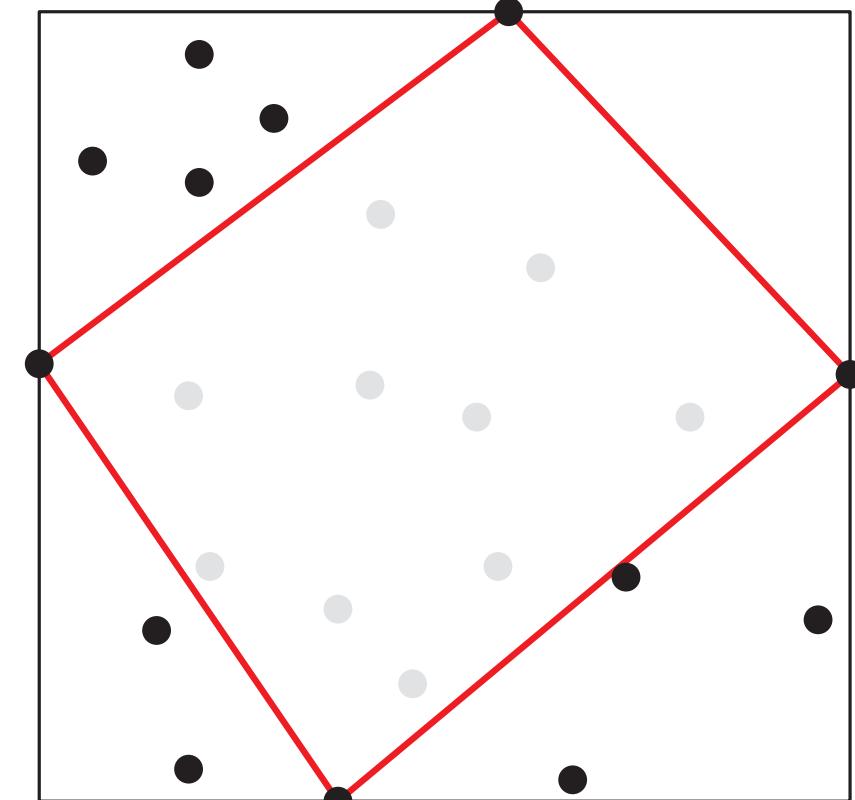
CONVEX HULL IN 2D

hm (by prune-and-search)

extreme points in the horizontal and vertical directions.

the convex hull of these (between 2 extreme points).

remaining points, and classify them according to their position (NE, SE, SW, NW) relative to the hull, and repeat them if they lie in the interior.



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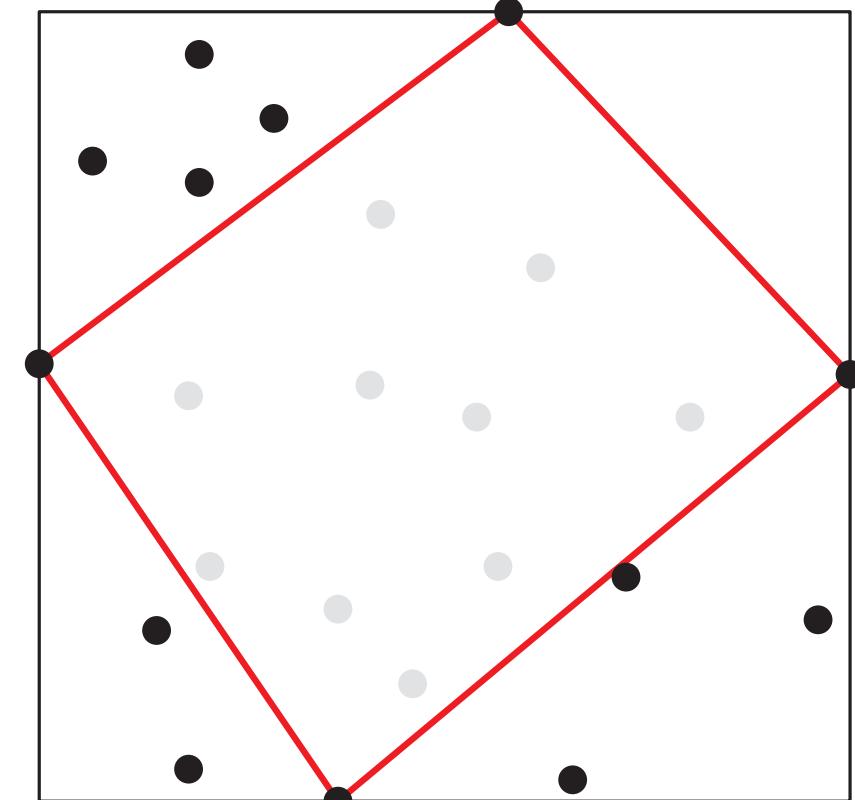
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the convex hull of these (between 2 extreme points).

remaining points, and classify them according to their position (NE, SE, SW, NW) relative to the hull, and repeat them if they lie in the interior.

this step: $O(n)$



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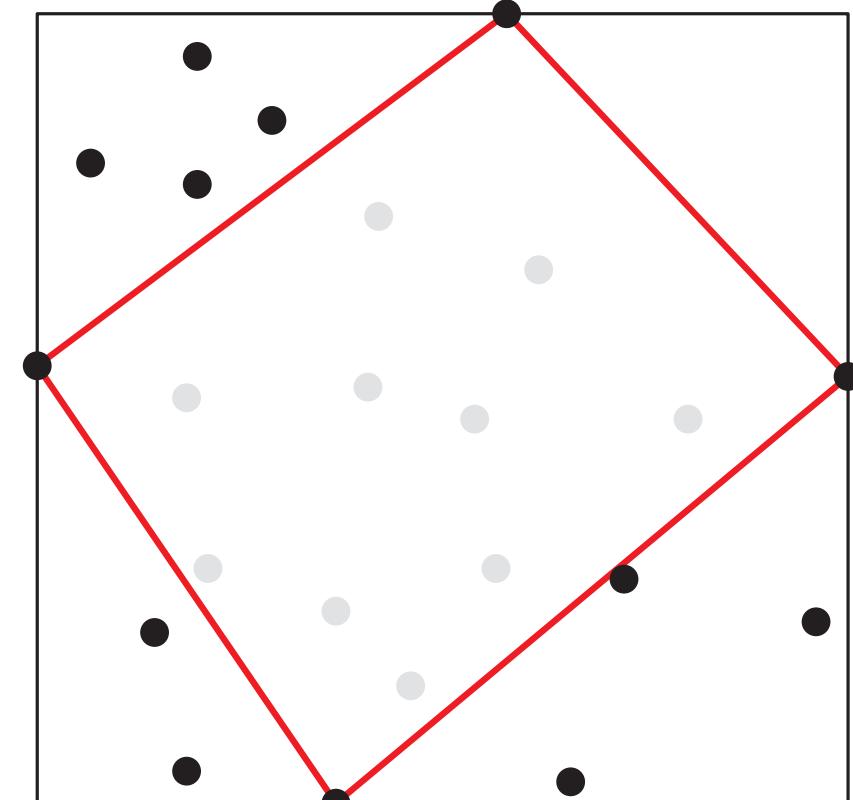
CONVEX HULL IN 2D

hm (by prune-and-search)

points lying in each region, find the point in the direction orthogonal to the line that determines the region.

extreme point with the endpoints of the line and update the convex hull.

remaining points of each region, and sort them according to their position (left or right) and eliminate them if they lie in the interior of the created triangle.



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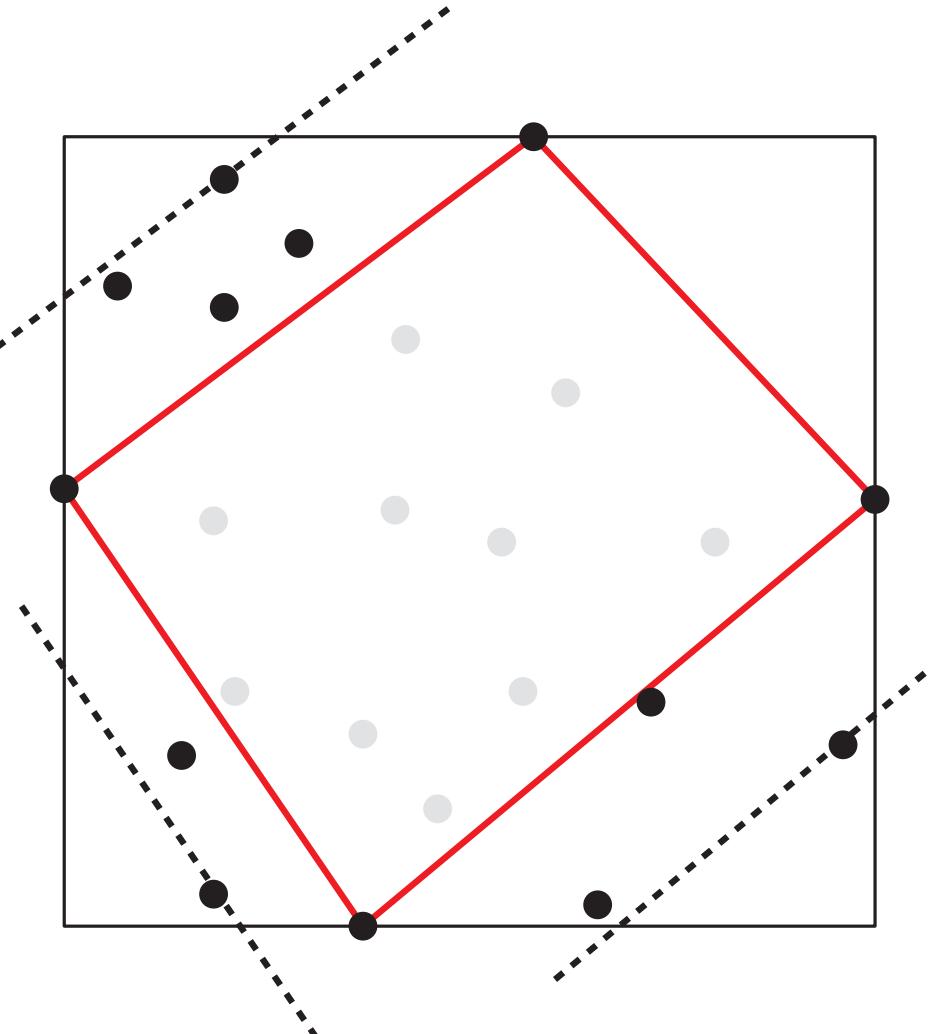
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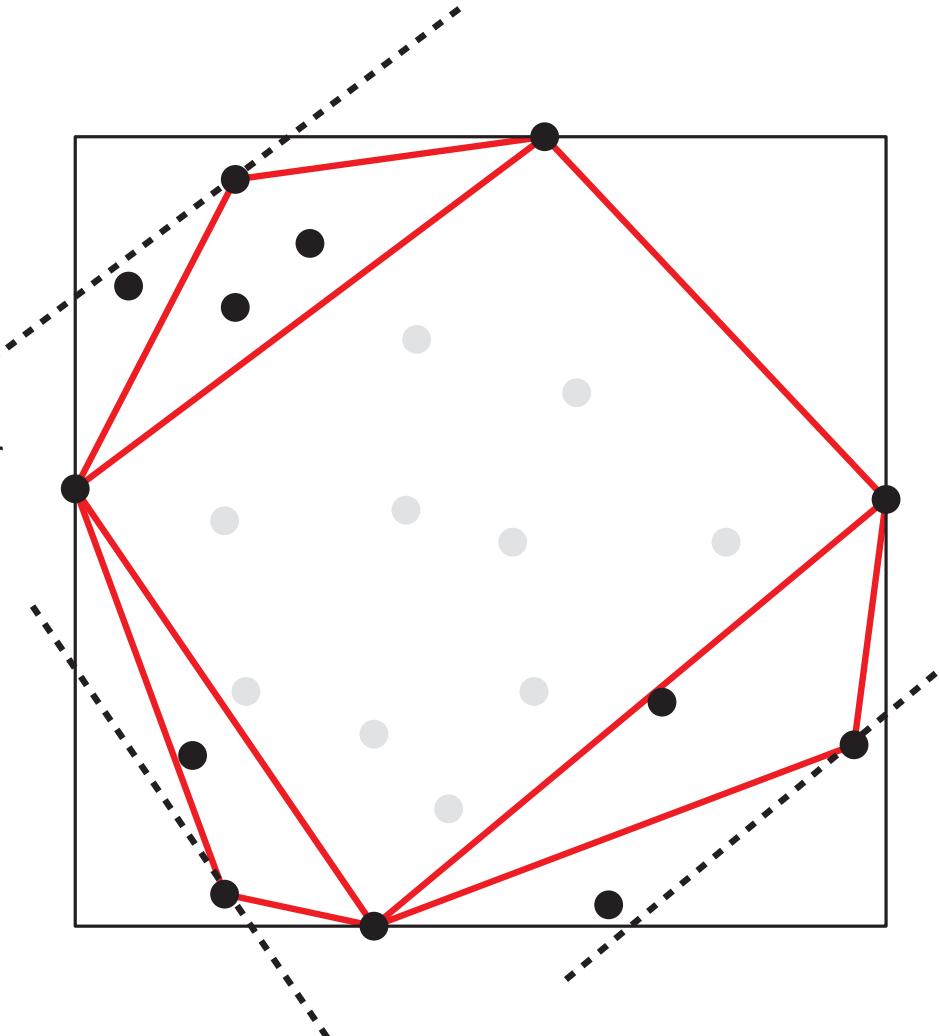
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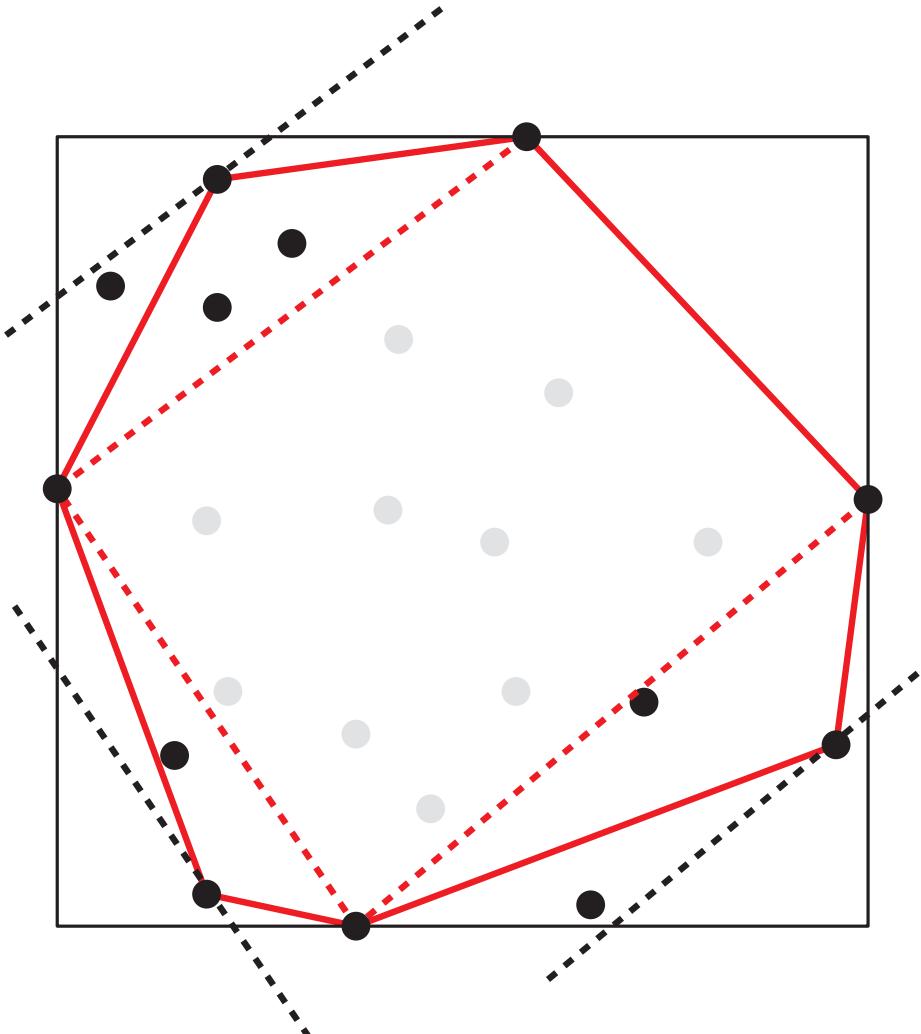
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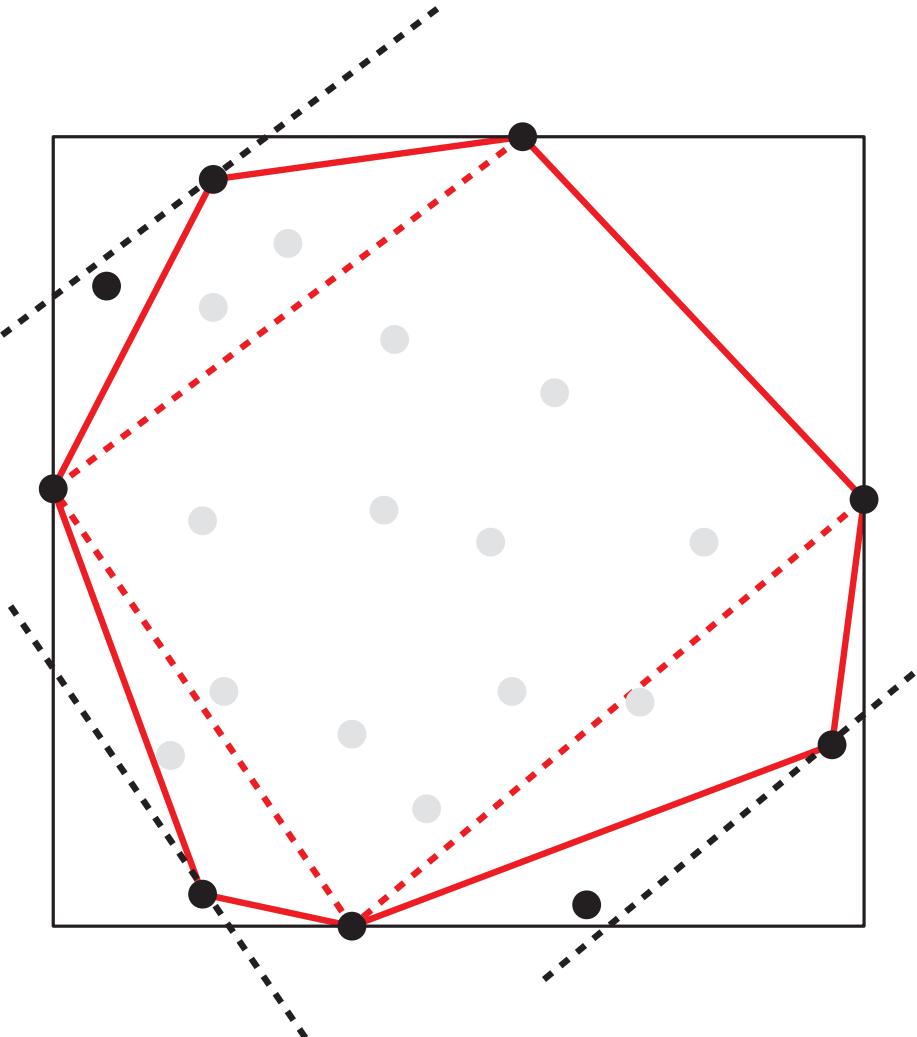
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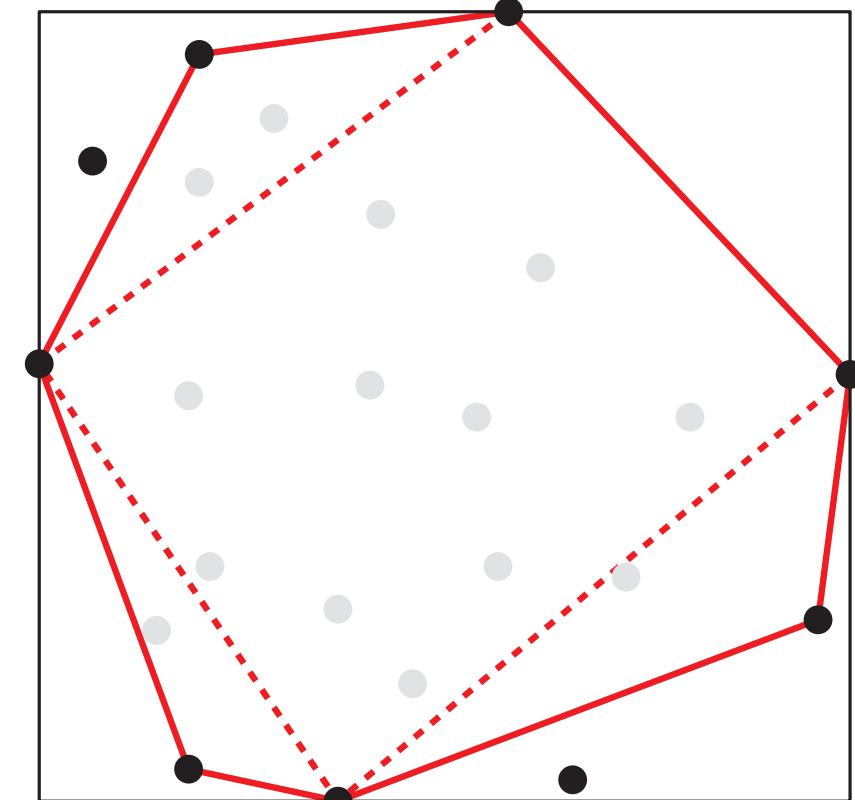
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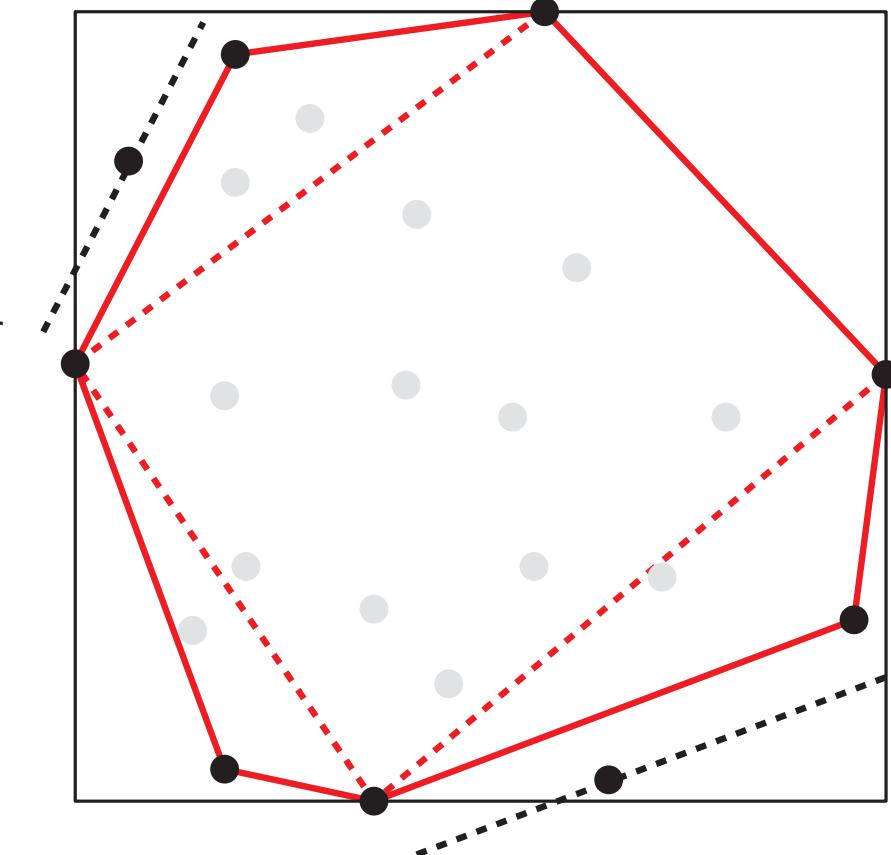
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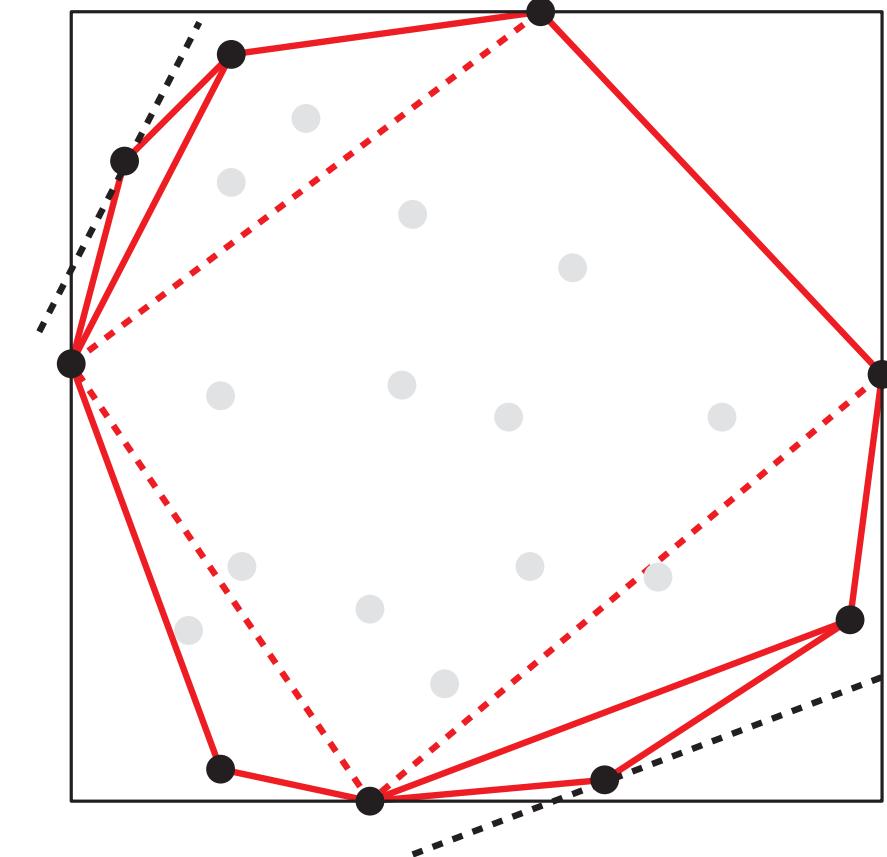
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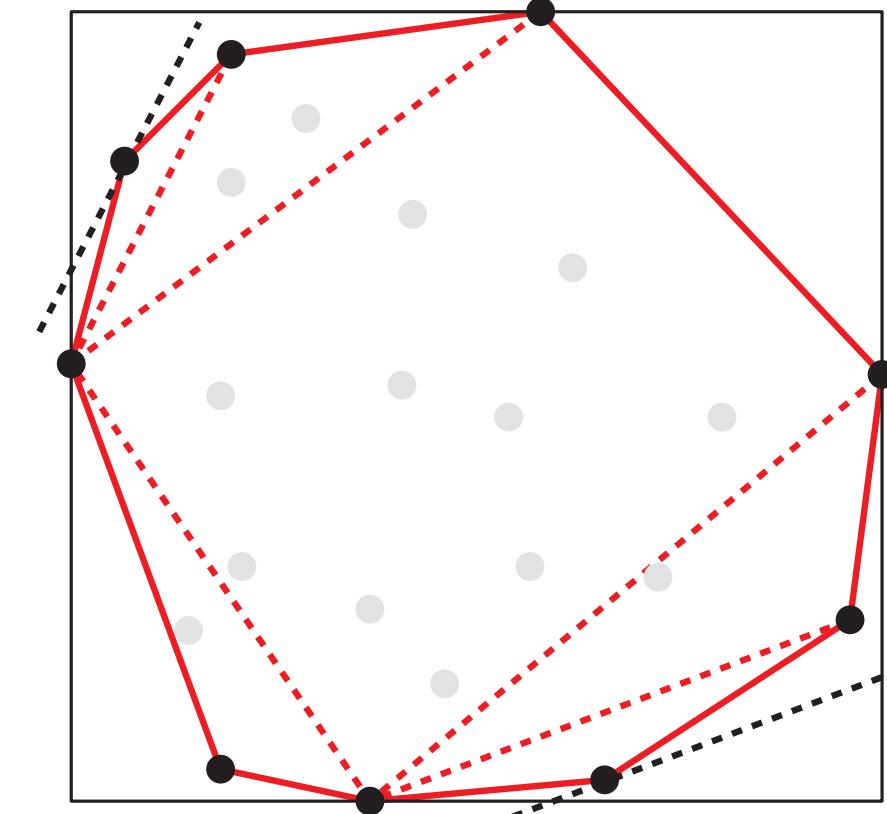
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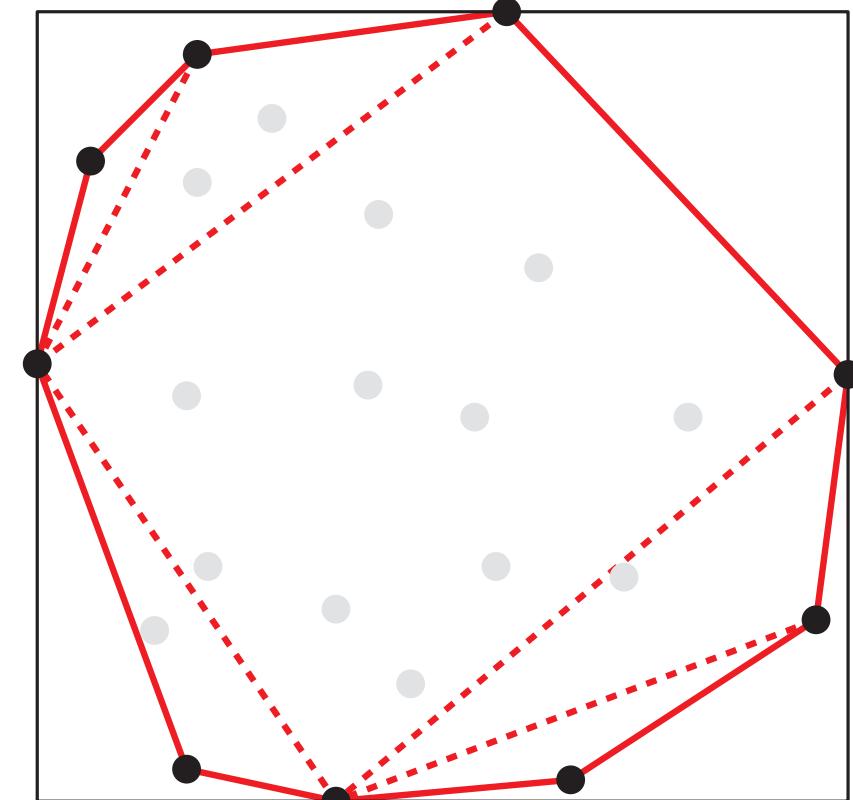
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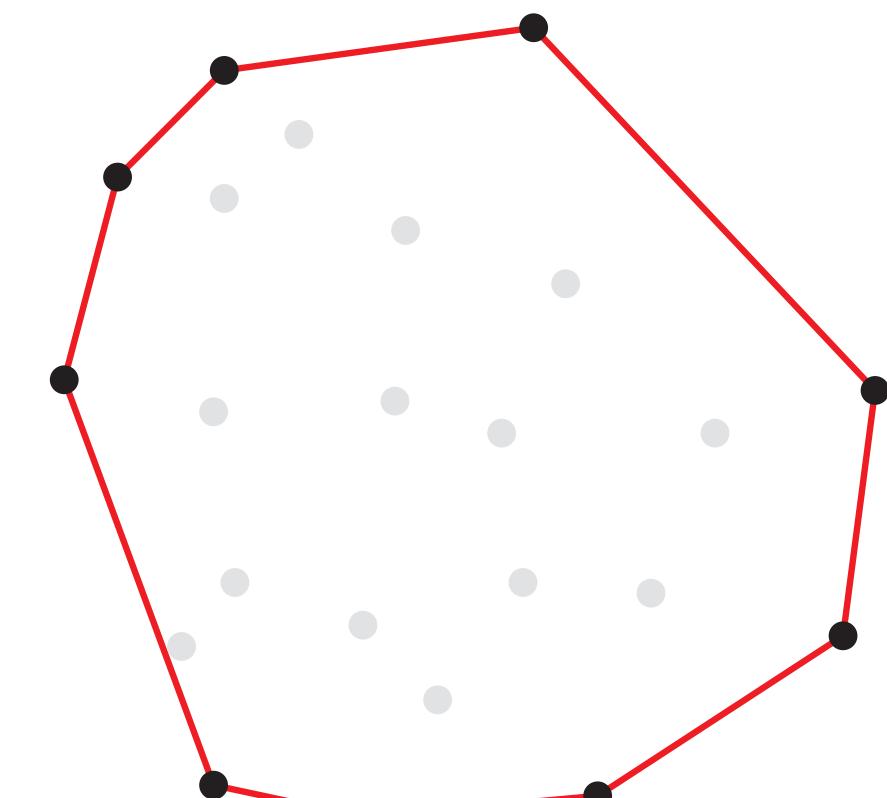
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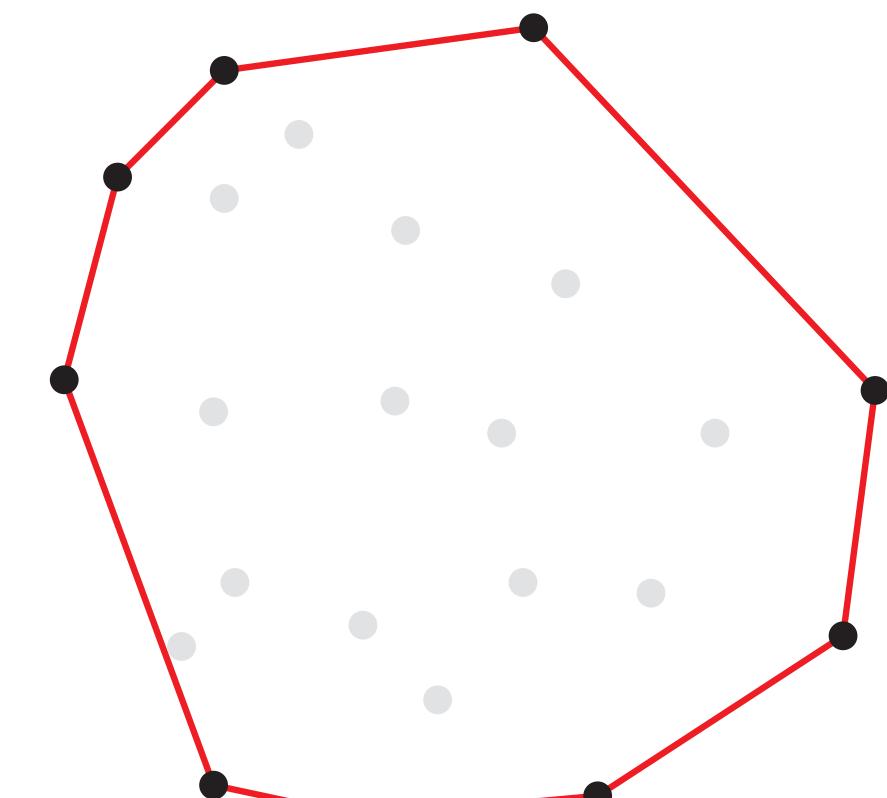
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this step: $O(n^2)$



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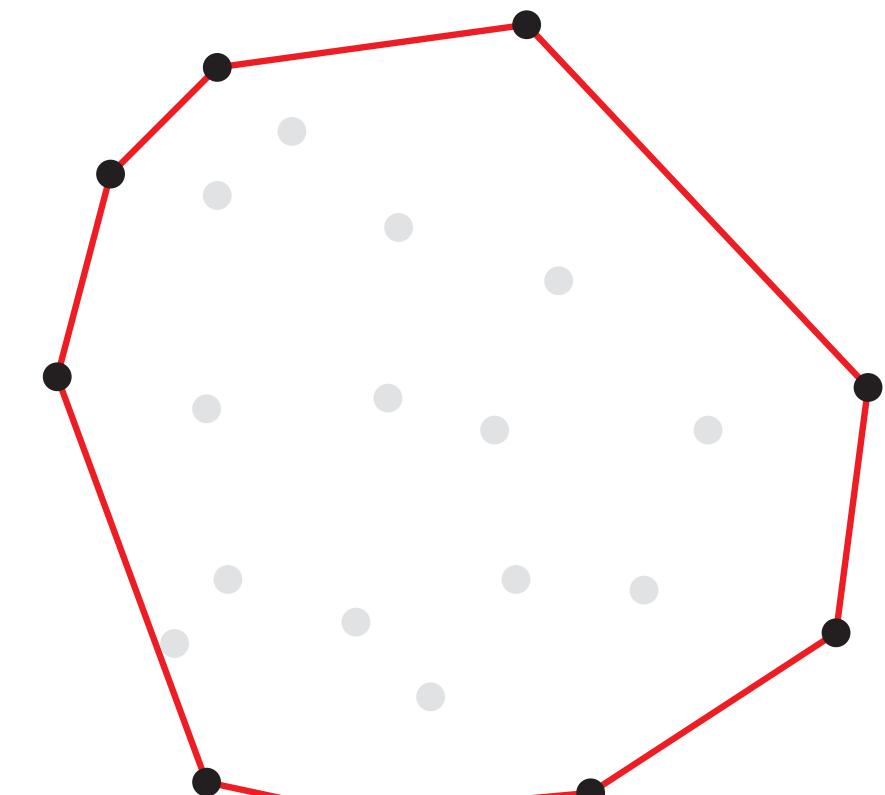
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Run

CONVEX HULL IN 2D

hm (by prune-and-search)

time: $O(n^2)$



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CONVEX HULL IN 2D

hm (by prune-and-search)

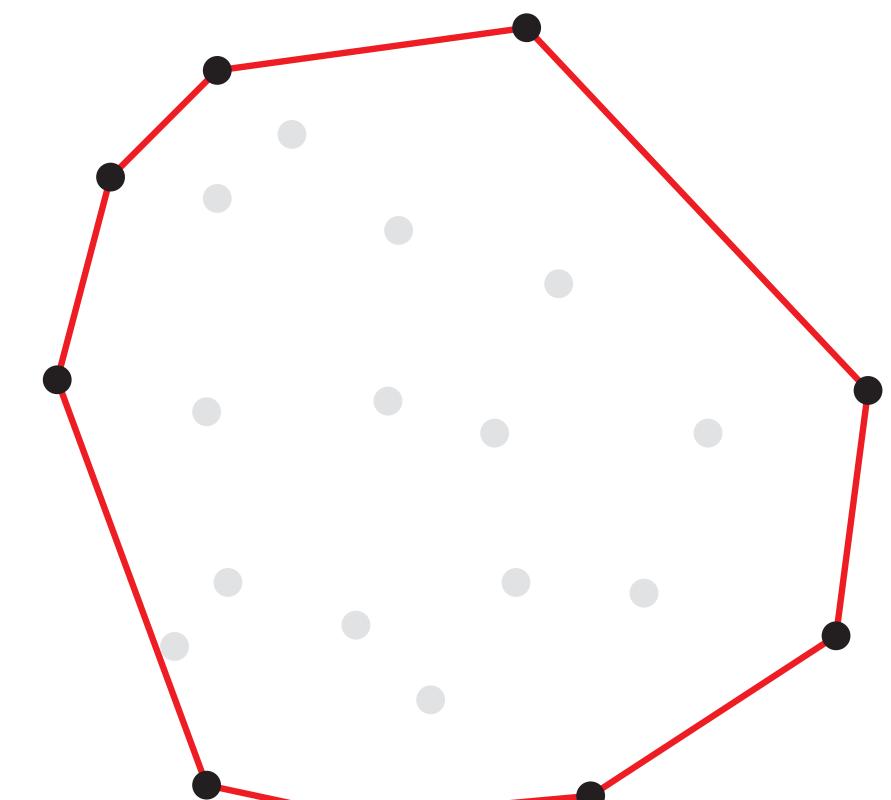
time: $O(n^2)$

running time of this algorithm depends on the input points.

points are in convex position, the time is $\Theta(n^2)$.

are such that each prune step eliminates all the current points, then the algorithm runs in $\Theta(n \log n)$ time.

If the hull is triangular, the algorithm runs in $\Theta(n)$ time.



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CONVEX HULL IN 2D

hm

◦ of $ch(P)$, push it in l and delete it from P
the points around v
point in l and delete if from P

◦ for points $p_i \in P$ to be explored, do:

◦ $s(\text{top}(l))$
◦ left turn:
◦ in l
◦ e_i
◦ from l

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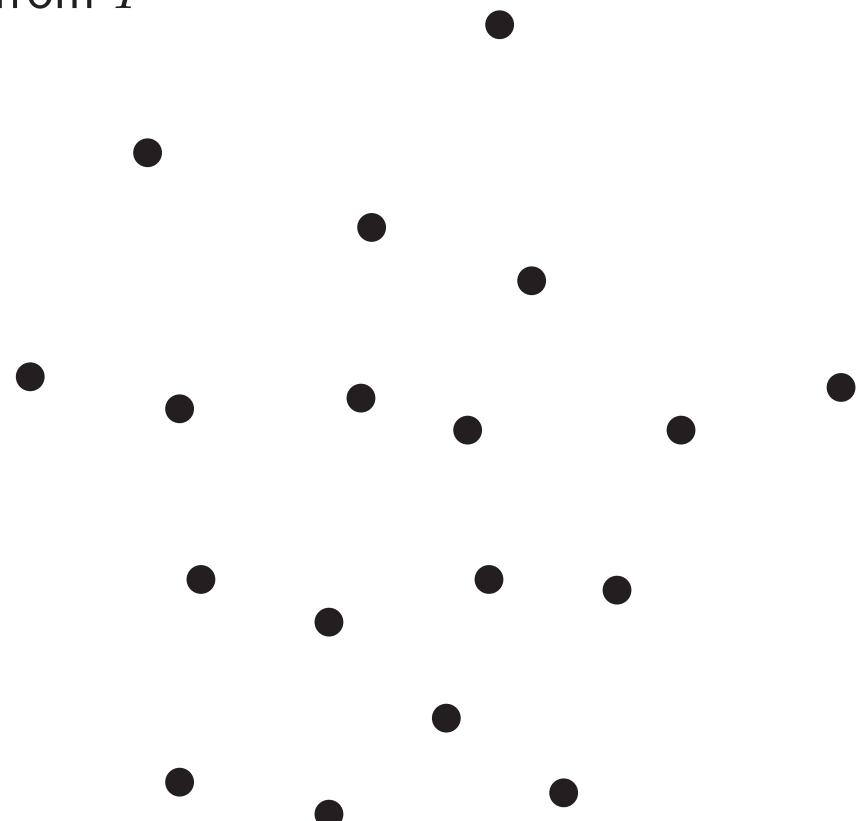
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in l

e i

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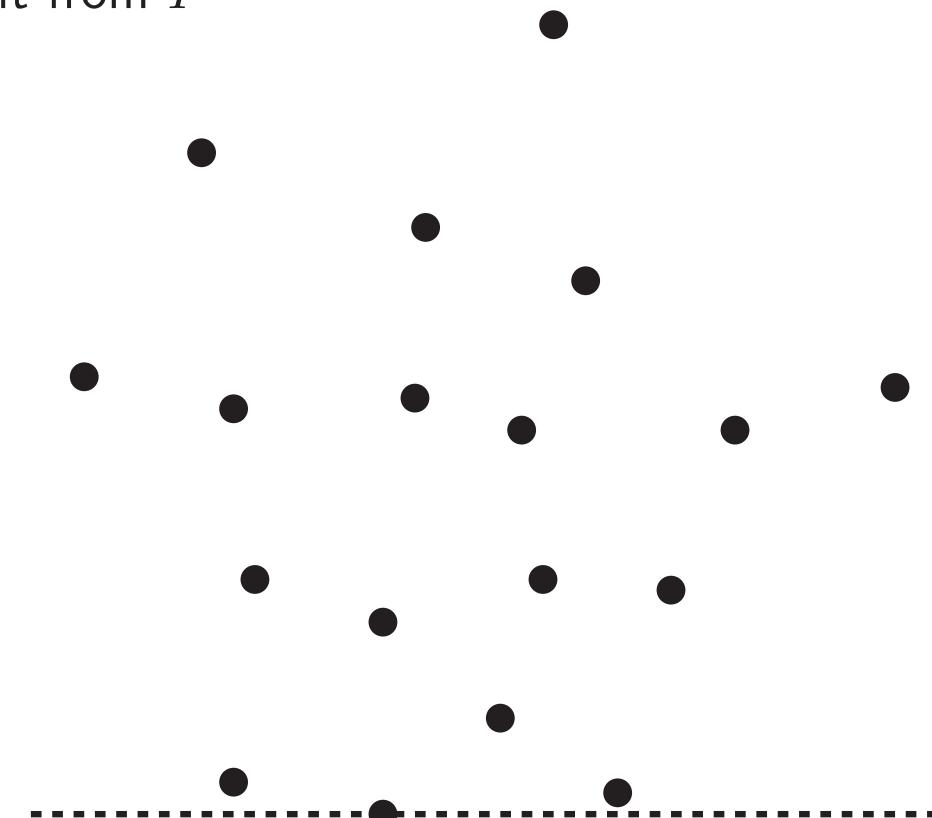
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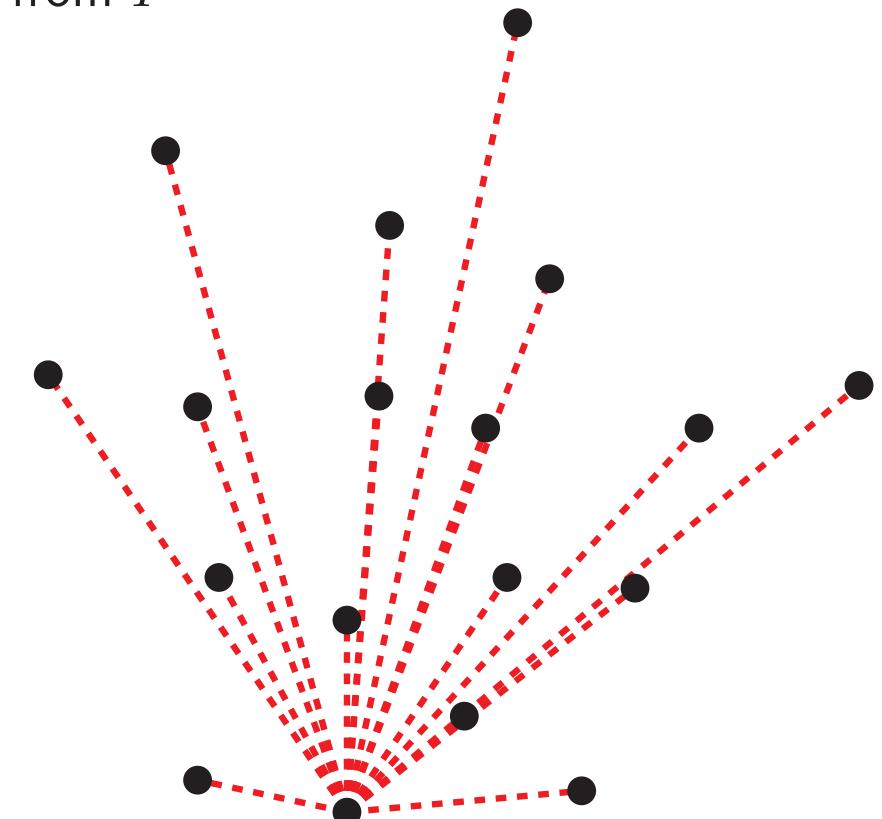
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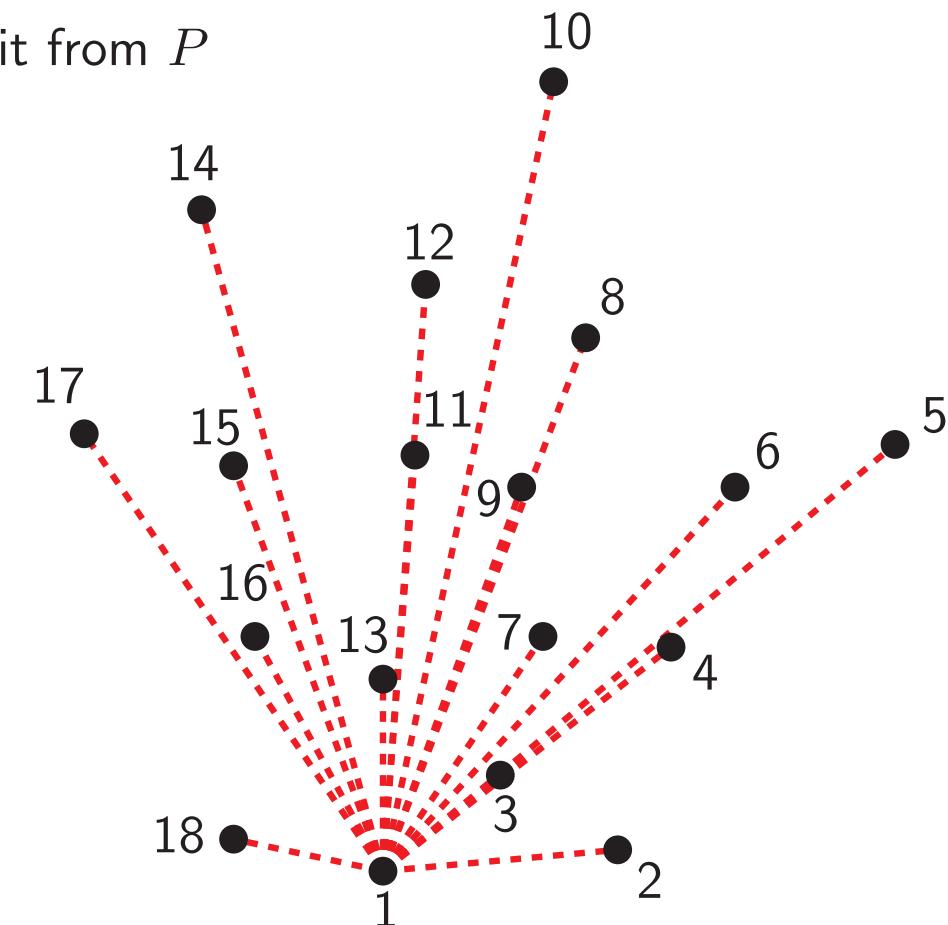
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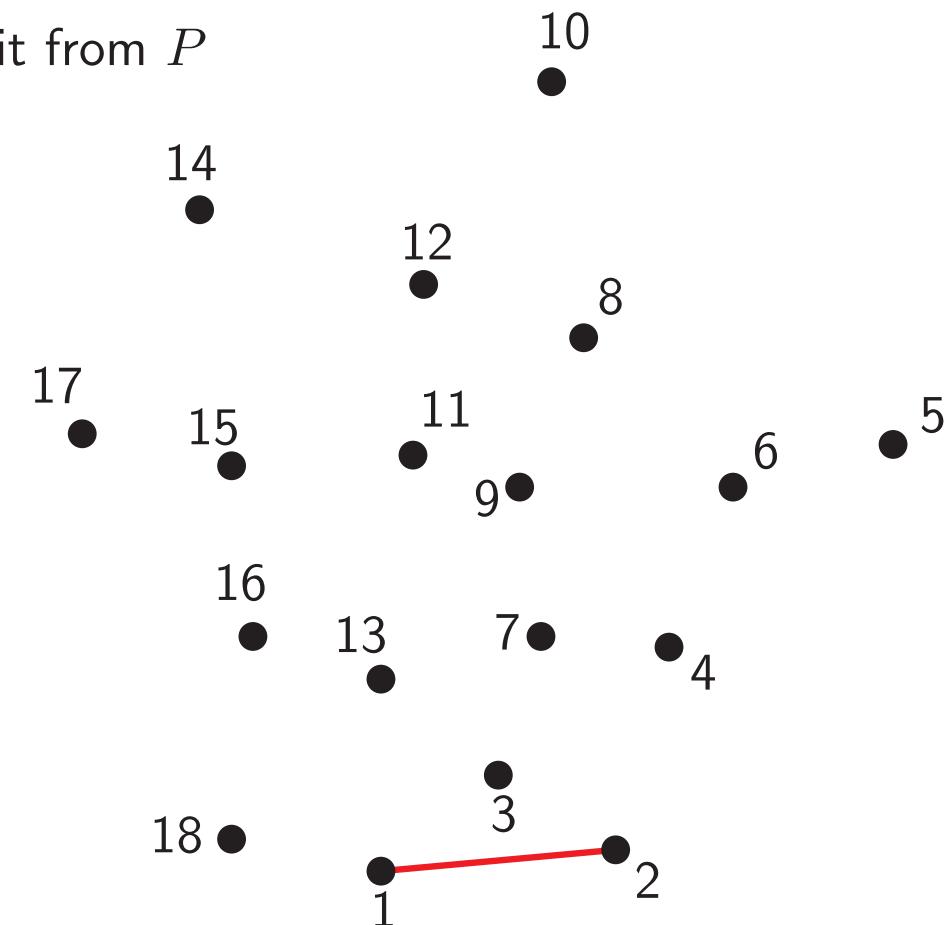
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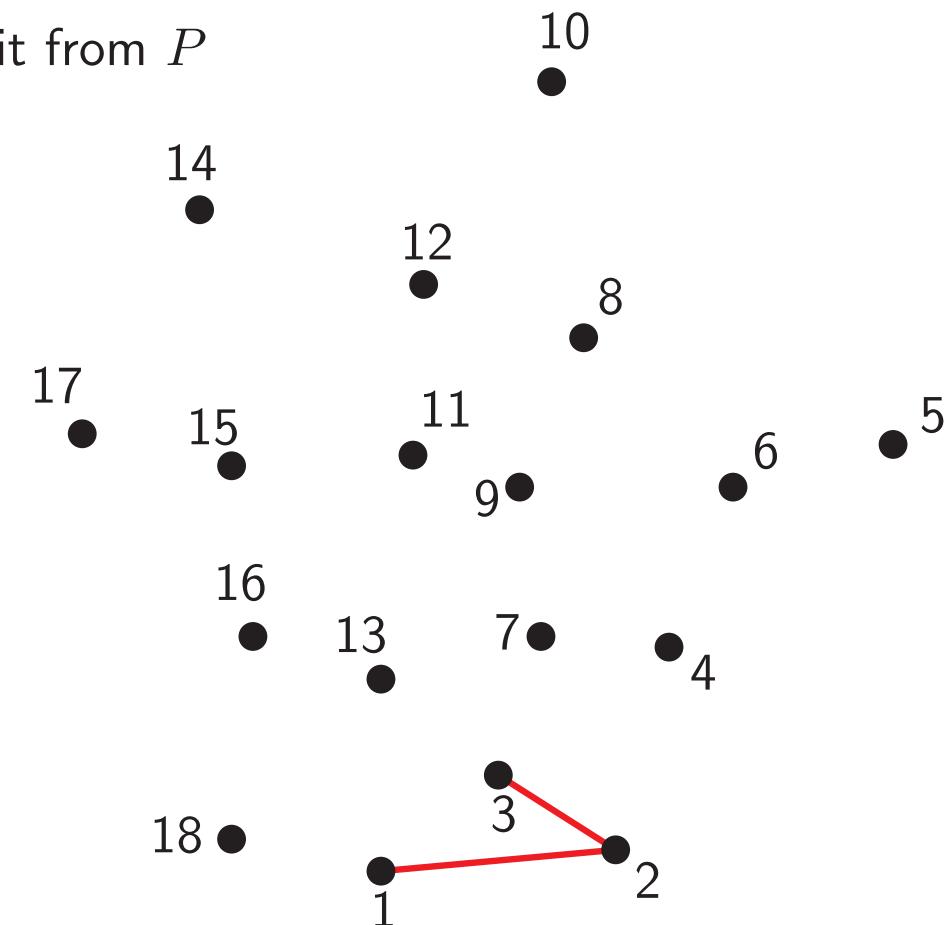
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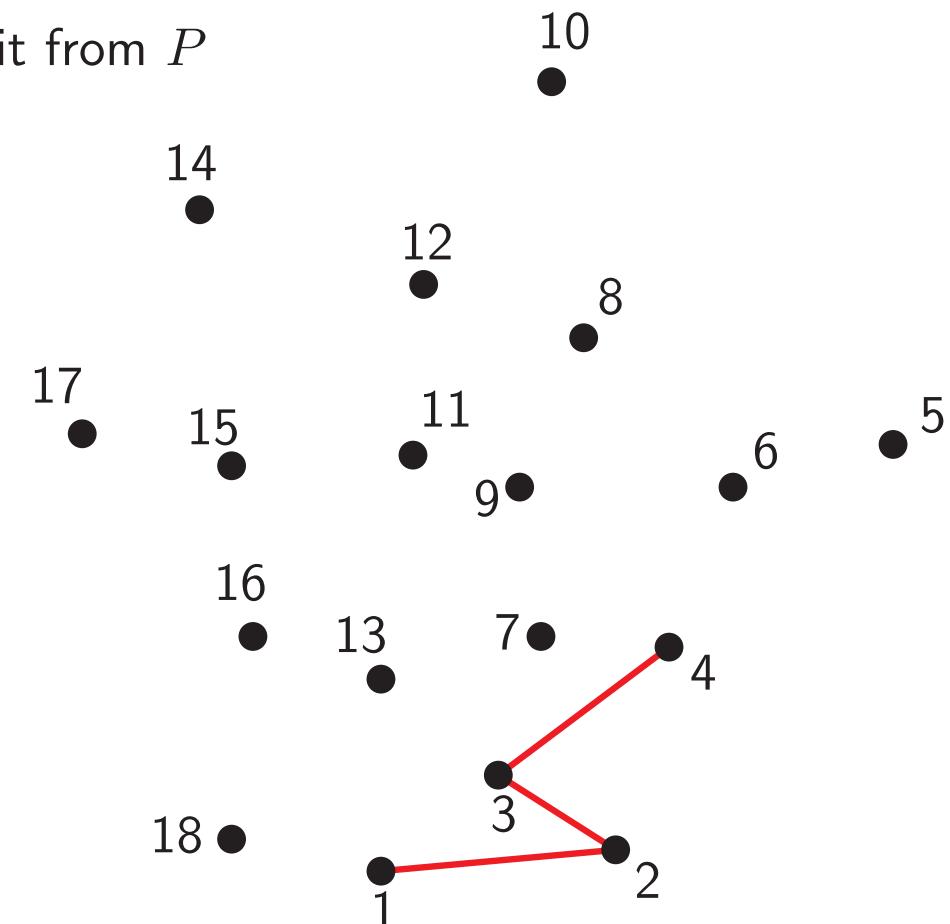
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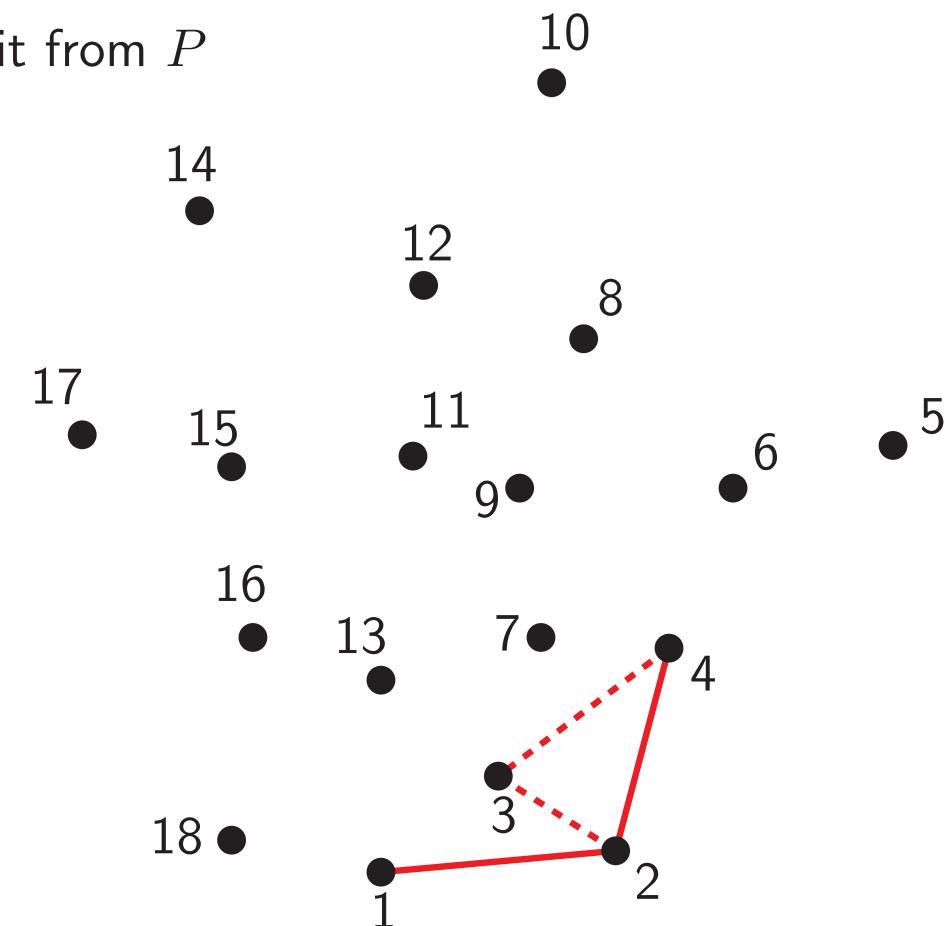
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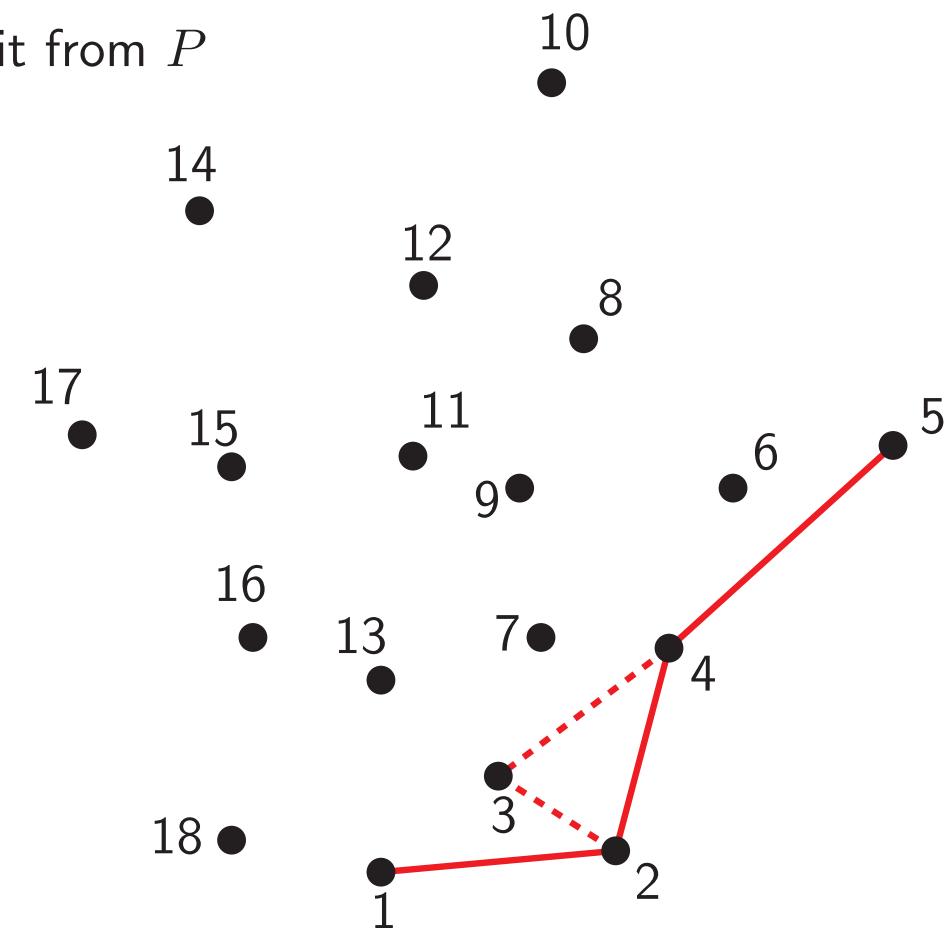
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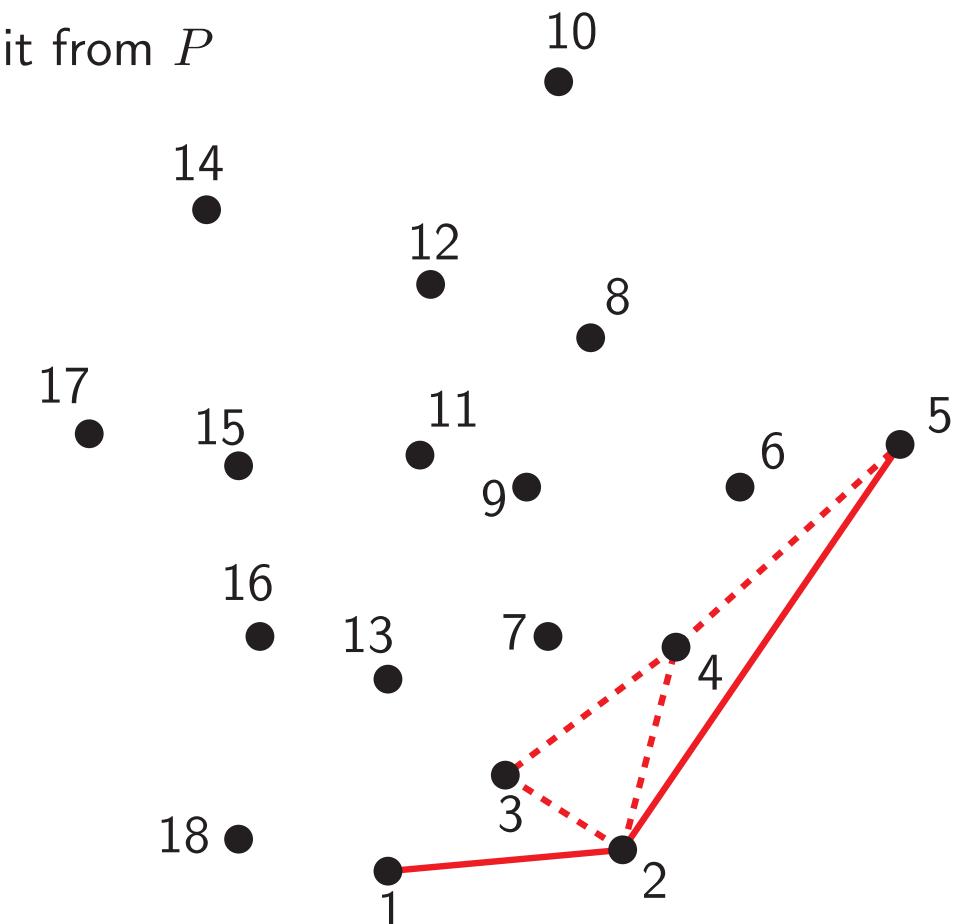
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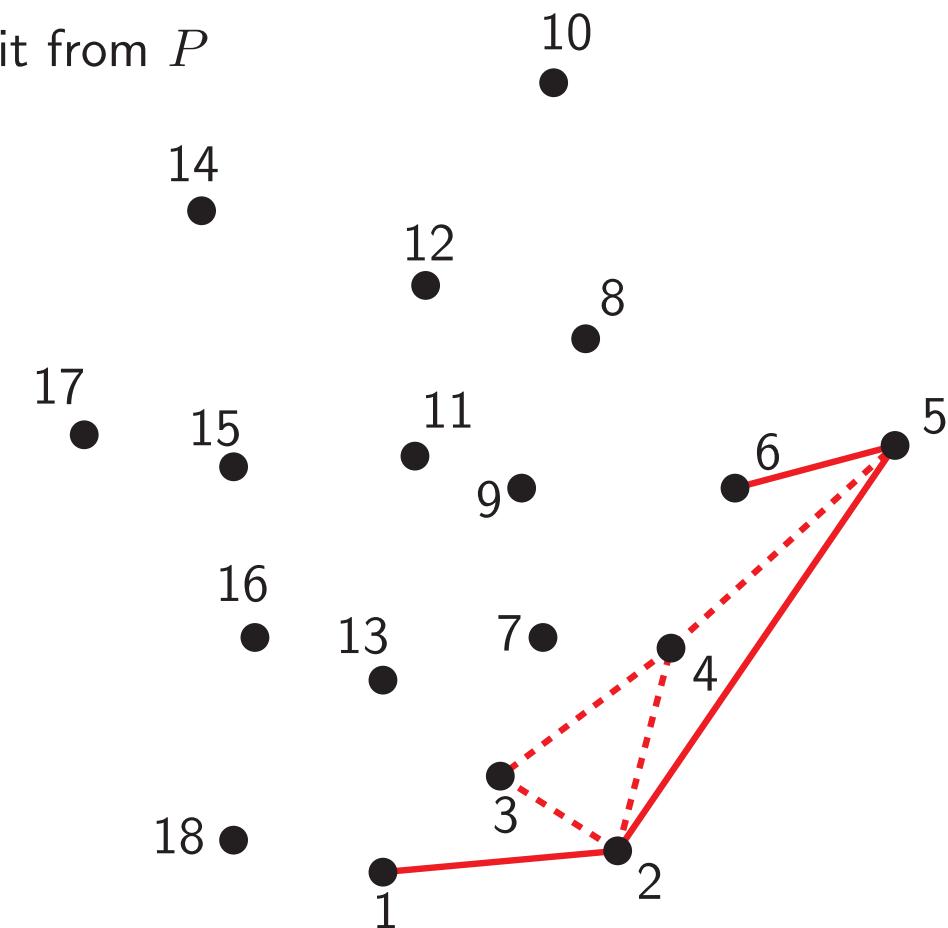
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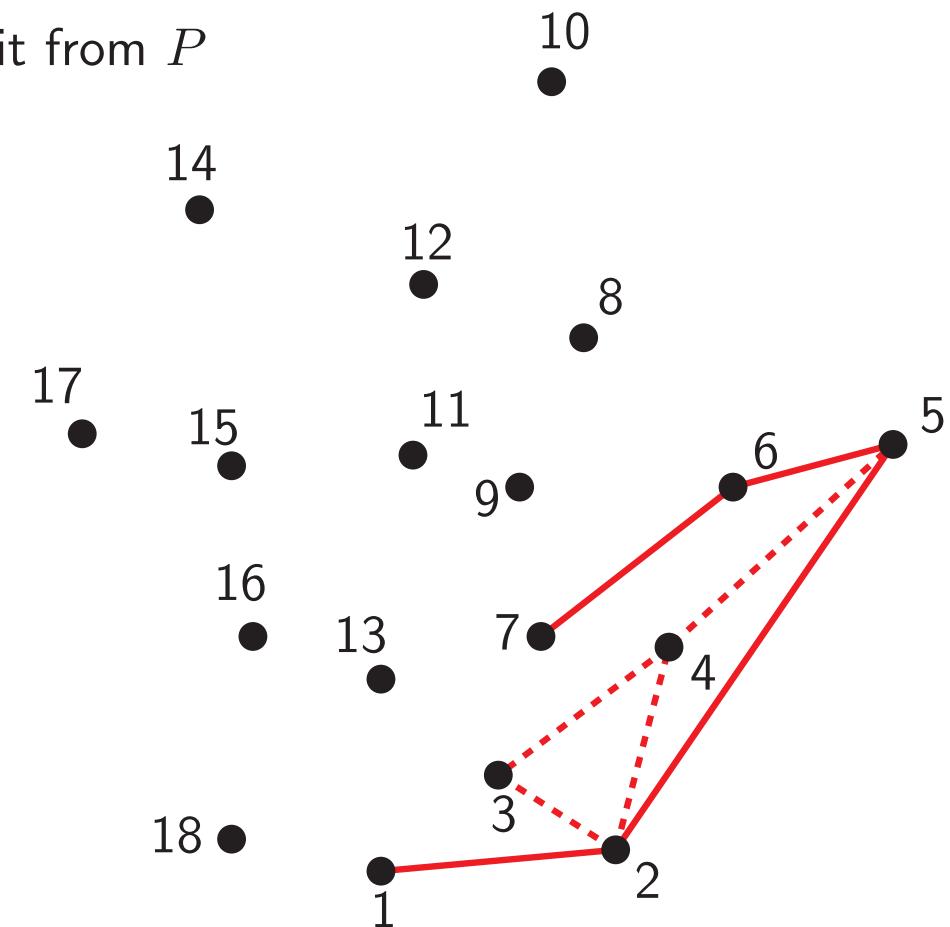
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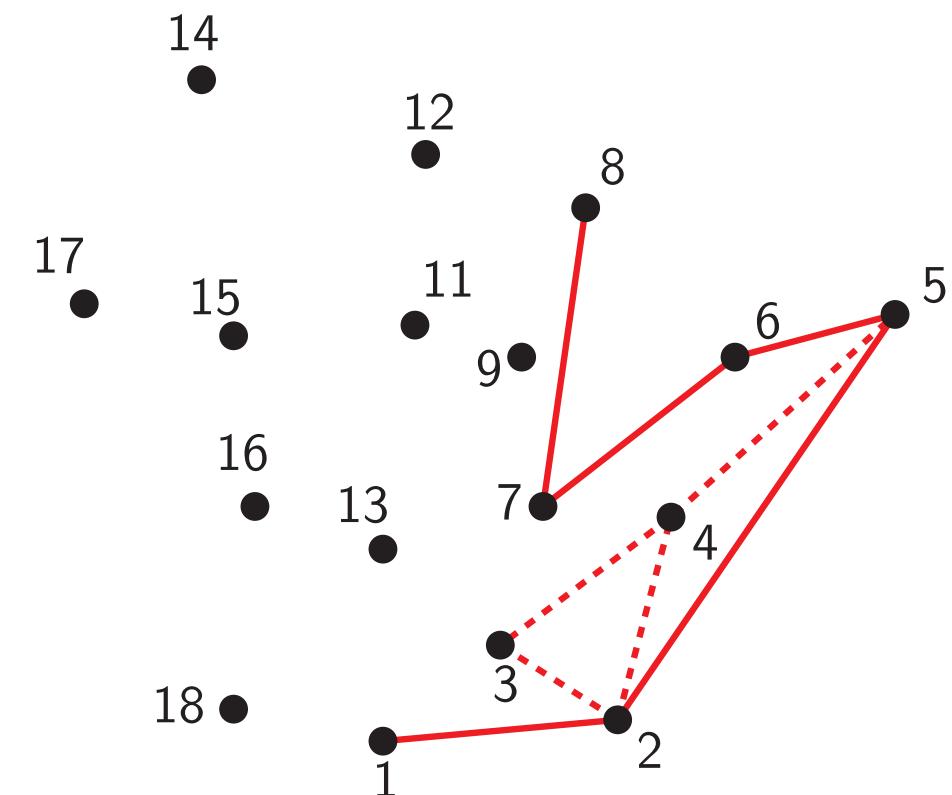
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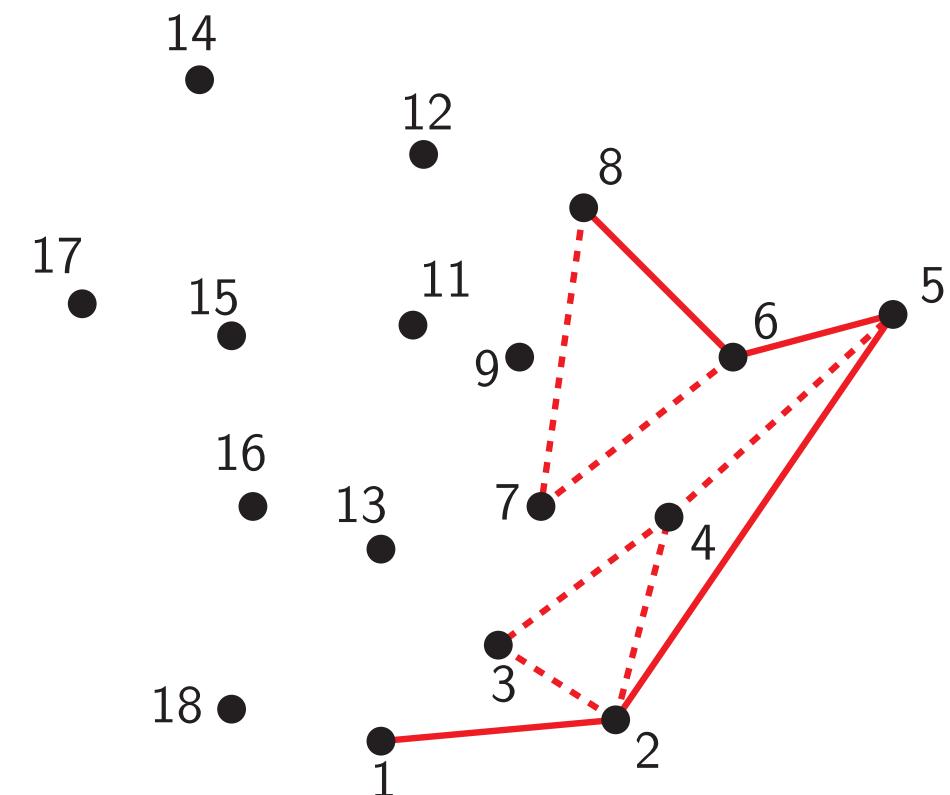
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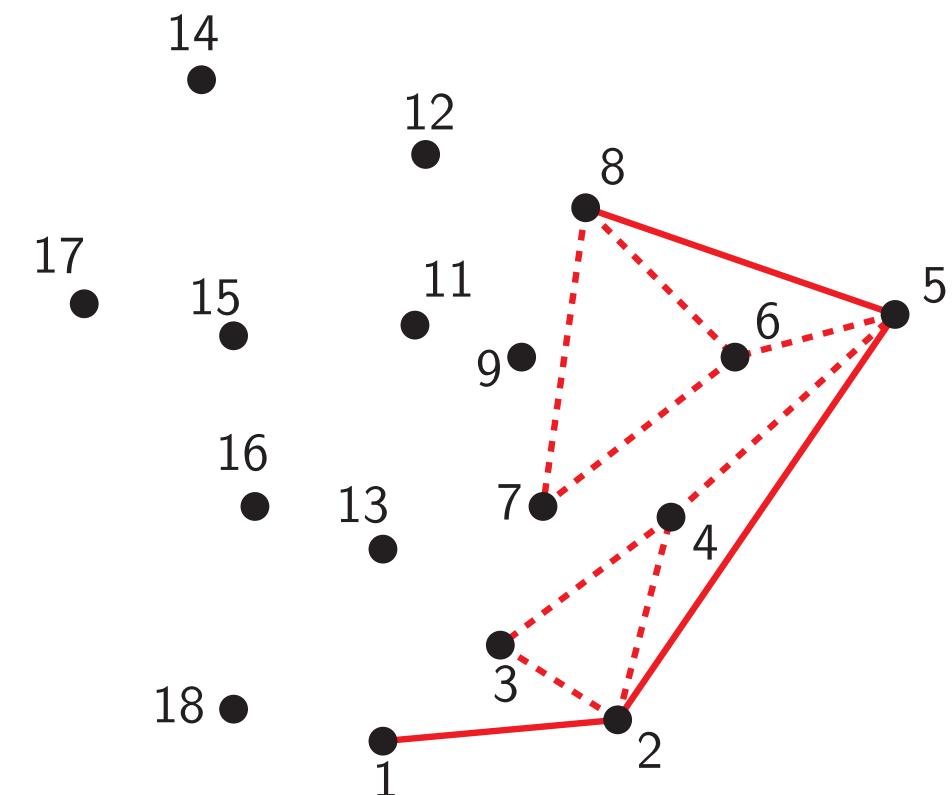
◦ $s(\text{top}(l))$

◦ left turn:

◦ in l

◦ i

◦ from l



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CONVEX HULL IN 2D

hm

◦ of $ch(P)$, push it in l and delete it from P
the points around v
point in l and delete if from P

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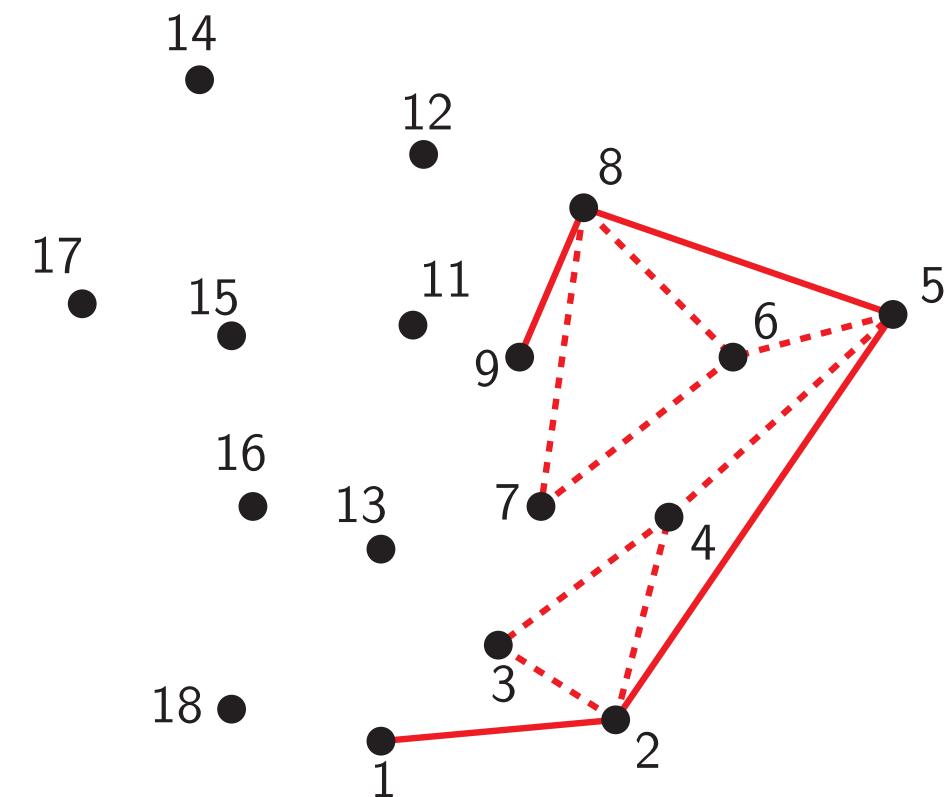
s($\text{top}(l)$)

left turn:

in l

e i

from l



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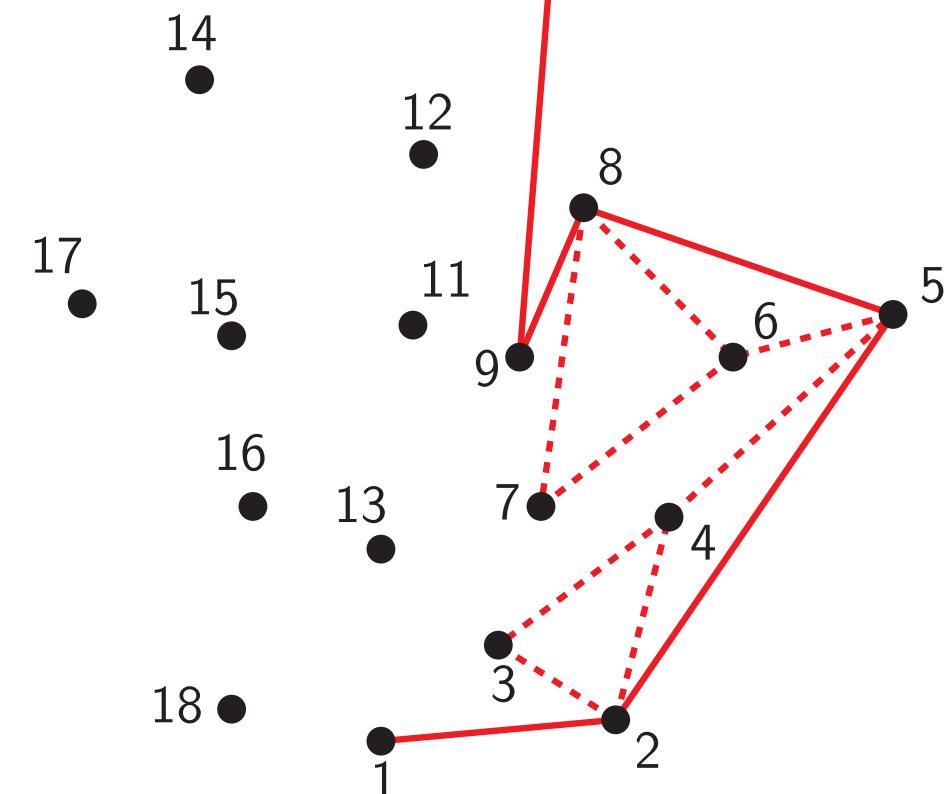
s($\text{top}(l)$)

left turn:

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e i

from l



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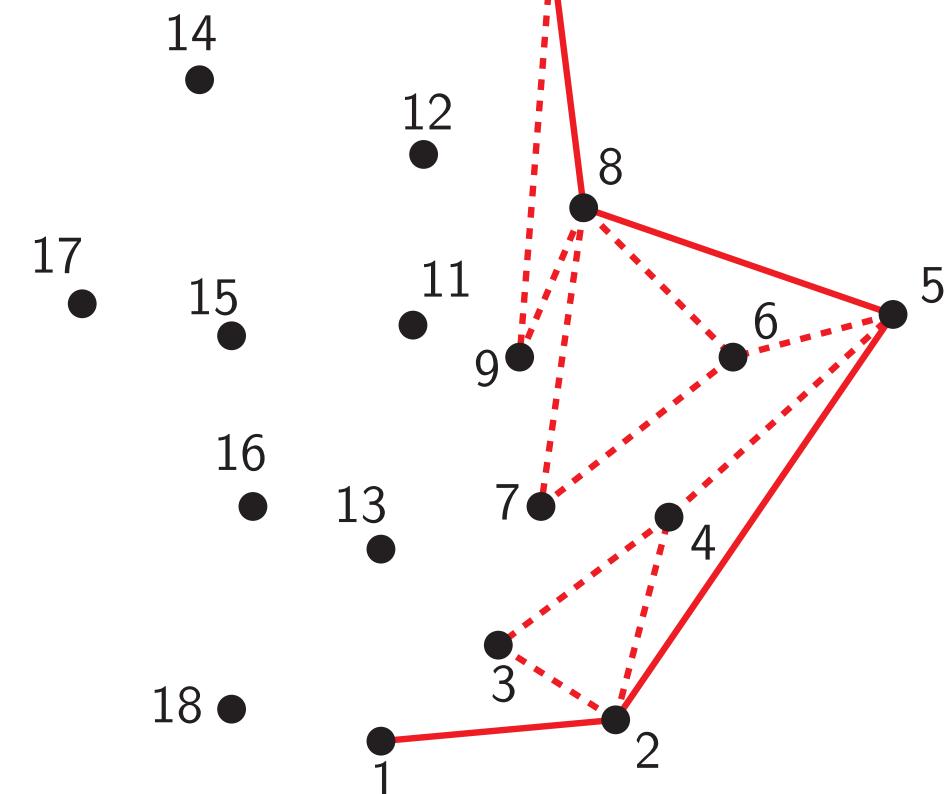
◦ $s(\text{top}(l))$

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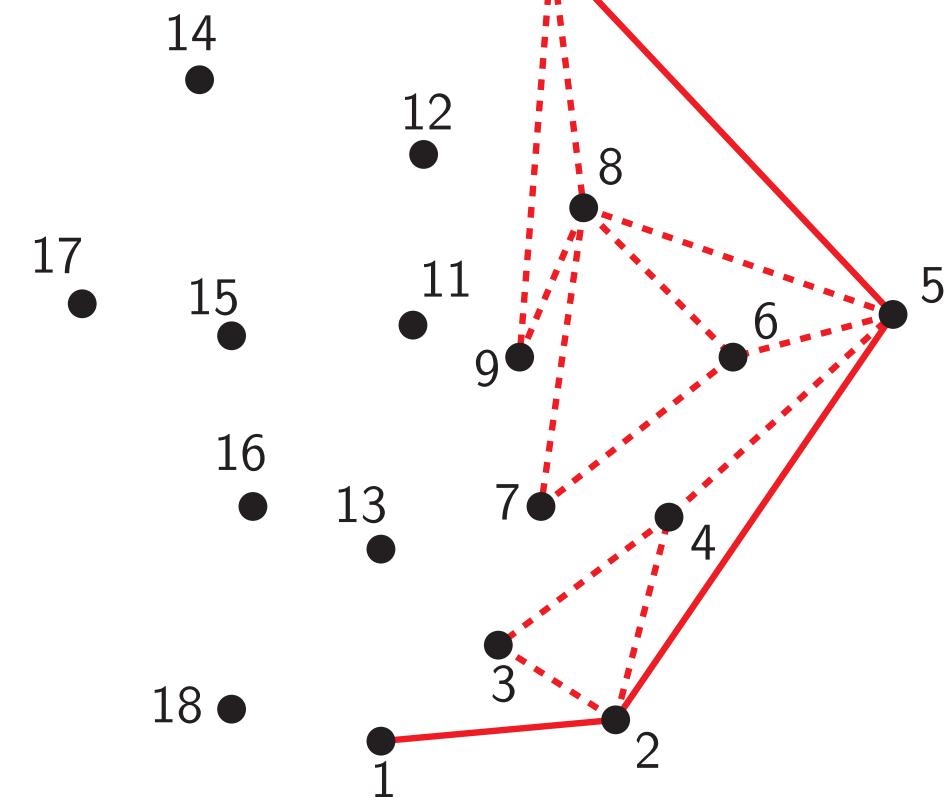
s($\text{top}(l)$)

left turn:

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e i

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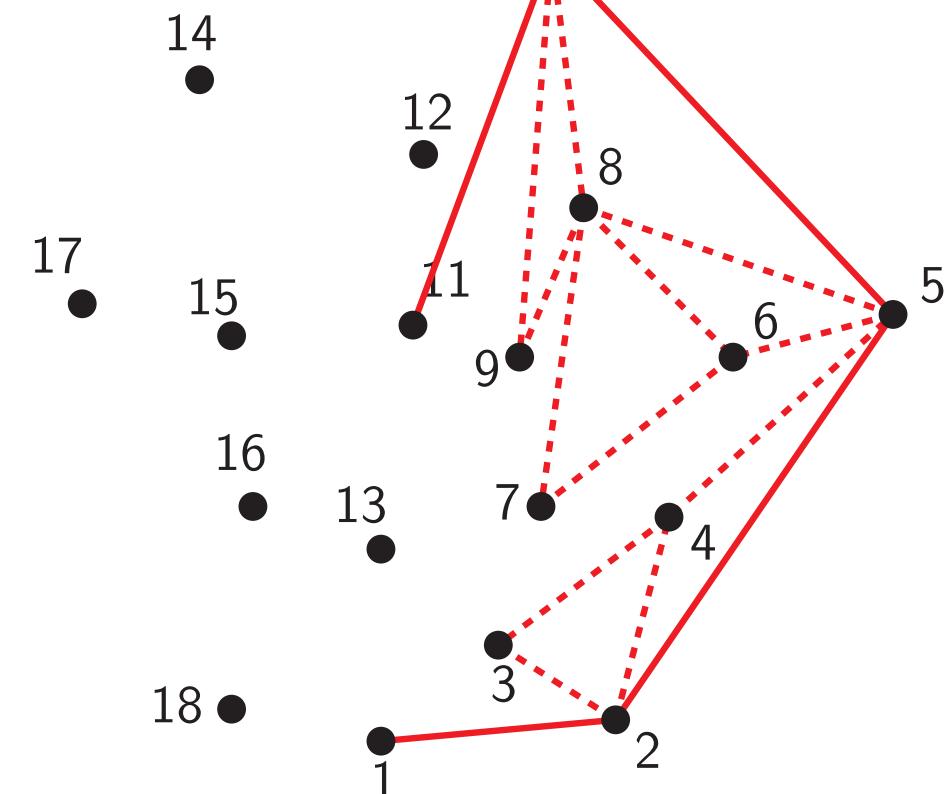
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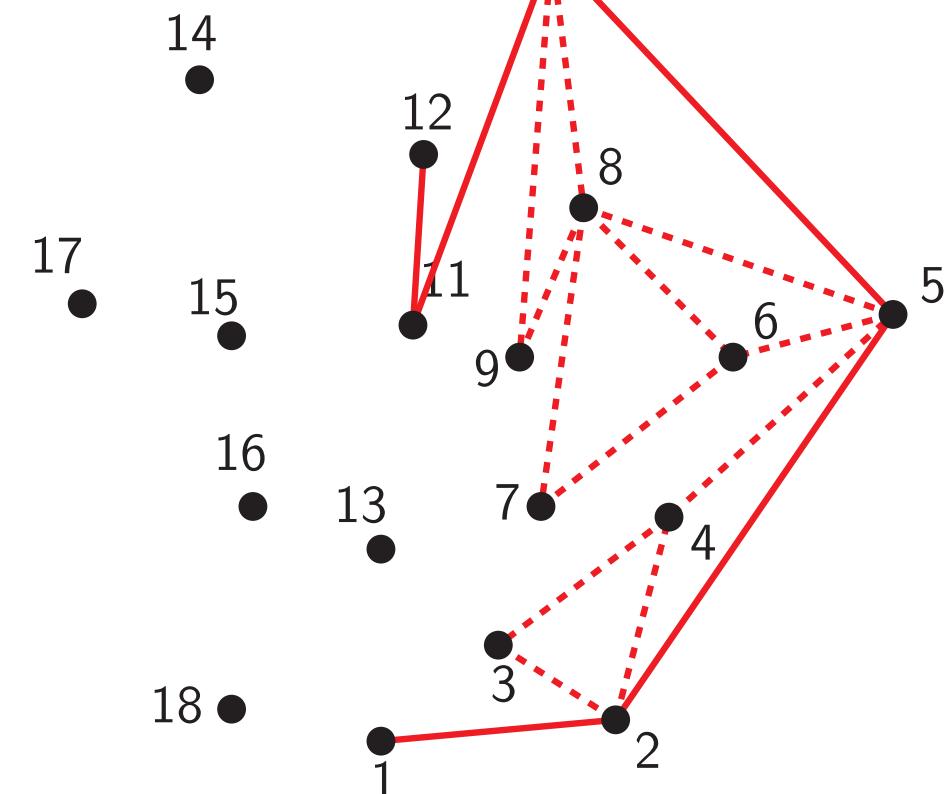
s($\text{top}(l)$)

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e i

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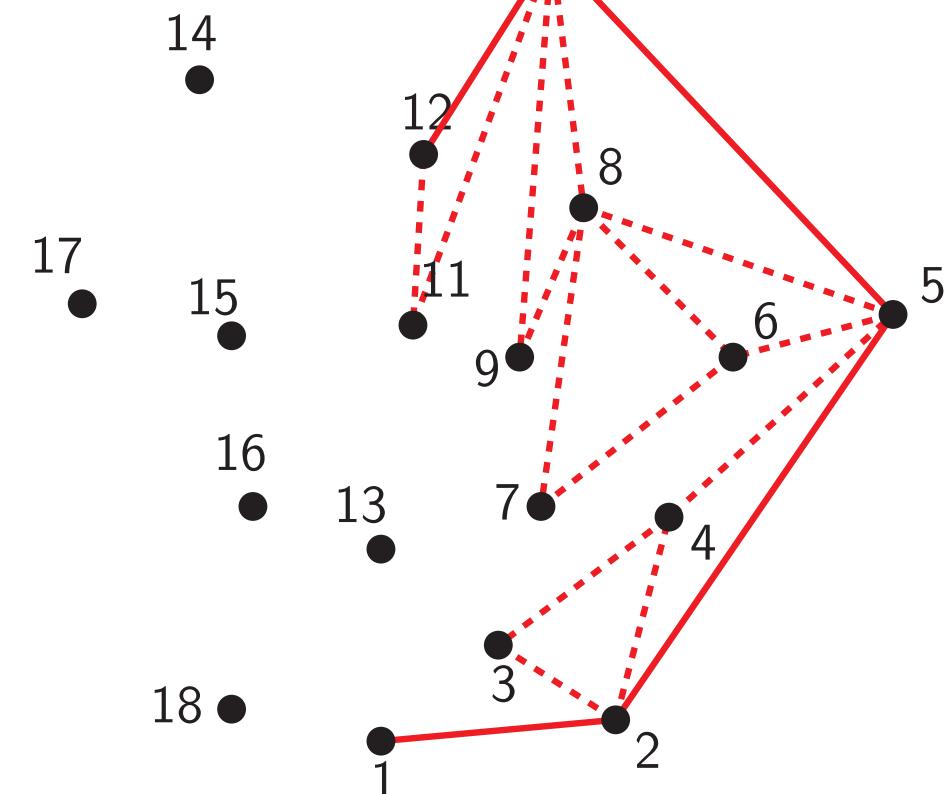
s($\text{top}(l)$)

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e i

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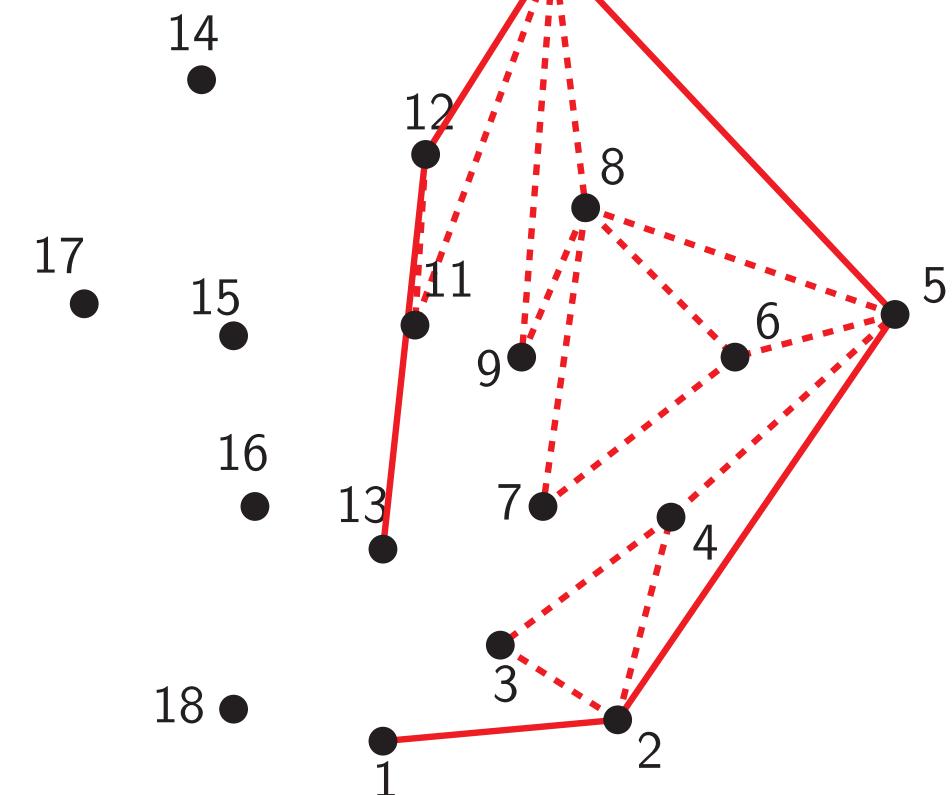
s($\text{top}(l)$)

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e i

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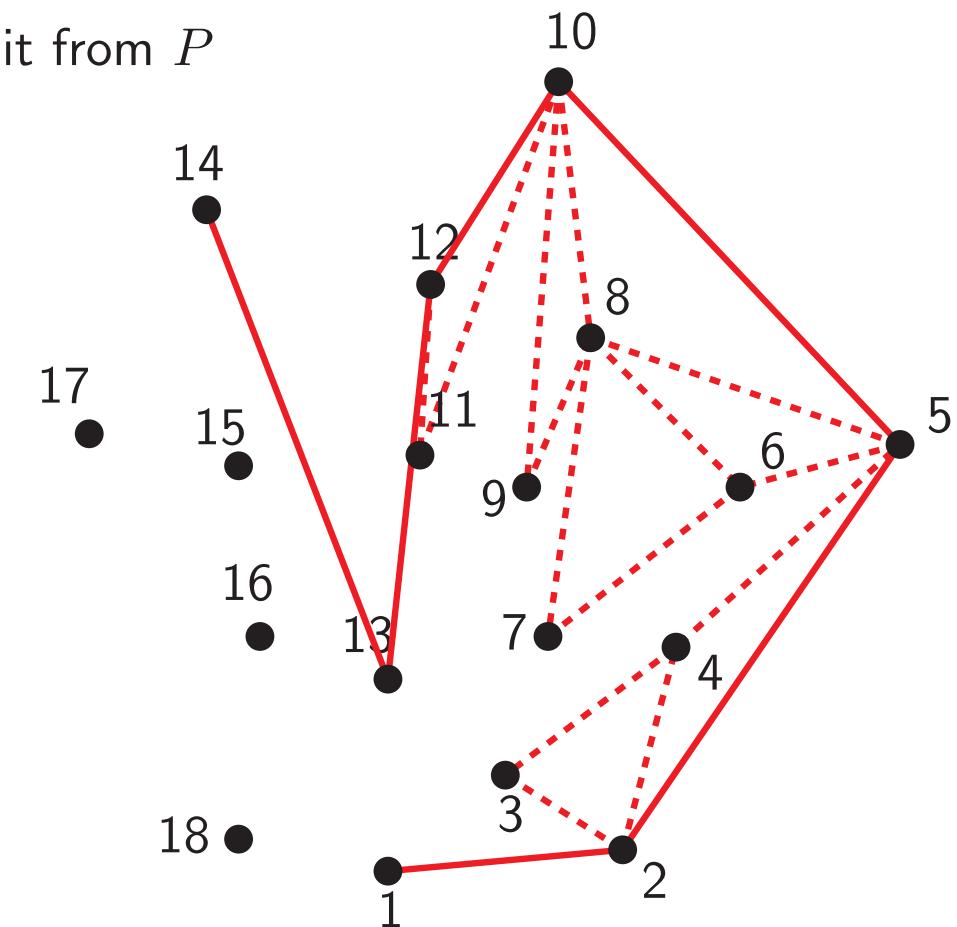
s($\text{top}(l)$)

left turn:

in l

e i

from l



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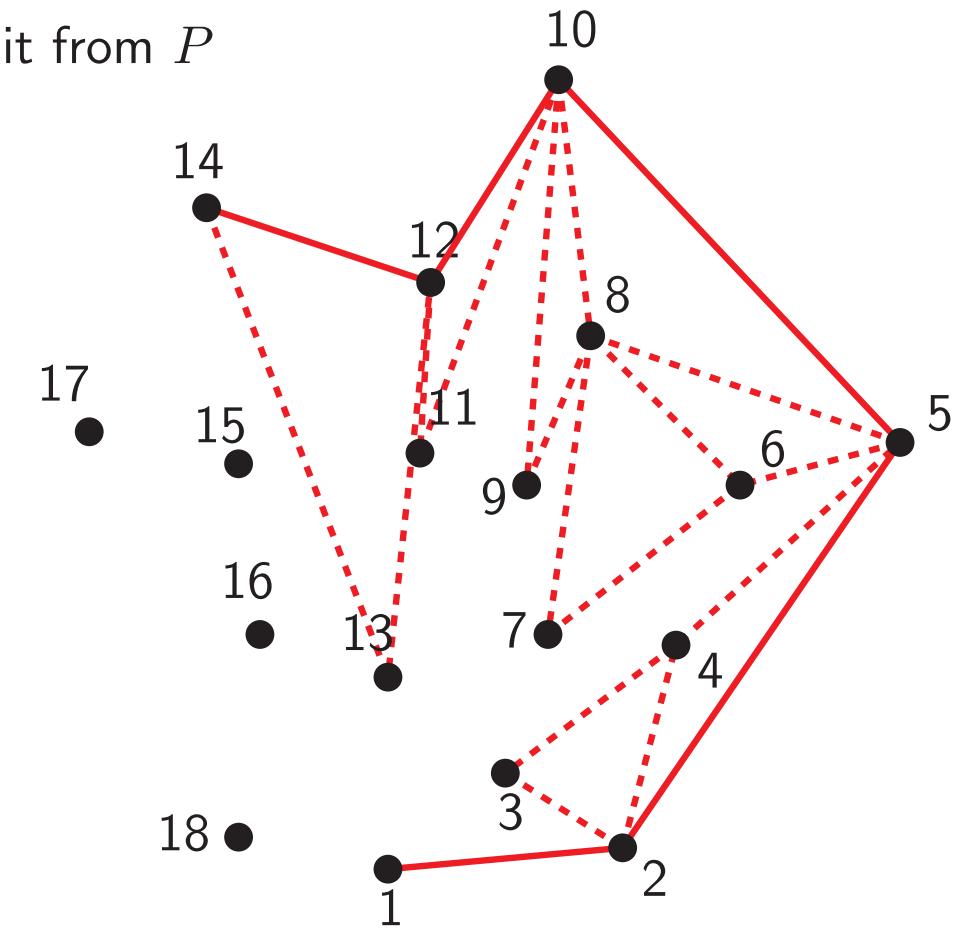
s($\text{top}(l)$)

left turn:

in l

e i

from l



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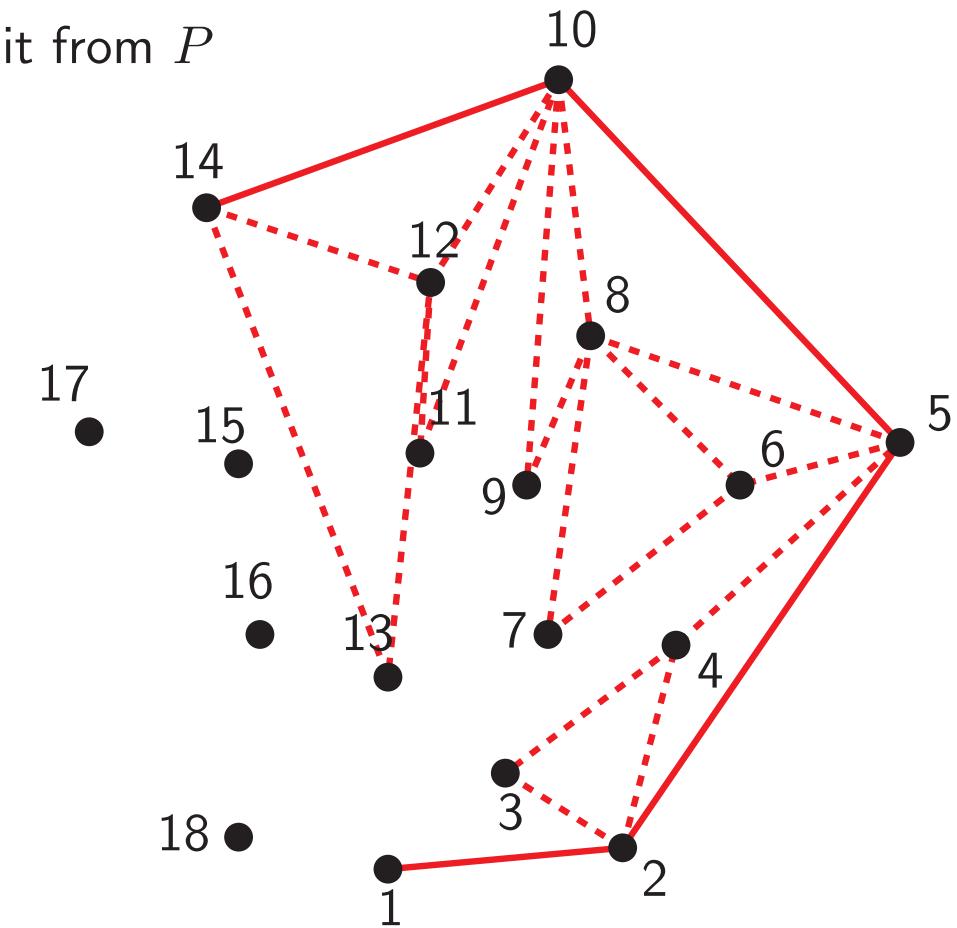
s($\text{top}(l)$)

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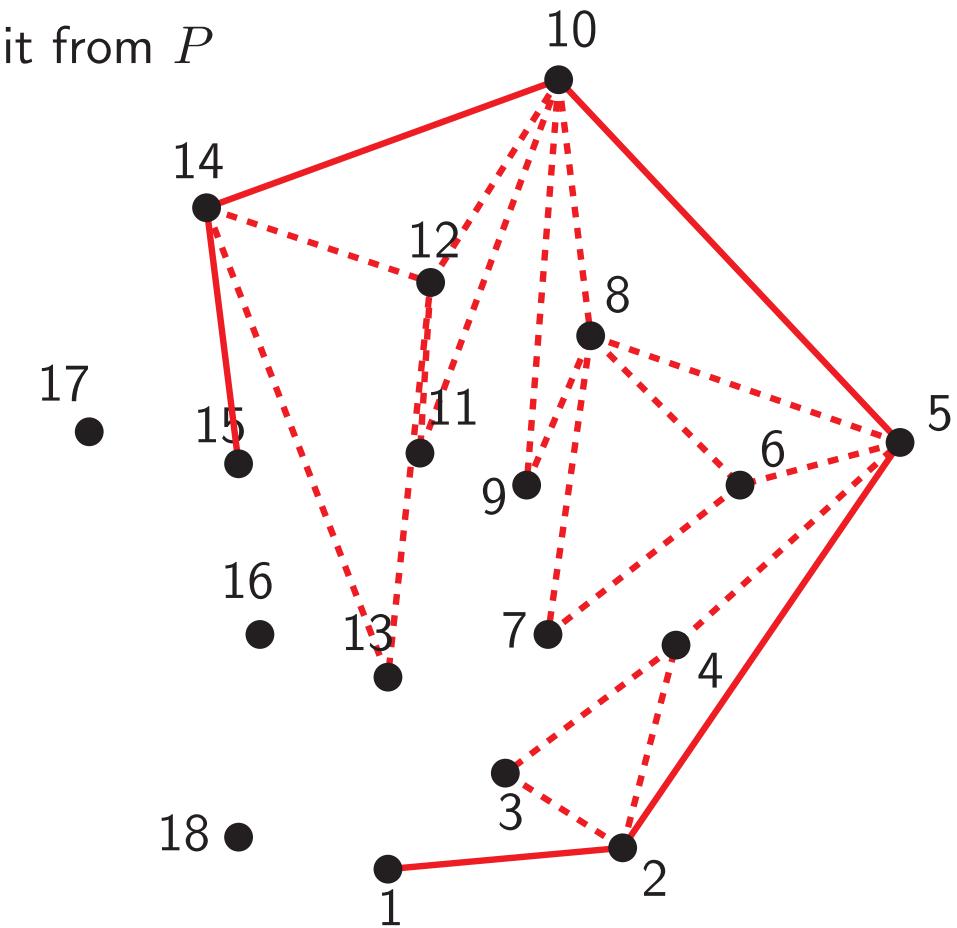
s($\text{top}(l)$)

left turn:

in l

e i

from l



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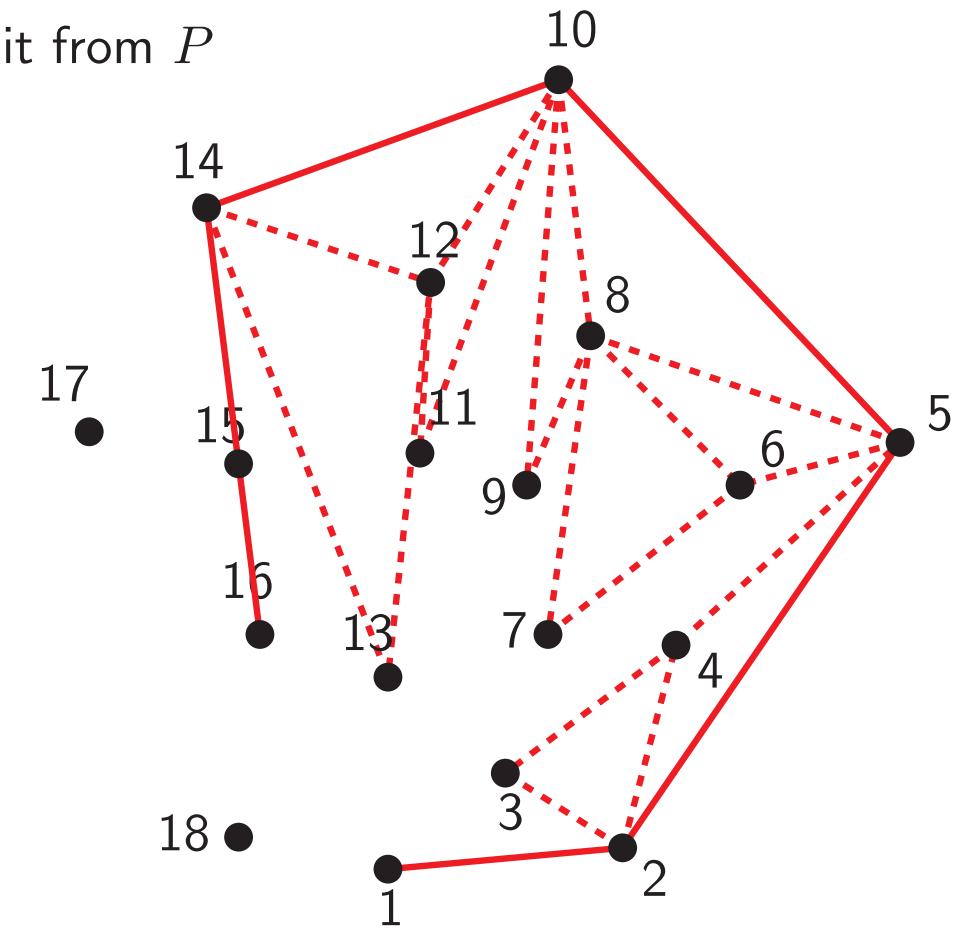
s($\text{top}(l)$)

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e i

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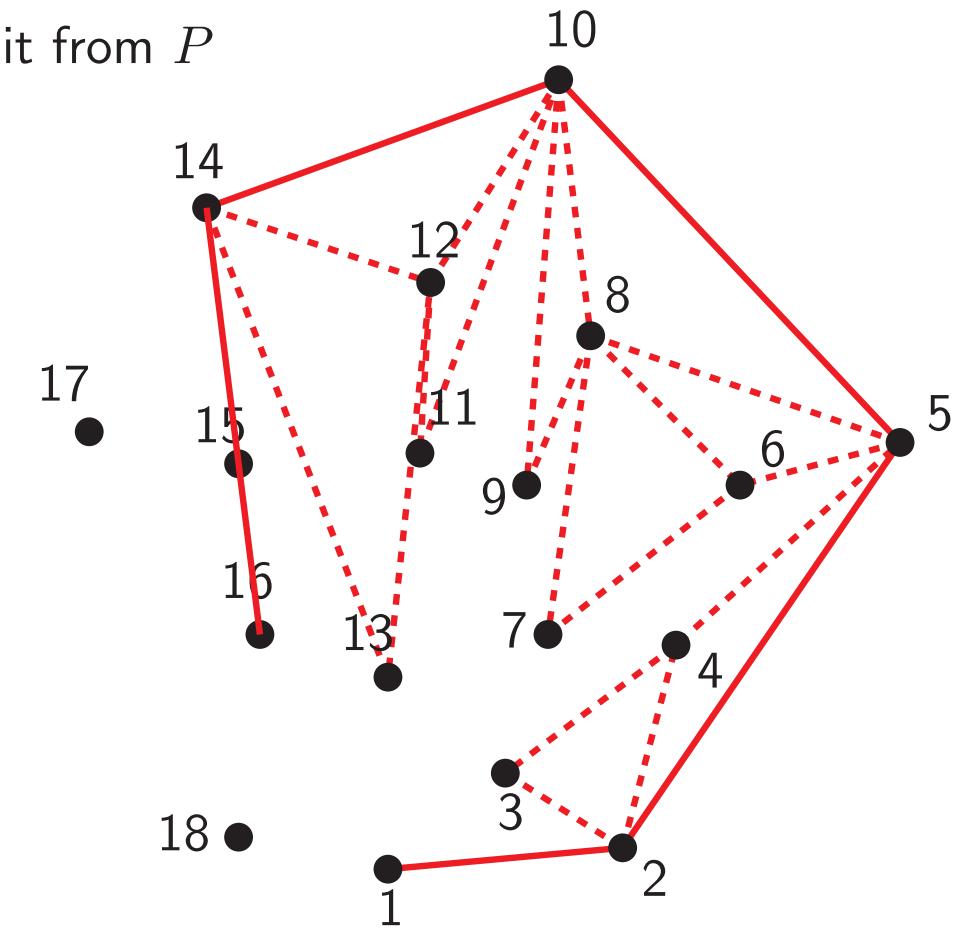
s($\text{top}(l)$)

left turn:

in l

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from l



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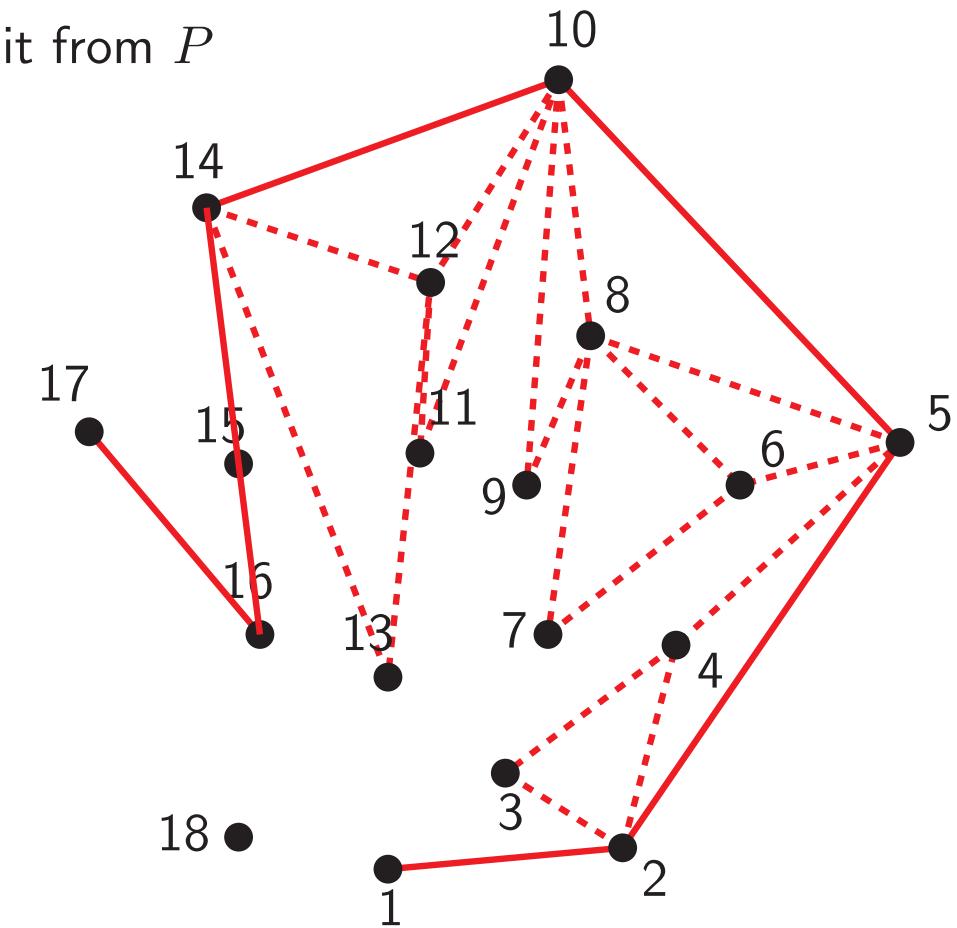
s($\text{top}(l)$)

left turn:

in l

e i

from l



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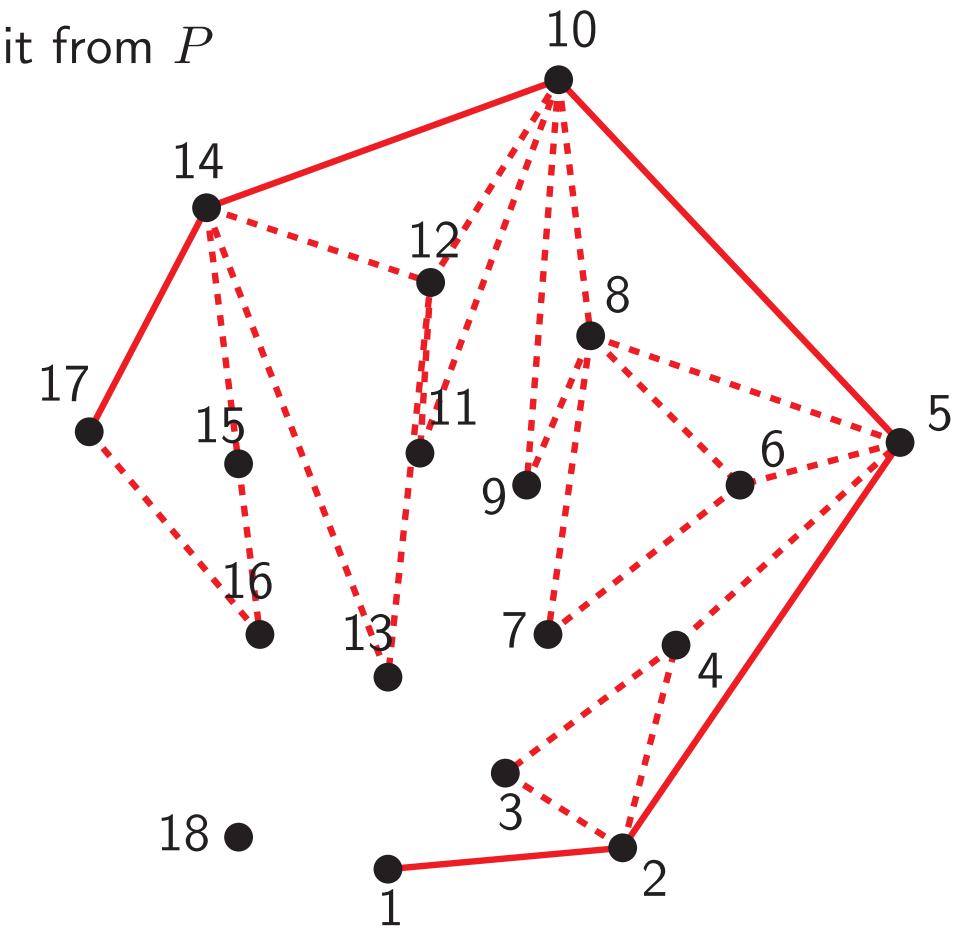
s($\text{top}(l)$)

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e i

from l



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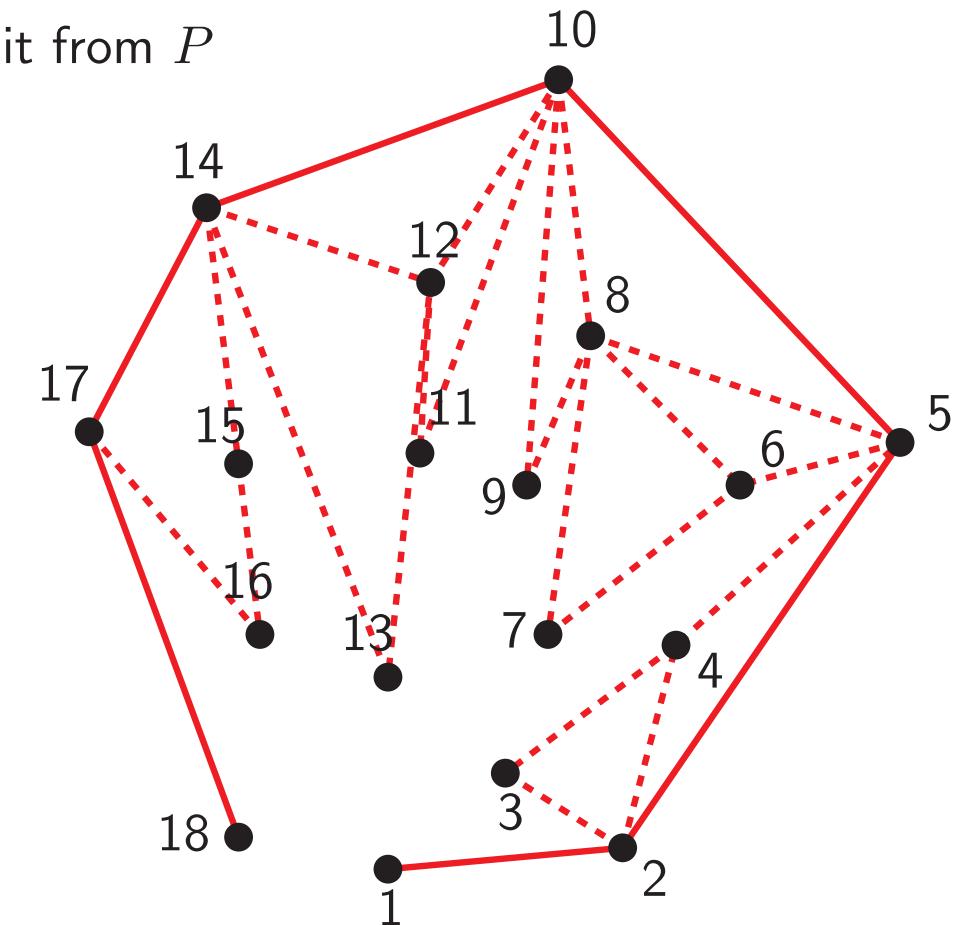
s($\text{top}(l)$)

left turn:

in l

e i

from l



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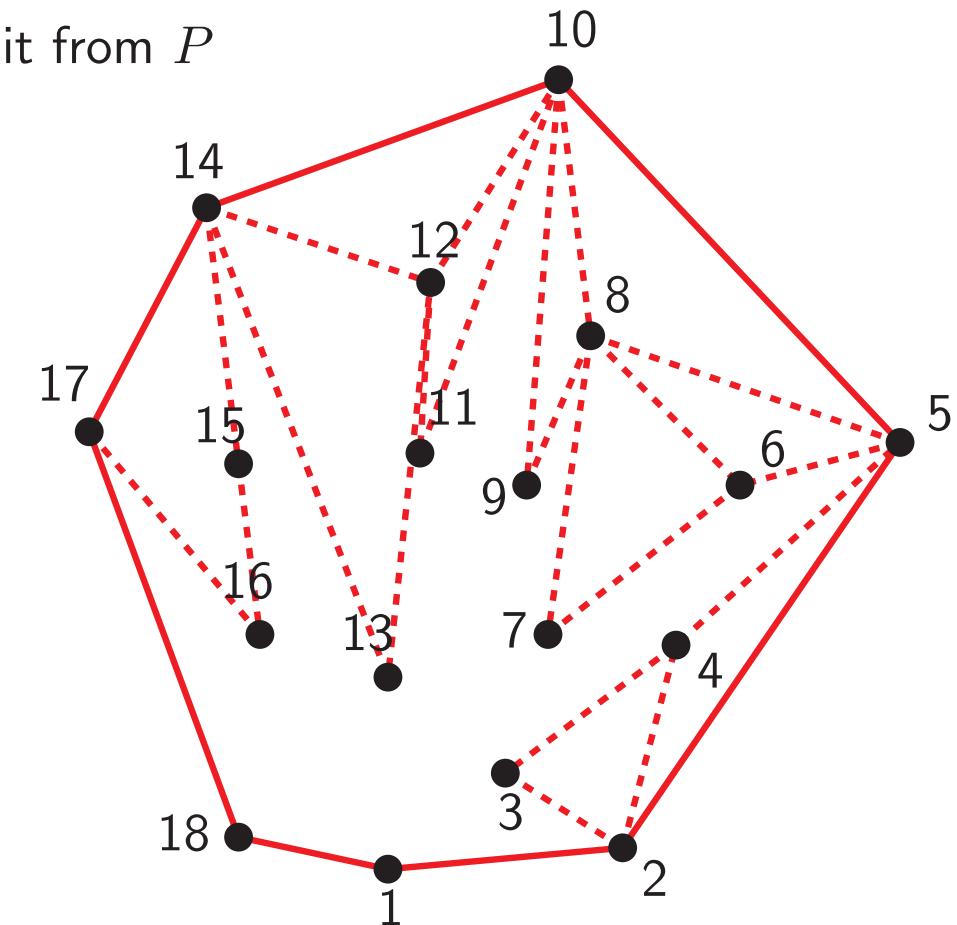
s($\text{top}(l)$)

left turn:

in l

e i

from l



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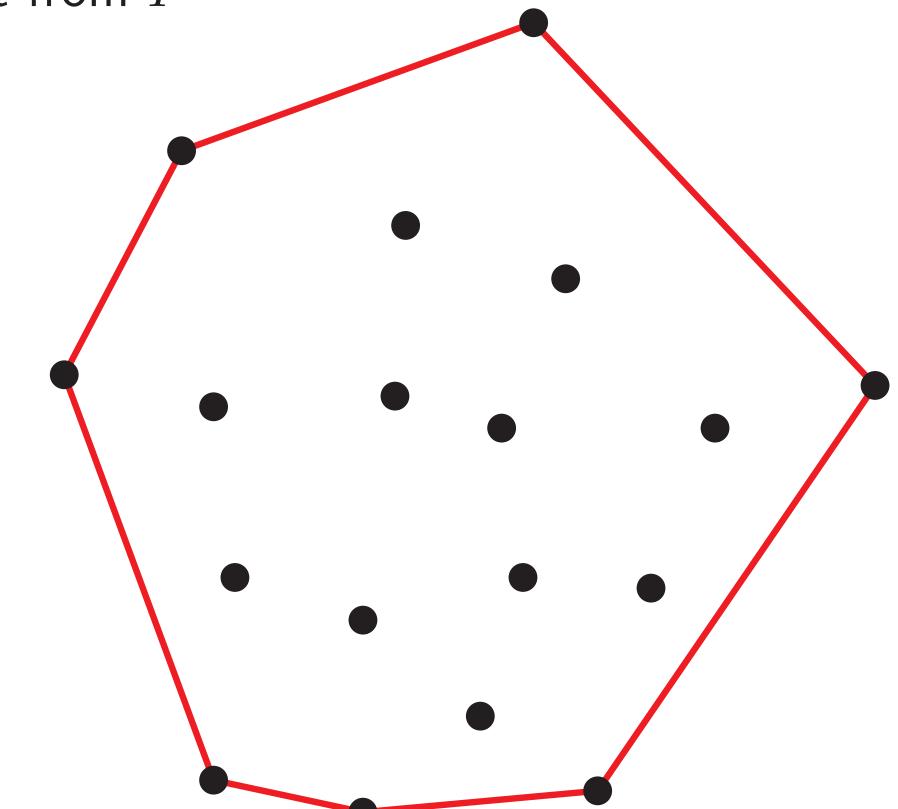
s($\text{top}(l)$)

left turn:

in l

e i

from l



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Cartagena99

CONVEX HULL IN 2D

hm

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at points $p_i \in P$ to be explored, do:

s($\text{top}(l)$)

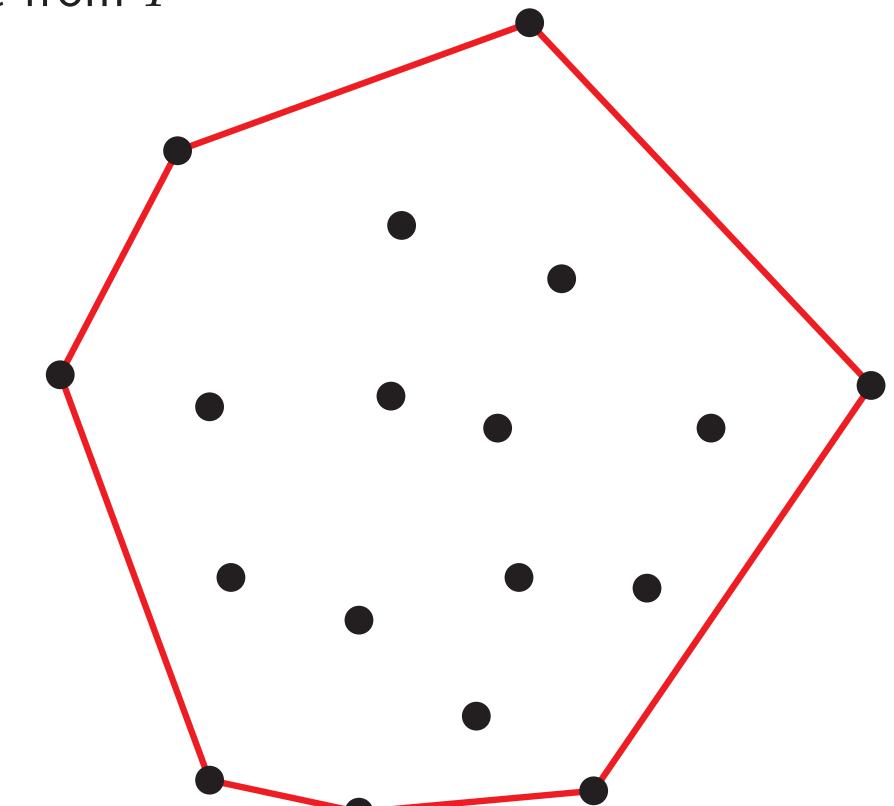
left turn:

in l

e i

from l

($n \log n$)



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CONVEX HULL IN 2D

rithm

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, do:

the exterior of the polygon defined by l :

the points p_l and p_r

the supporting lines

to the polygon

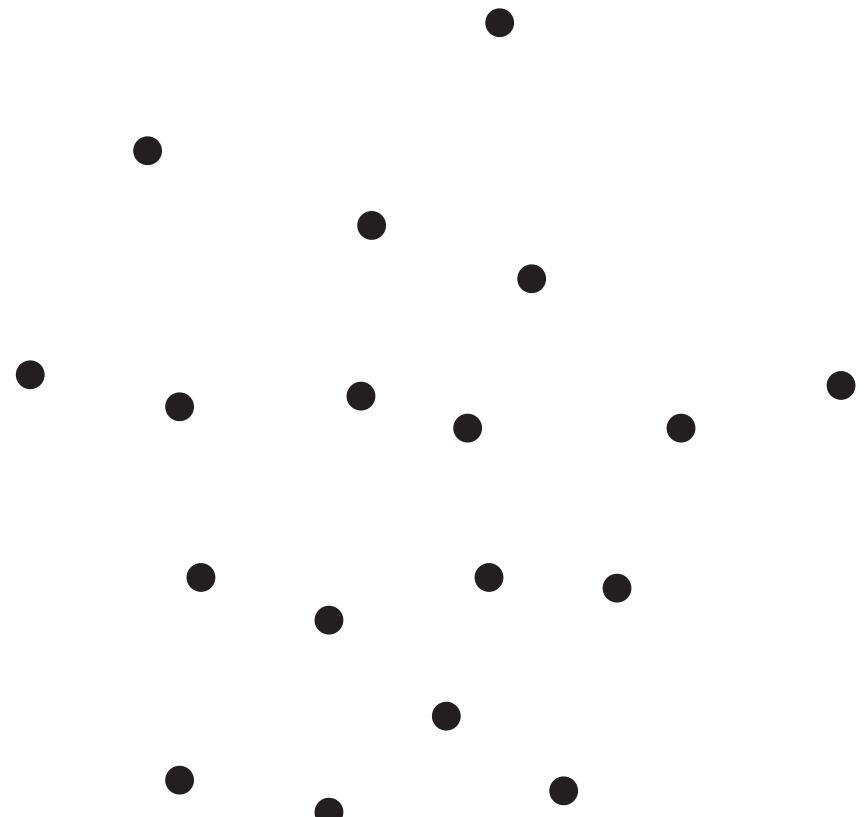
the chain p_l, \dots, p_r in l

the chain p_l, p_i, p_r

...

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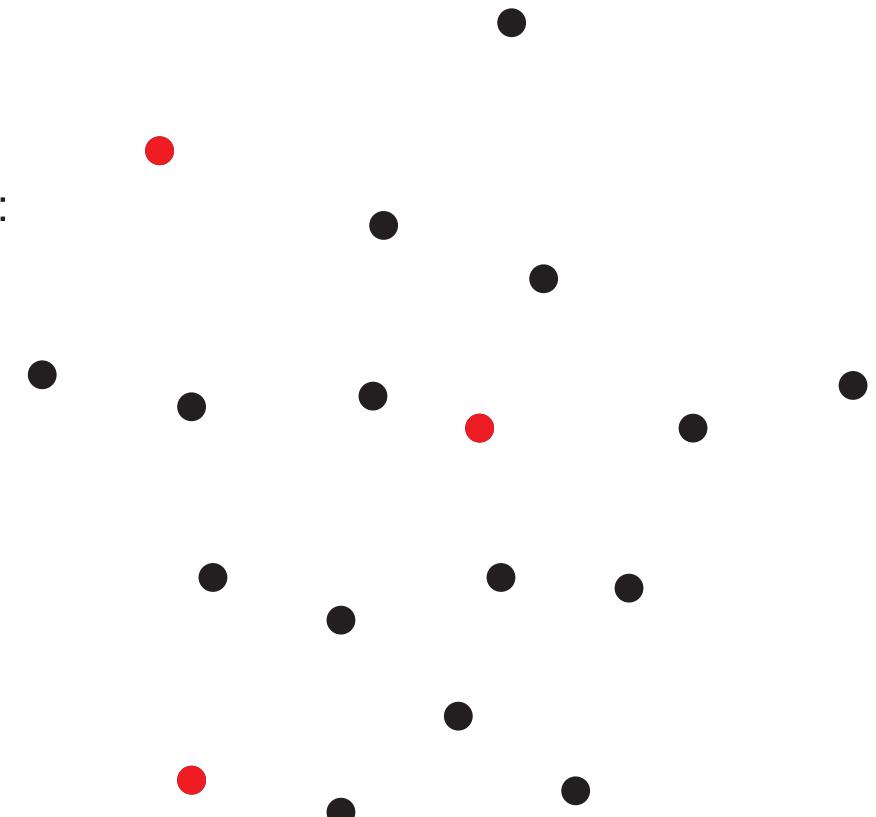
the chain p_l, \dots, p_r in l

the chain p_l, p_i, p_r

...

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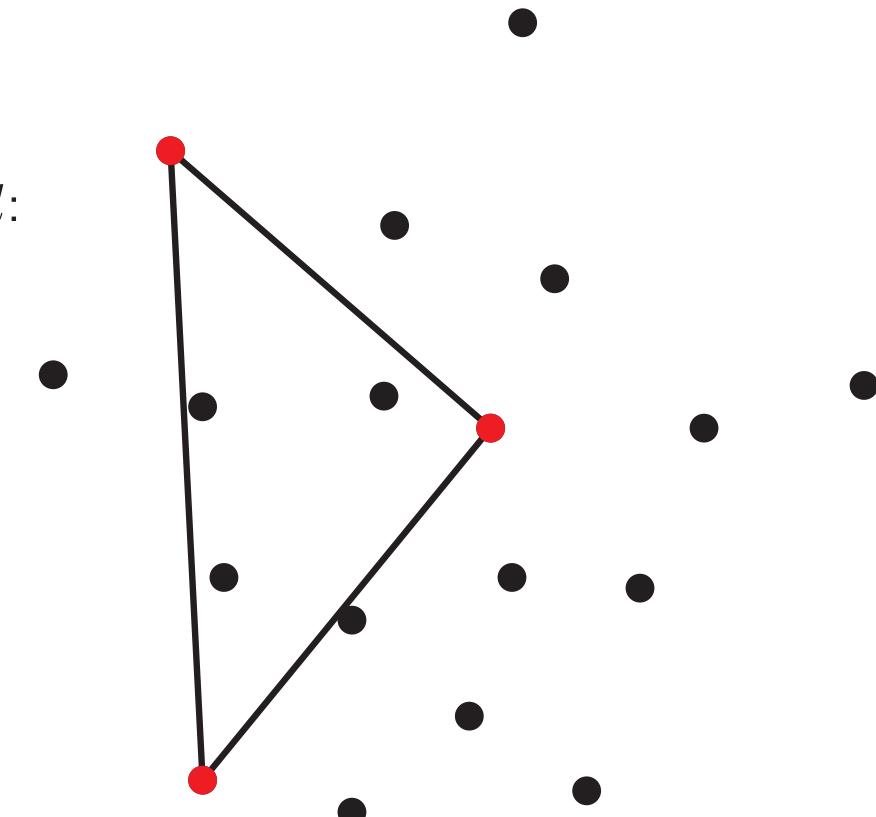


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, do:
the exterior of the polygon defined by l :
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to the polygon
the chain p_l, \dots, p_r in l
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...



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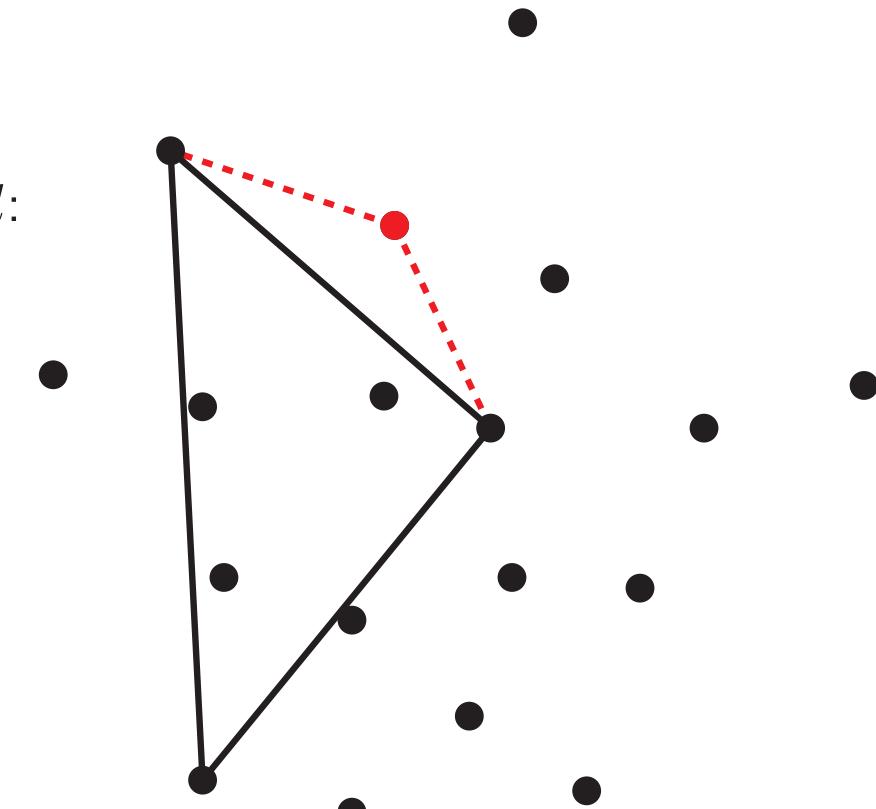
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rithm

Cartagena99

- do:
 - the exterior of the polygon defined by l :
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 - p_i to the polygon
 - the chain p_l, \dots, p_r in l
 - the chain p_l, p_i, p_r



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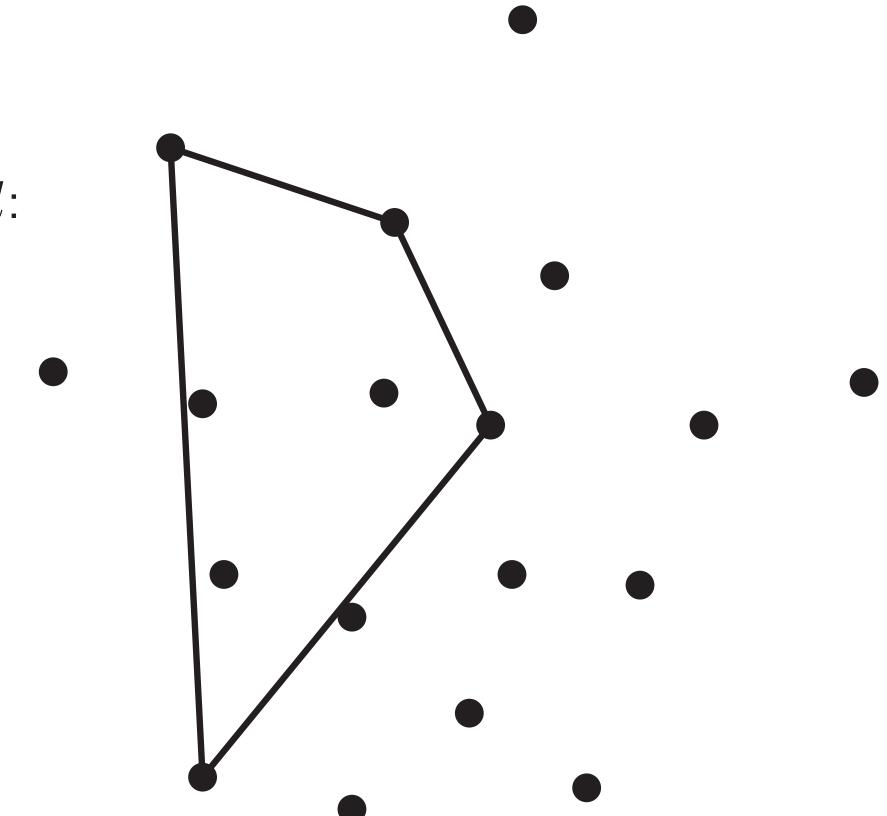
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CONVEX HULL IN 2D

rithm

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 - to the polygon
 - the chain p_l, \dots, p_r in l
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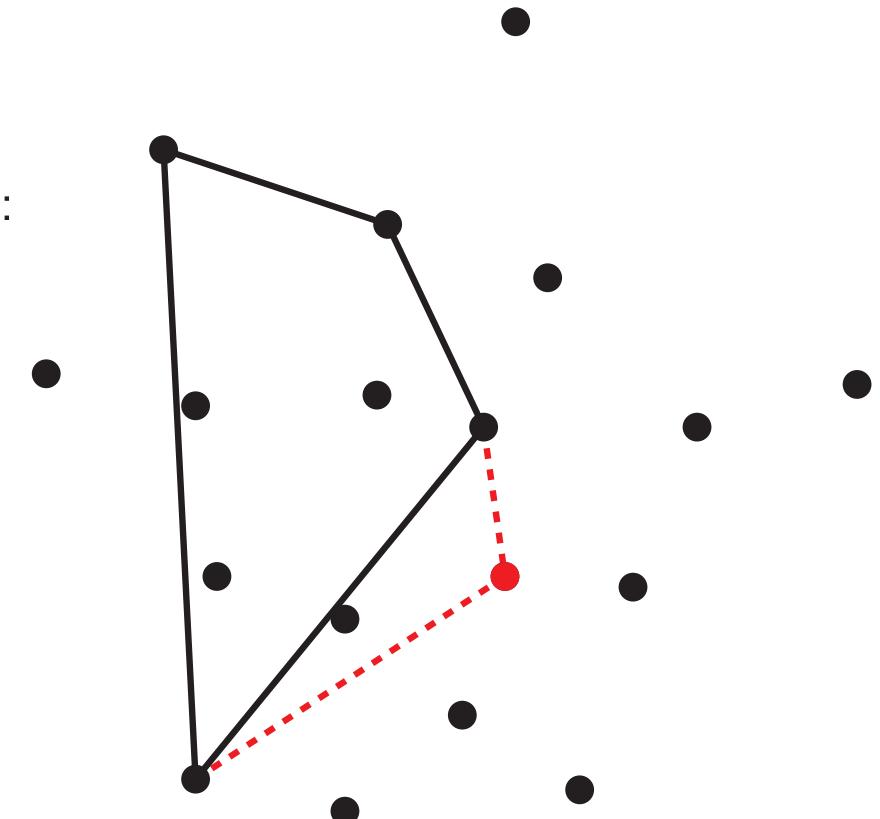
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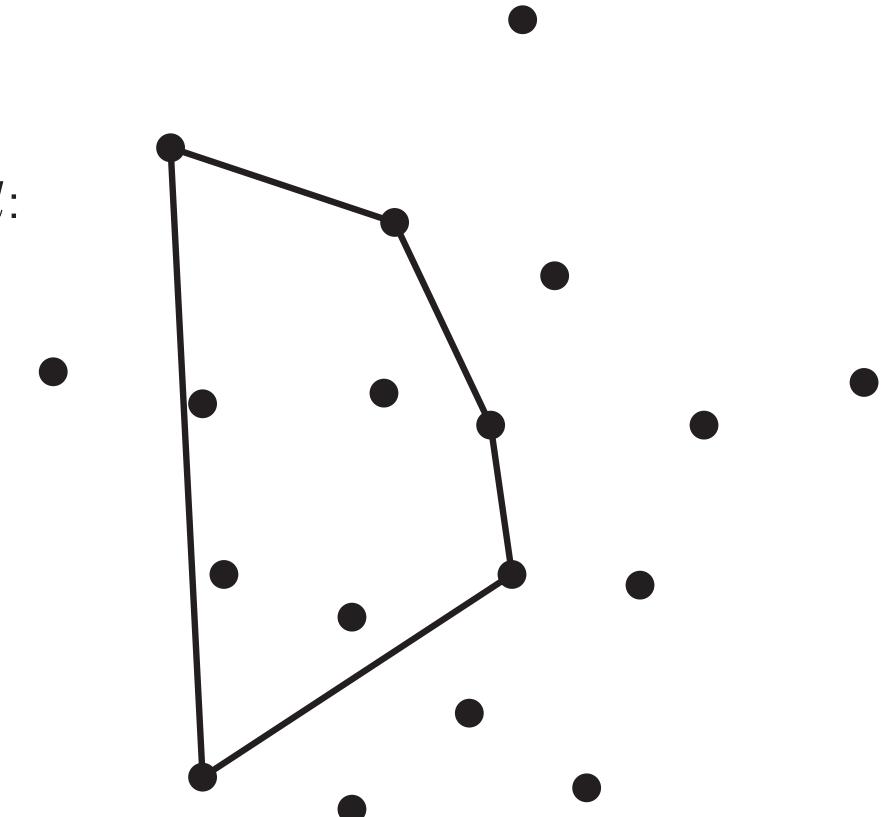


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rithm

- do:
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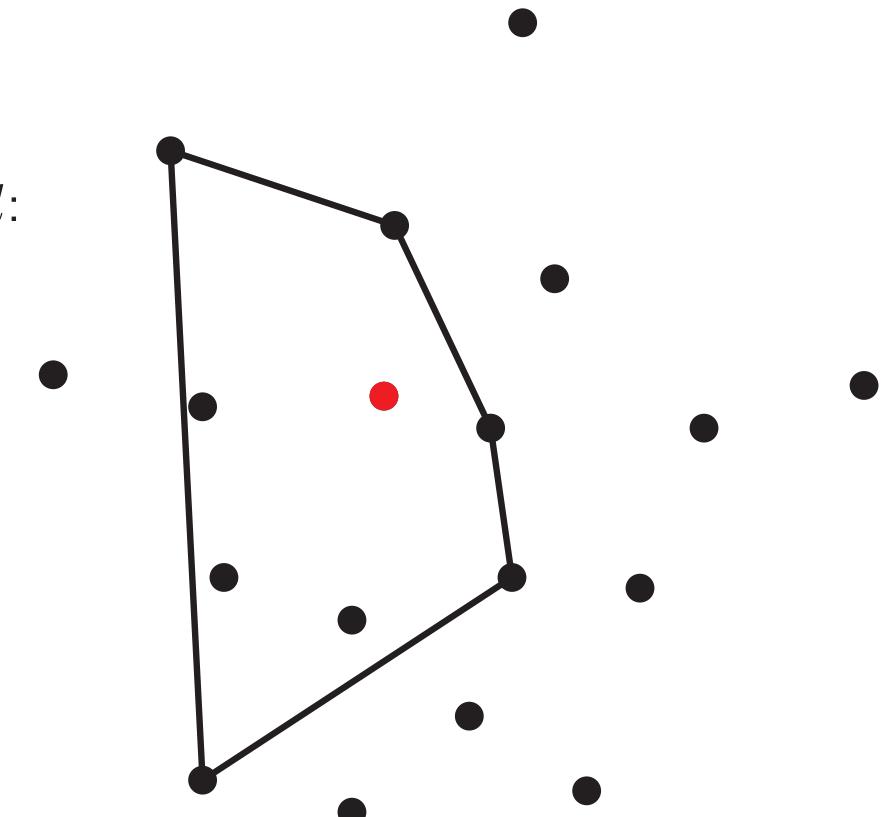
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CONVEX HULL IN 2D

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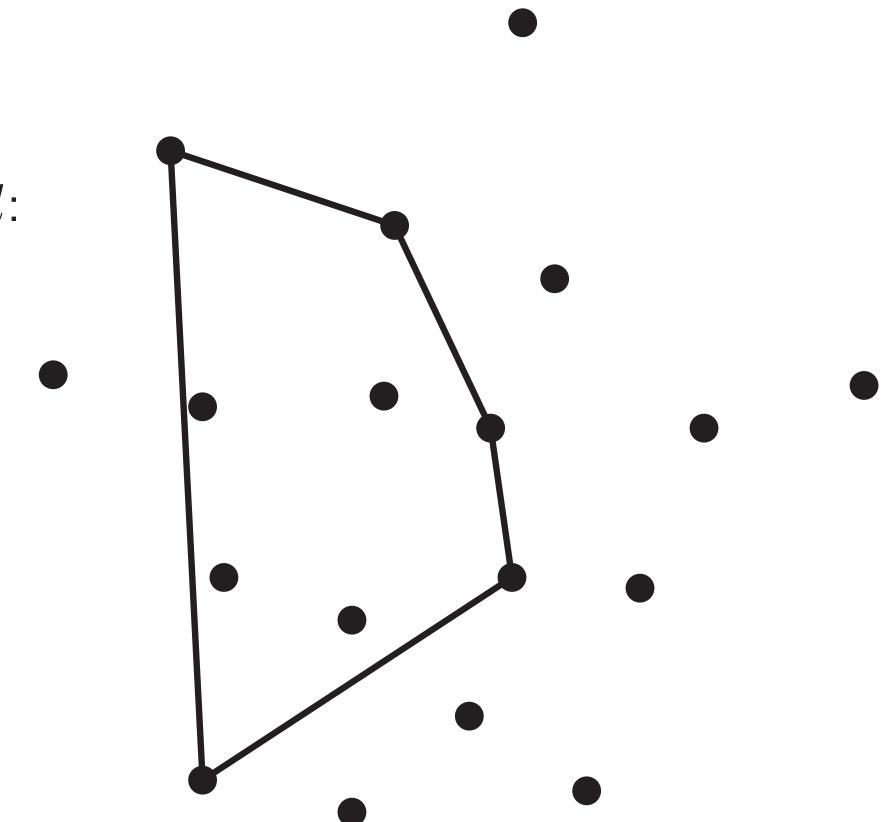
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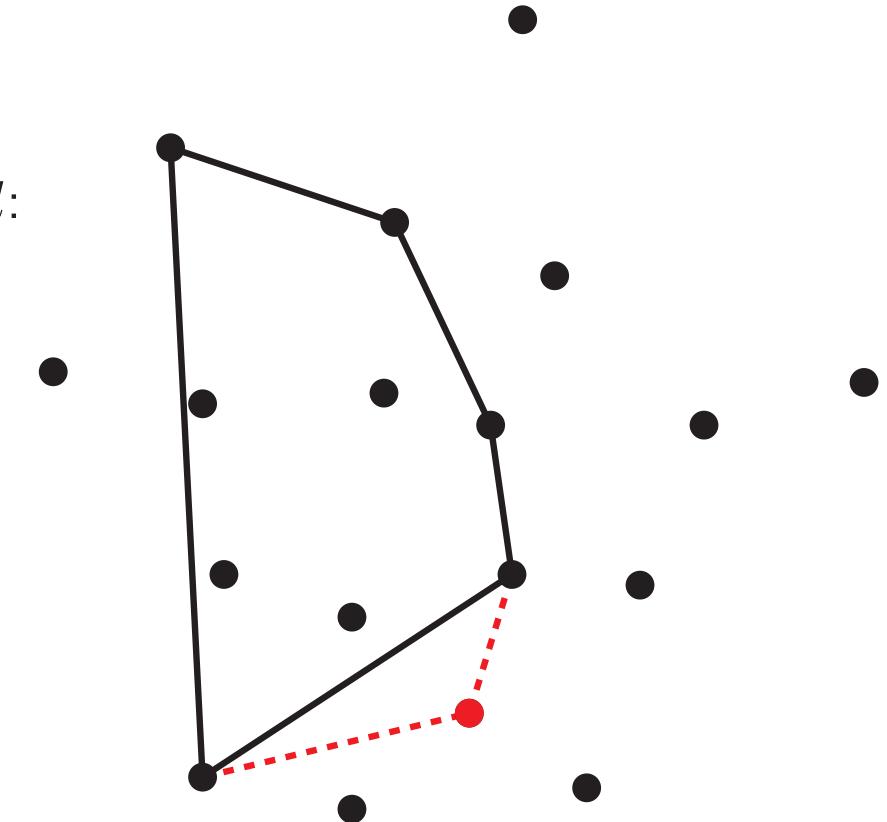
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CONVEX HULL IN 2D

rithm

Cartagena99

- do:
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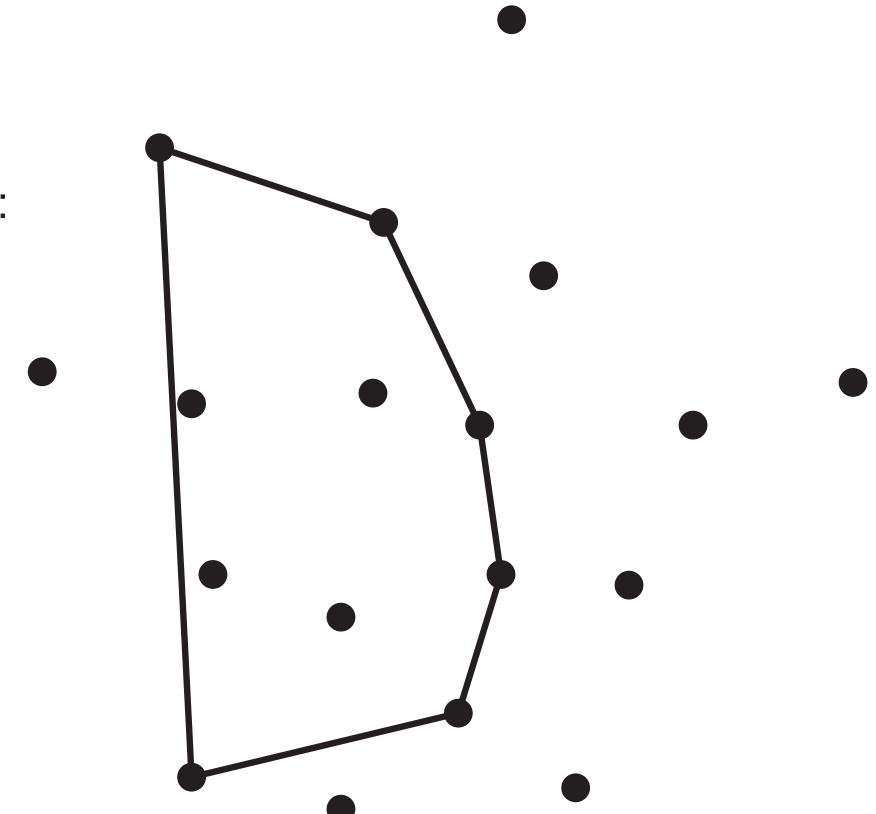
Cartagena99

- , do:
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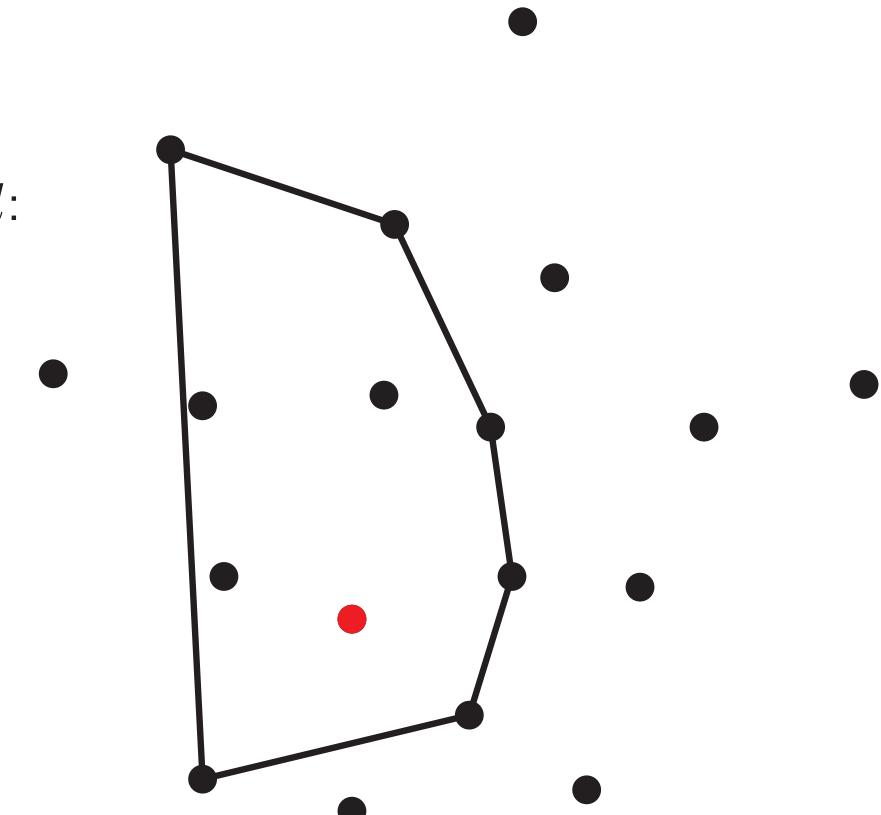


CONVEX HULL IN 2D

rithm



, do:
the exterior of the polygon defined by l :
the points p_l and p_r
the supporting lines
to the polygon
the chain p_l, \dots, p_r in l
the chain p_l, p_i, p_r
...



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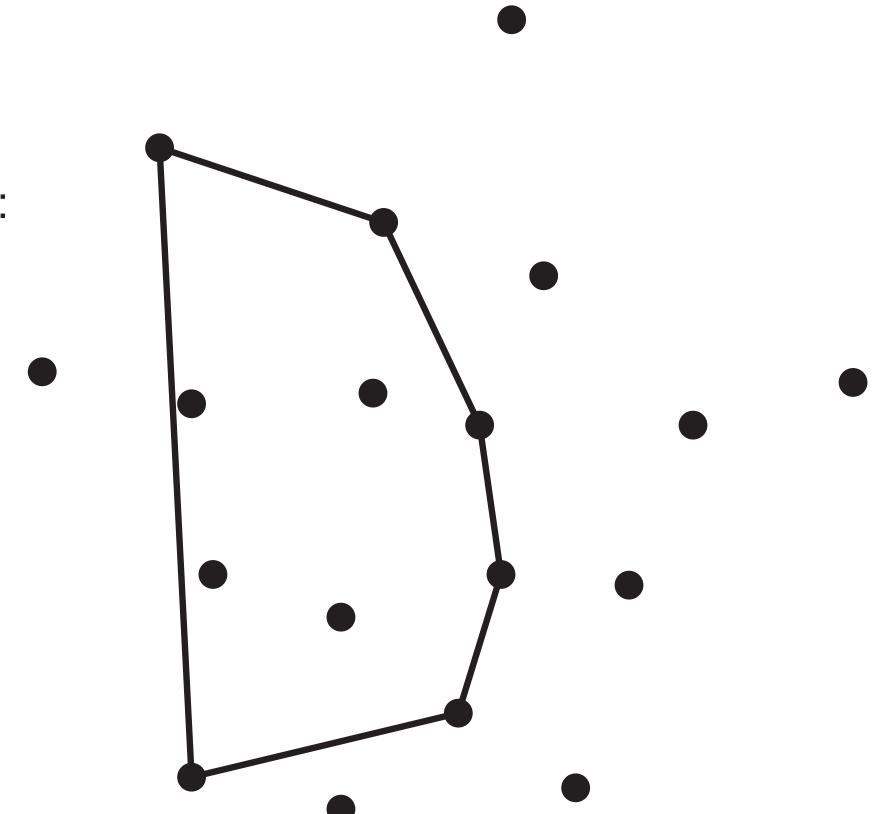
Cartagena99

- , do:
 - e exterior of the polygon defined by l :
 - te the points p_l and p_r
 - g the supporting lines
 - p_i to the polygon
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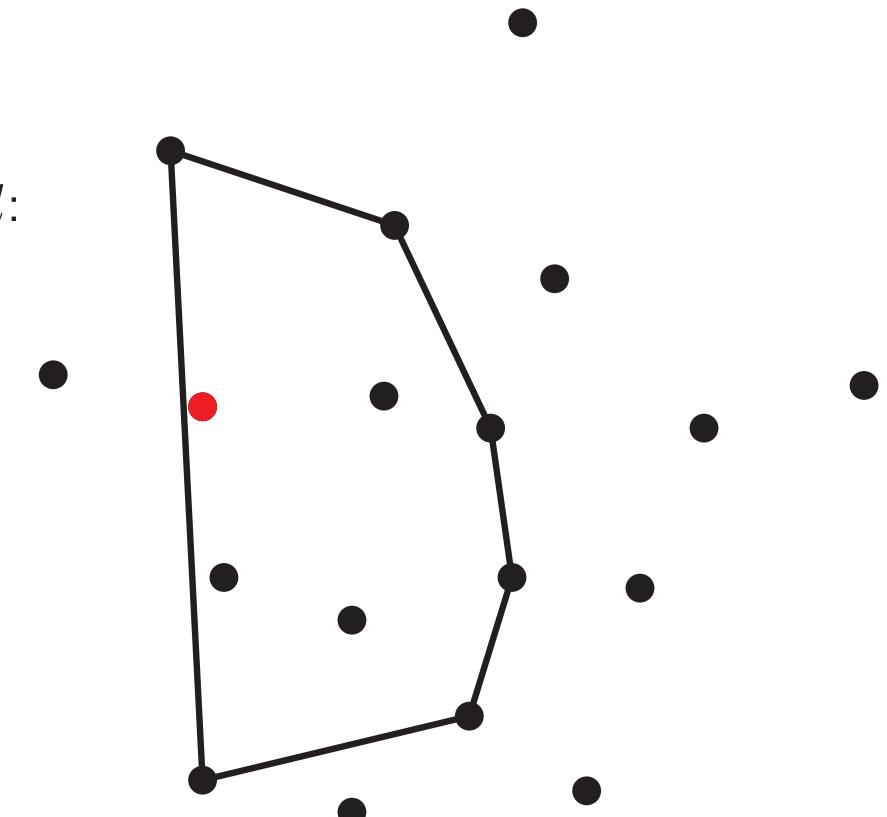
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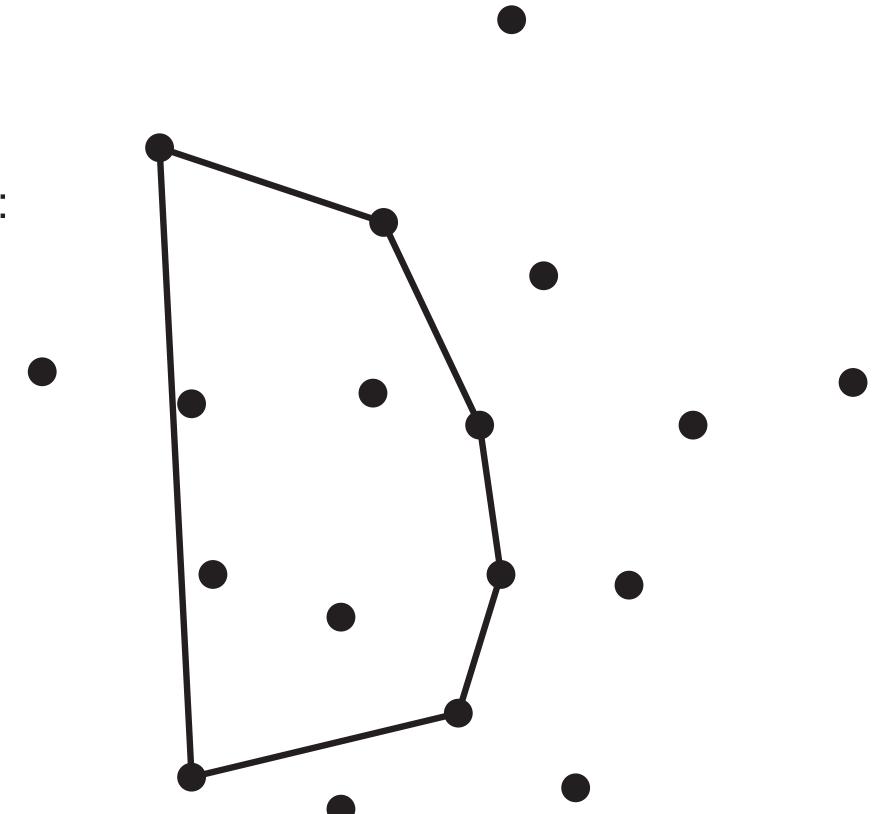
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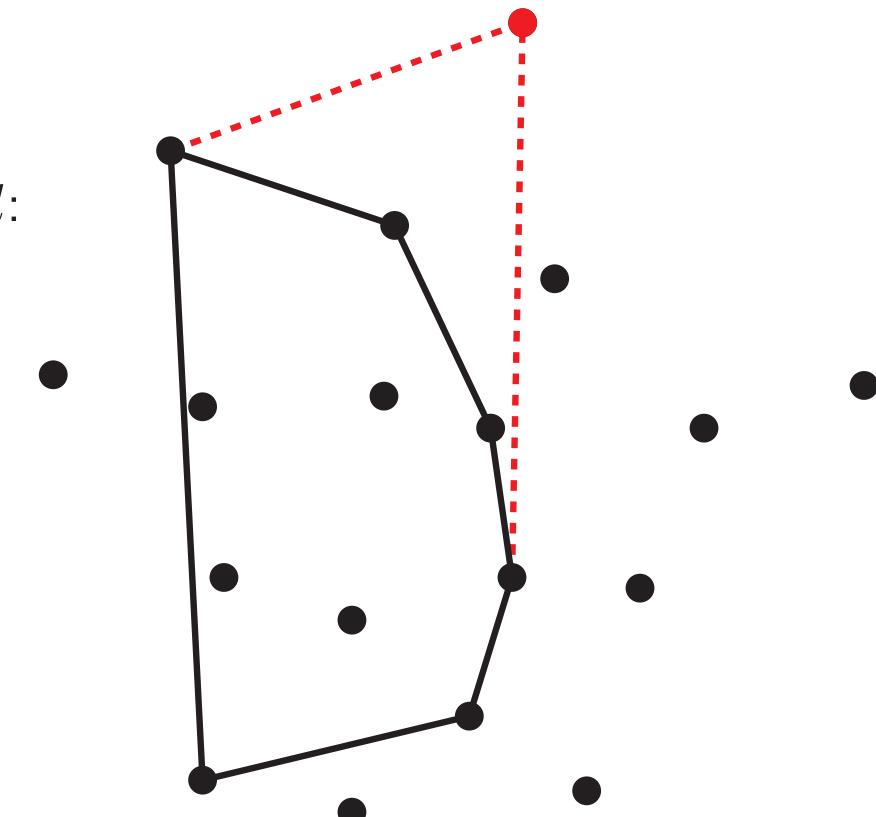
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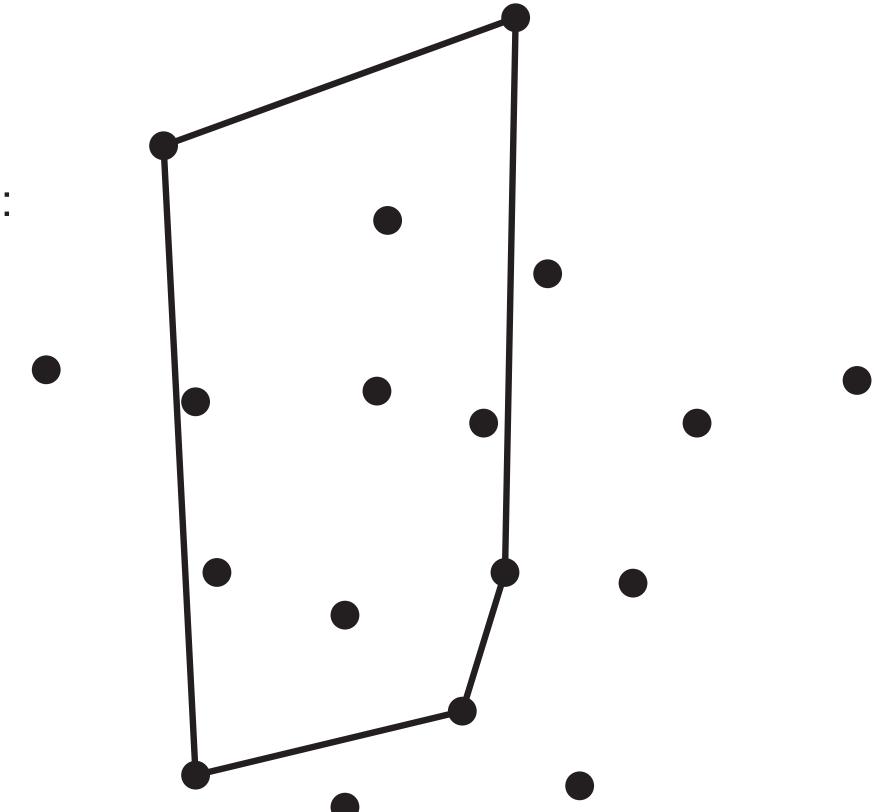
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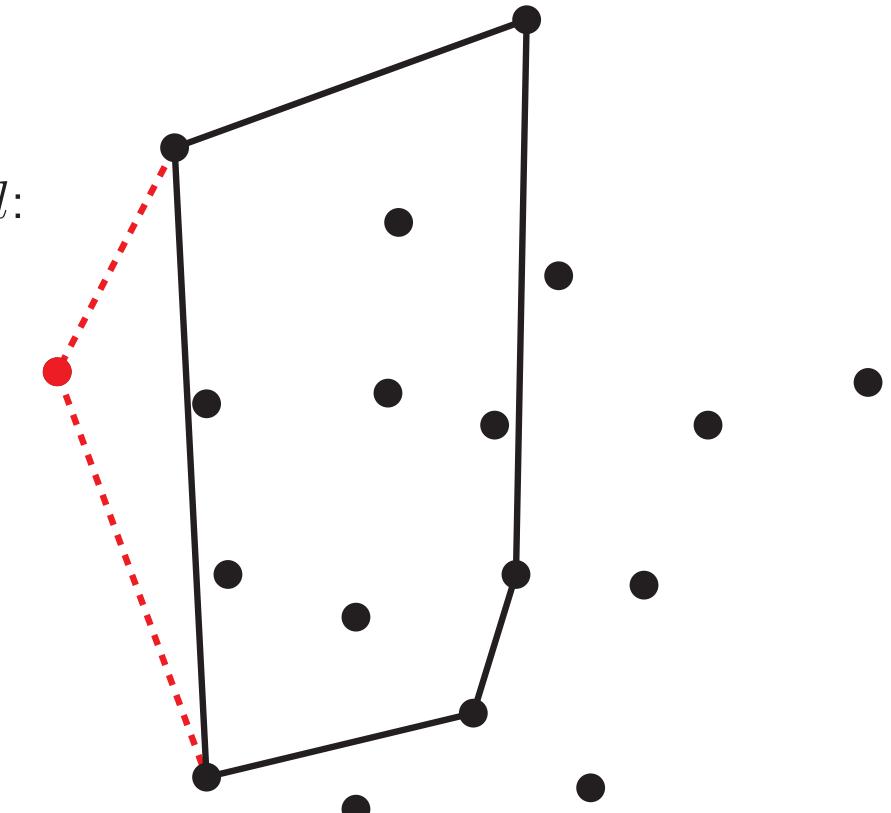
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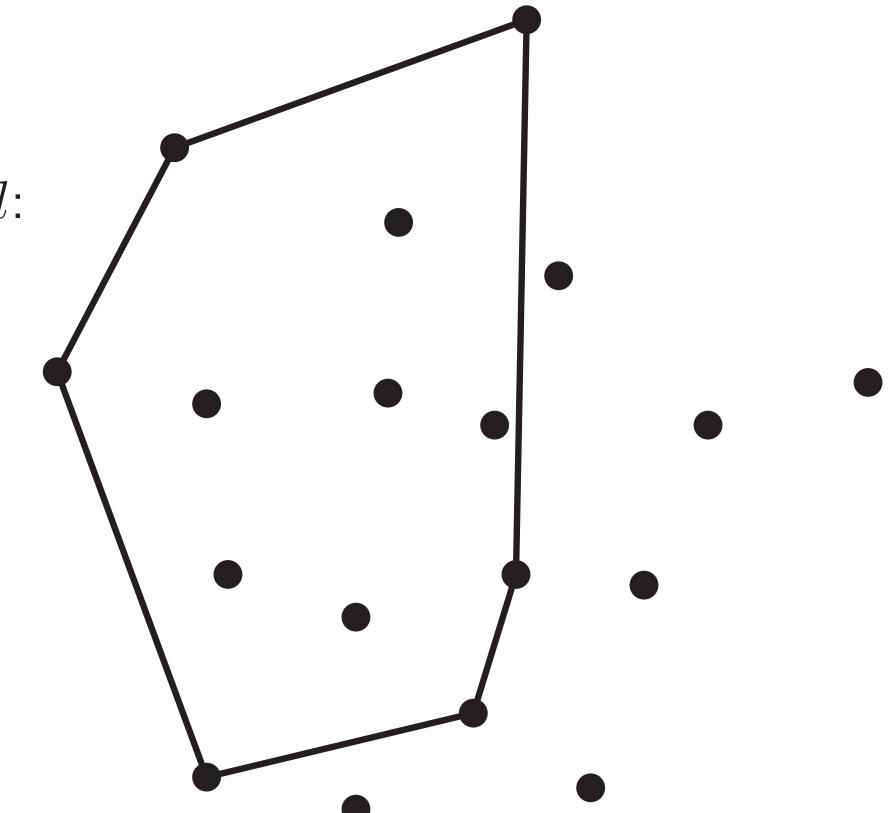
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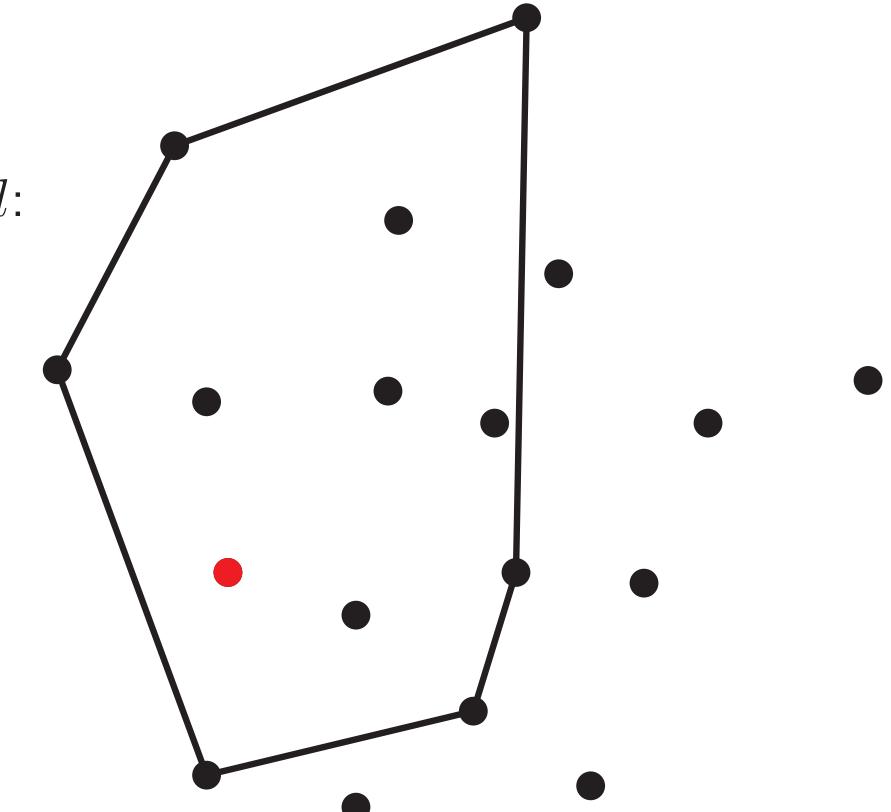
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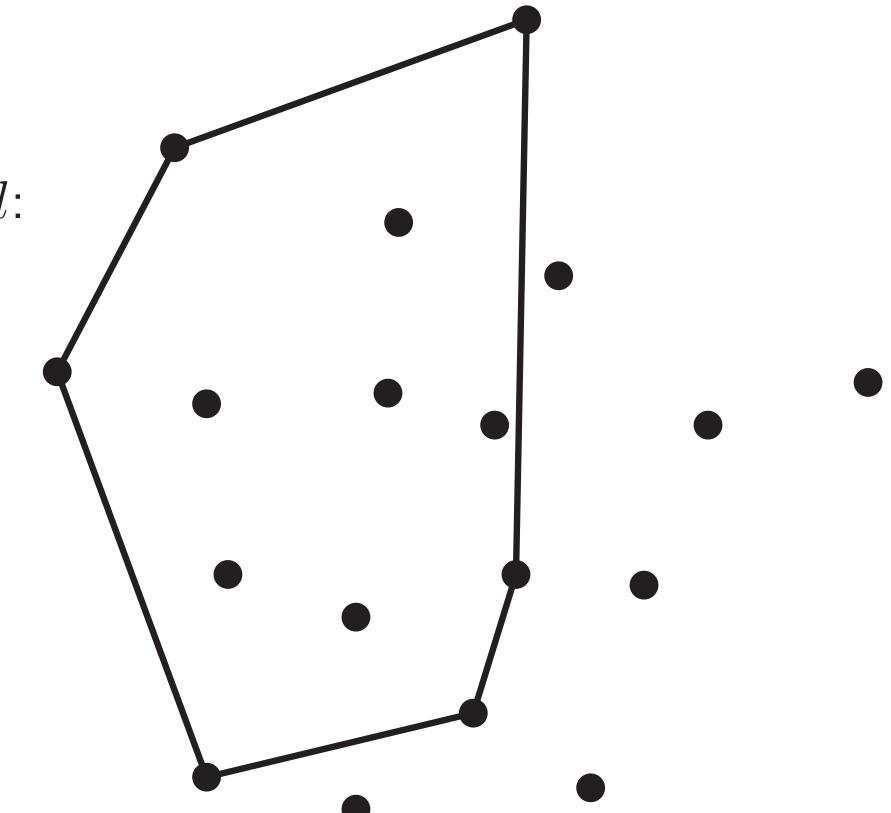
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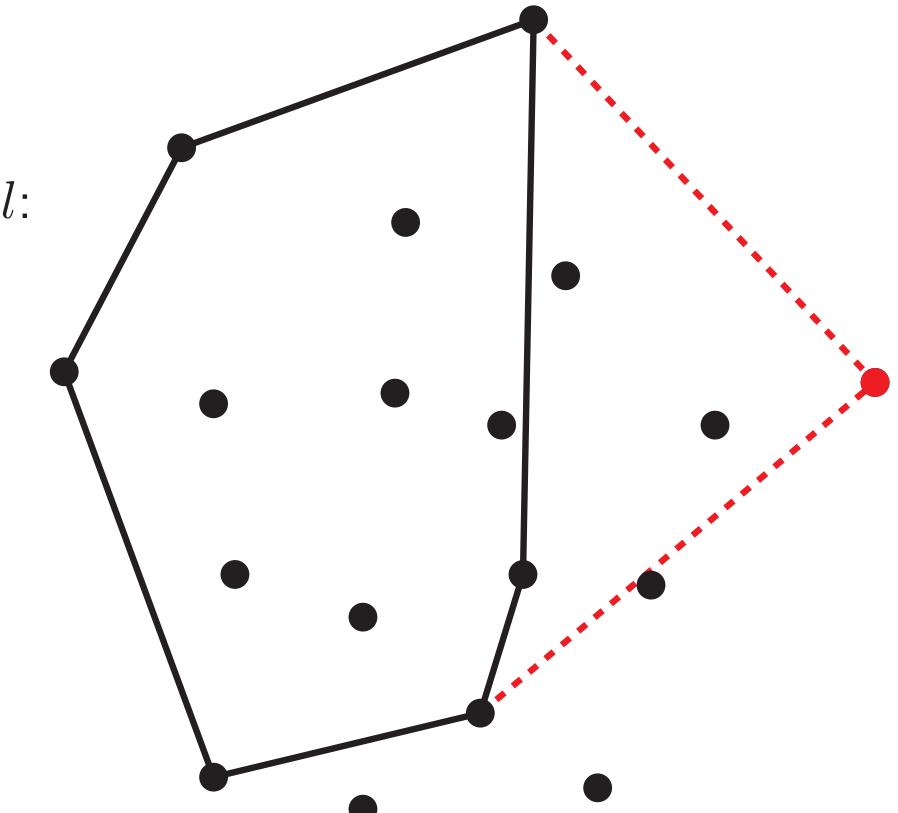
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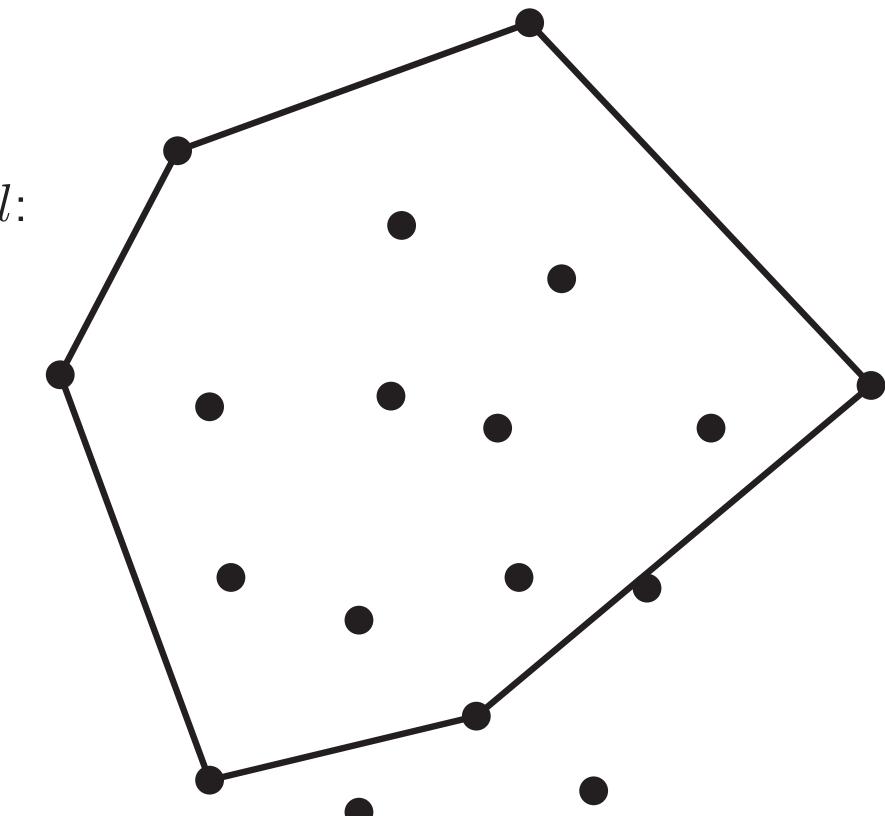
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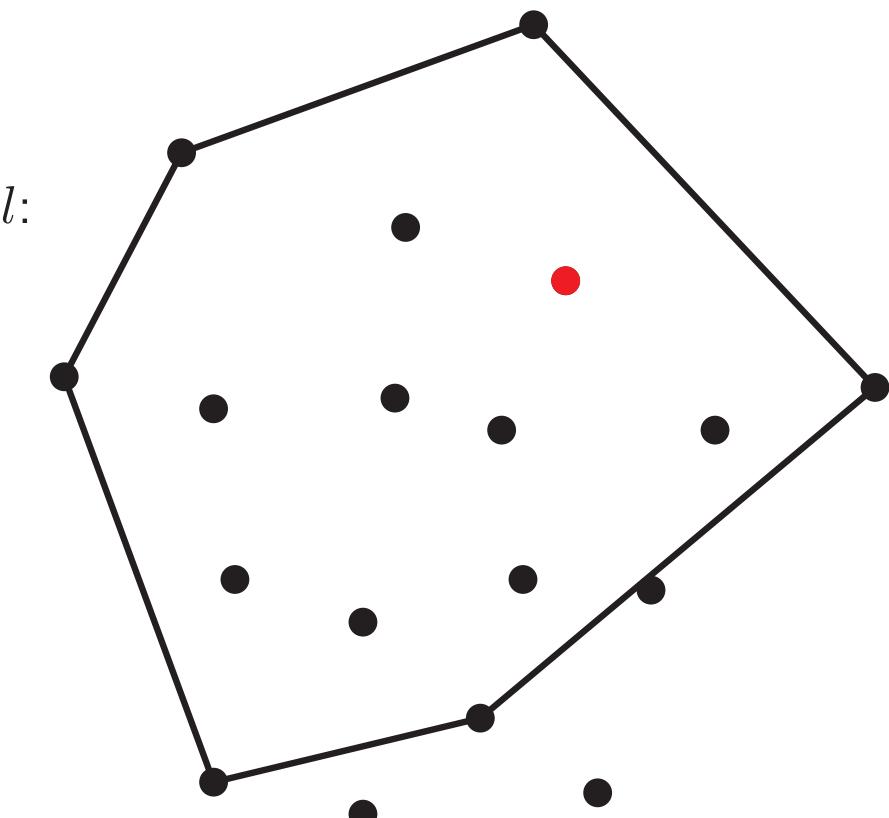
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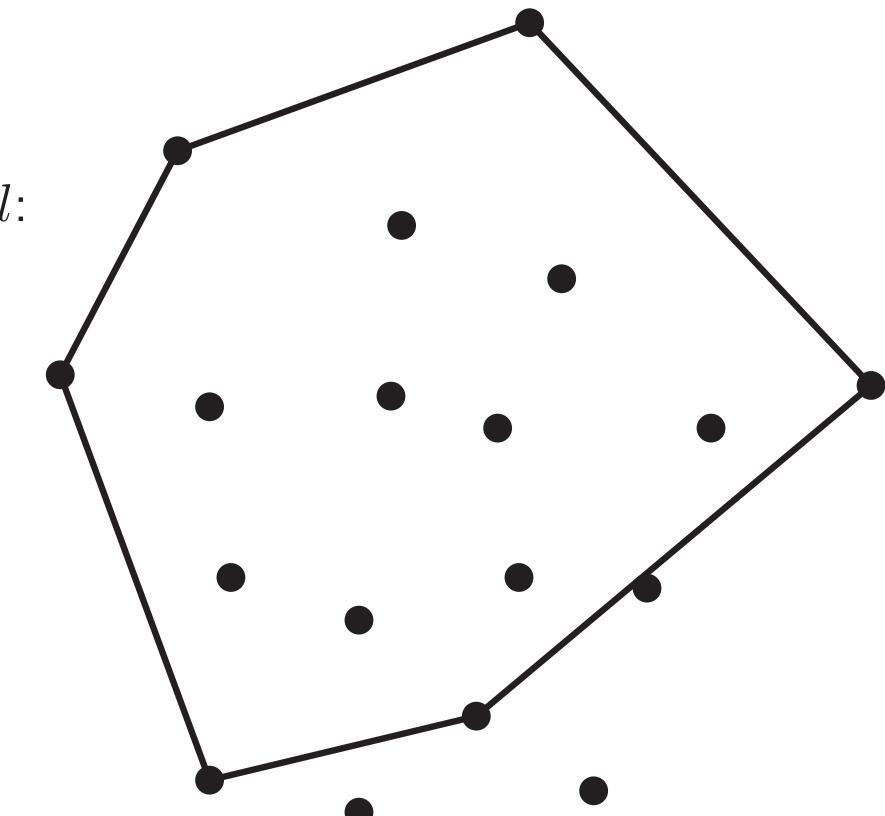
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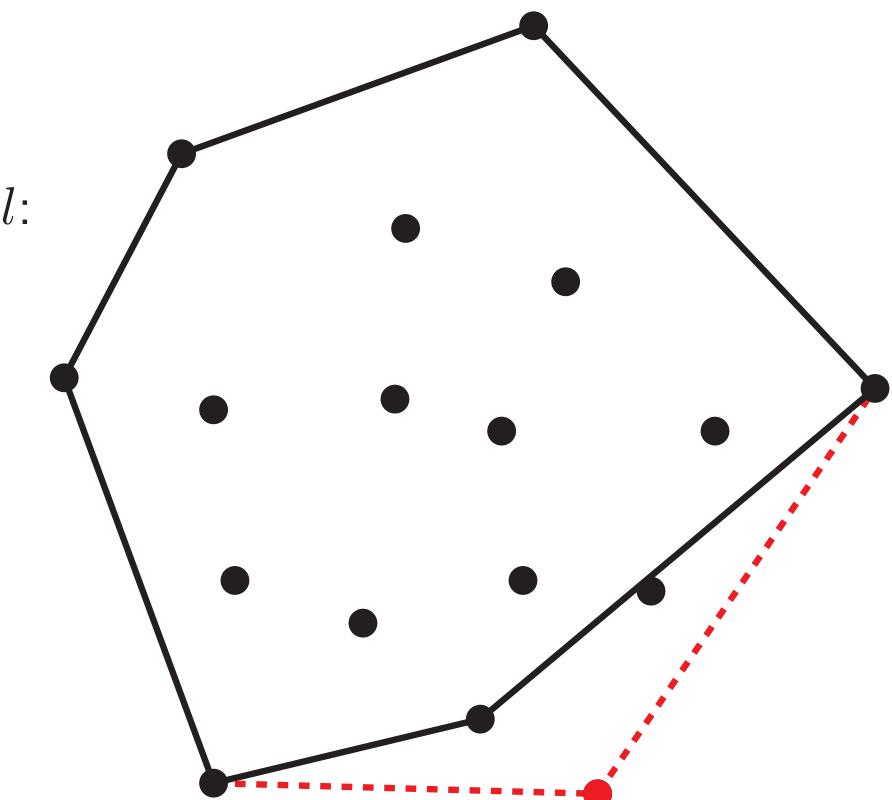
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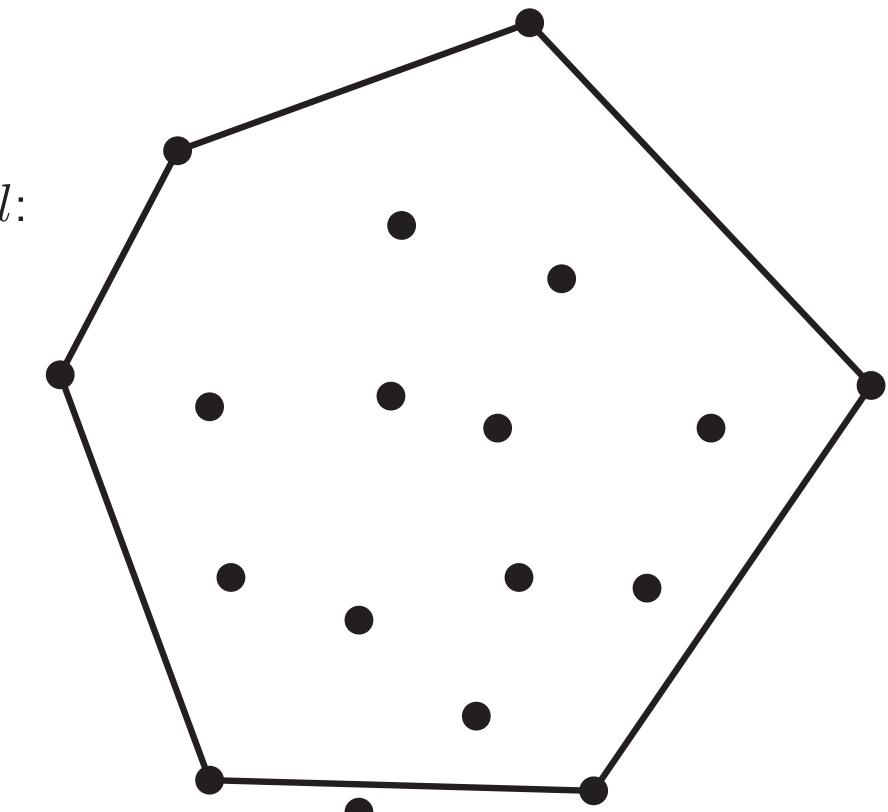
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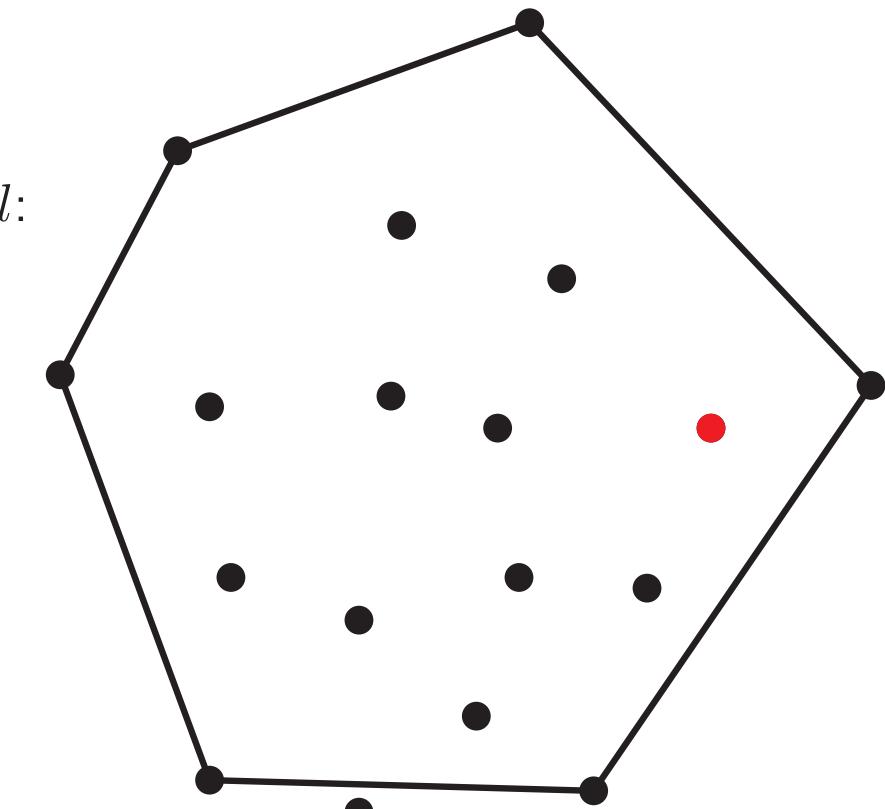
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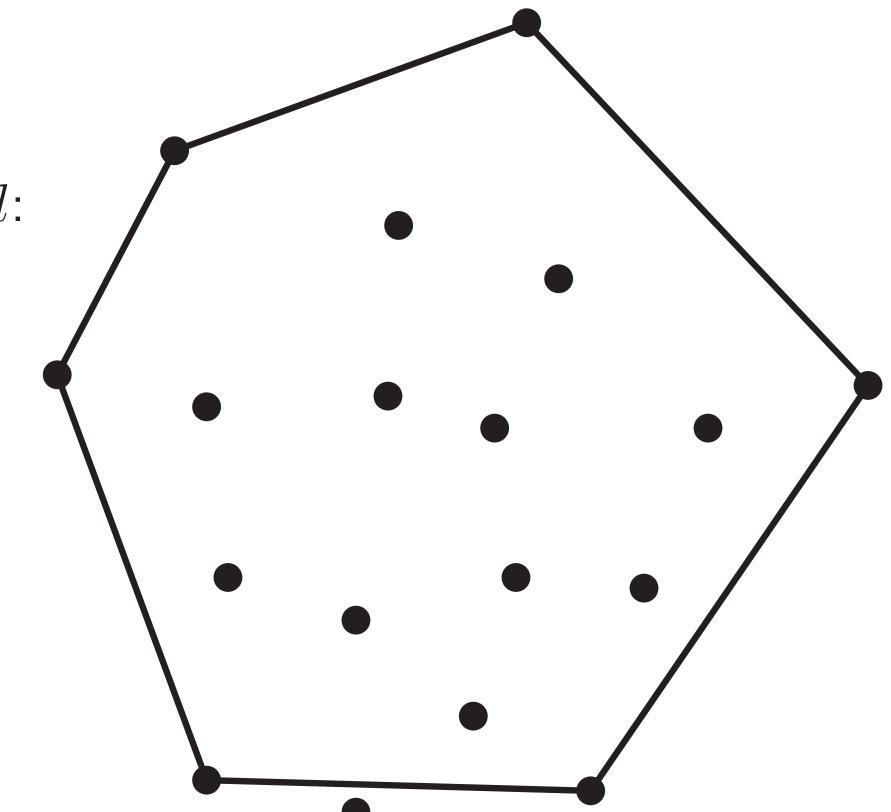
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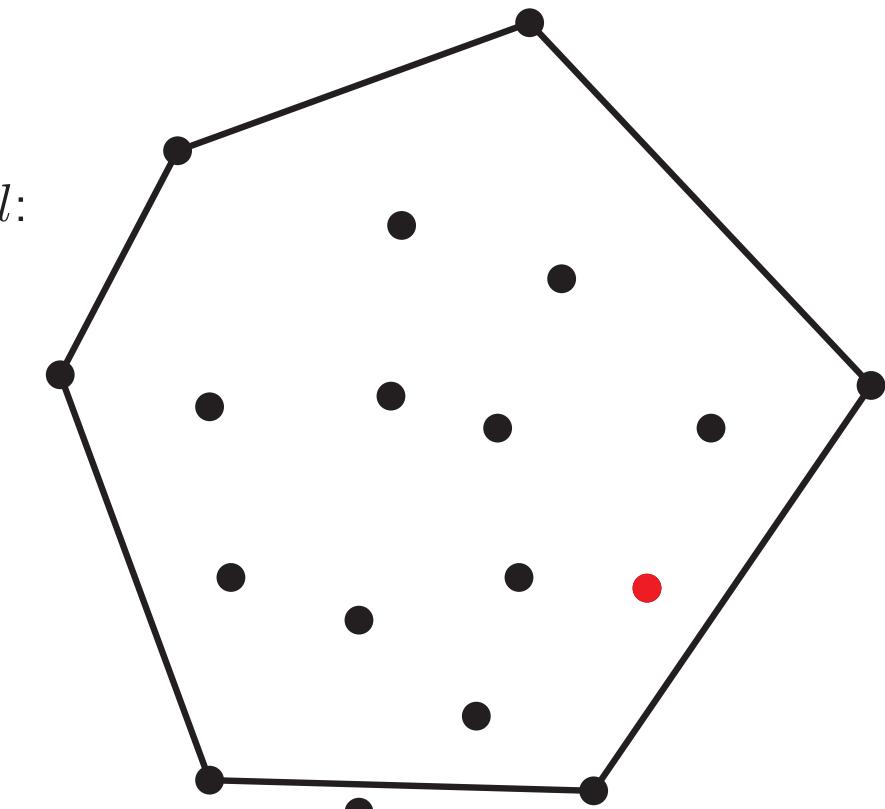
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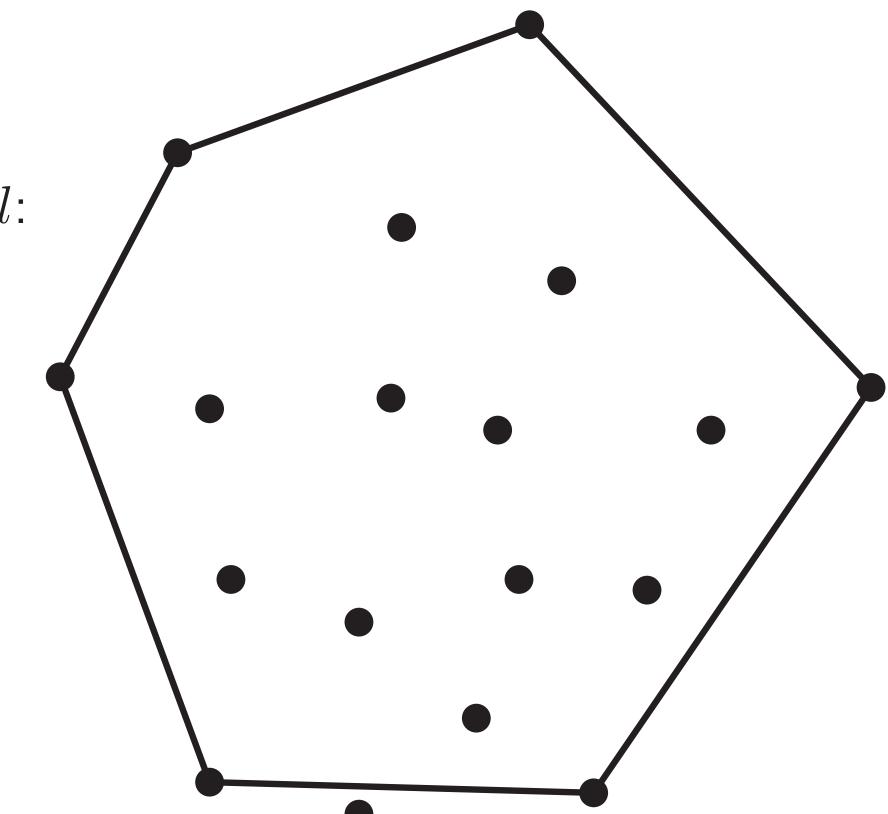
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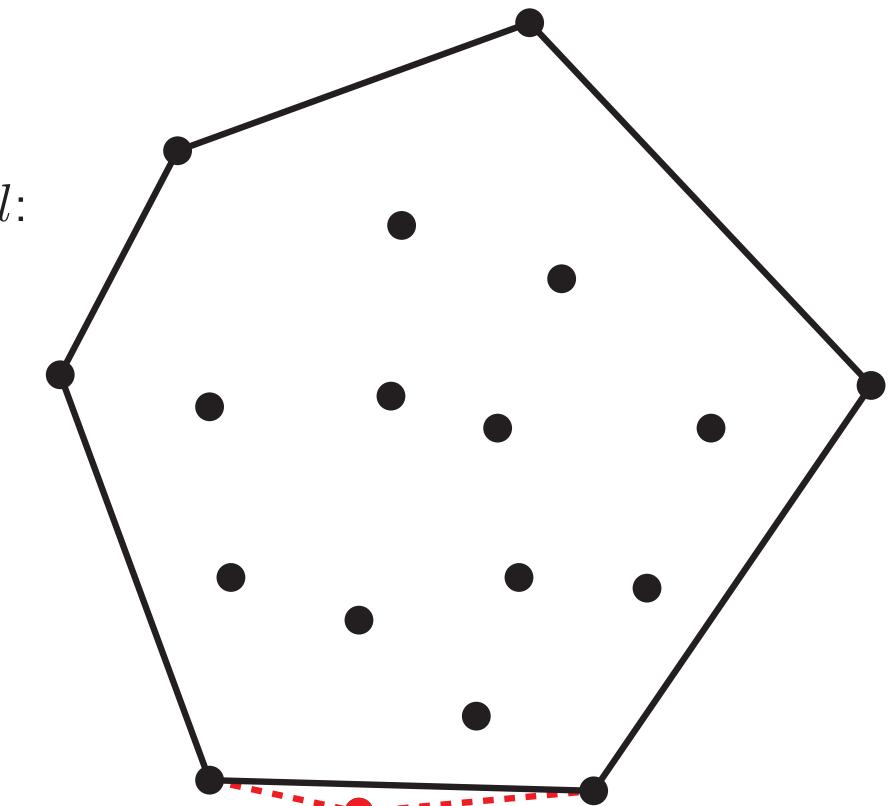
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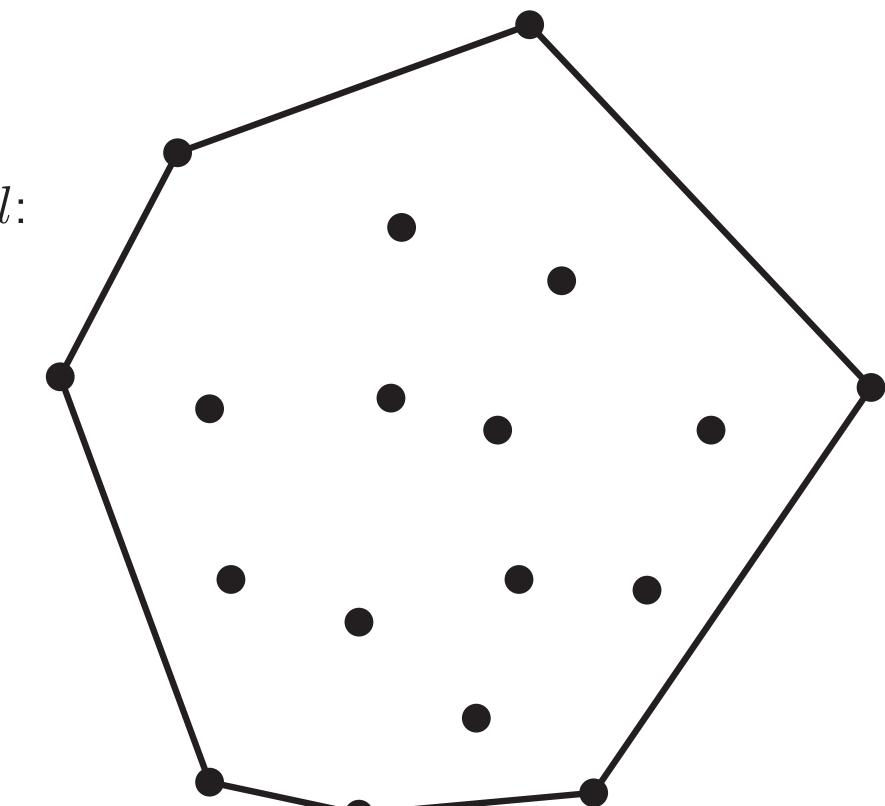
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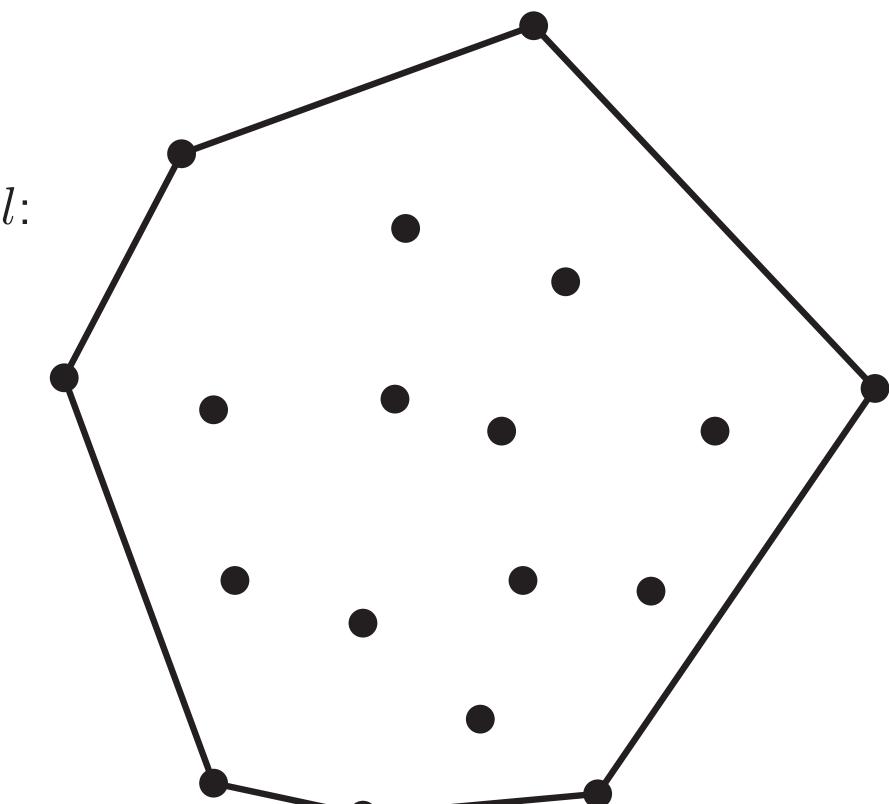
to the polygon

the chain p_l, \dots, p_r in l

the chain p_l, p_i, p_r

...

$(n \log n)$



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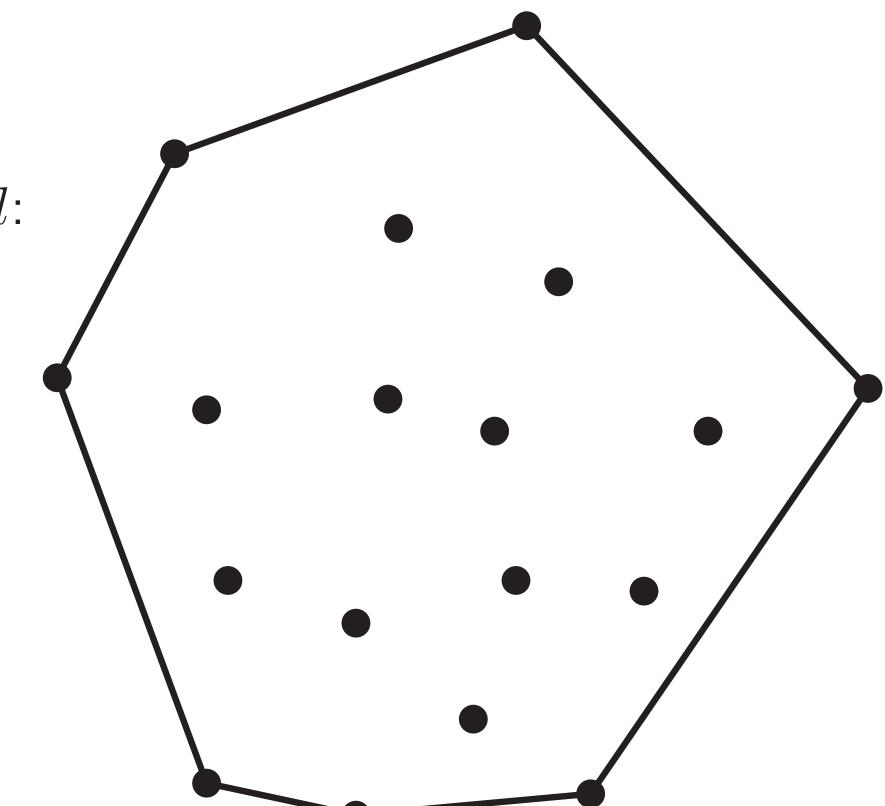
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$(n \log n)$

a structure allowing binary
gs (insertions and deletions)

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er algorithm



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er algorithm

nts by abscissae

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er algorithm

nts by abscissae

points (x_i, y_i) into two subsets,
ian value of the abscissae

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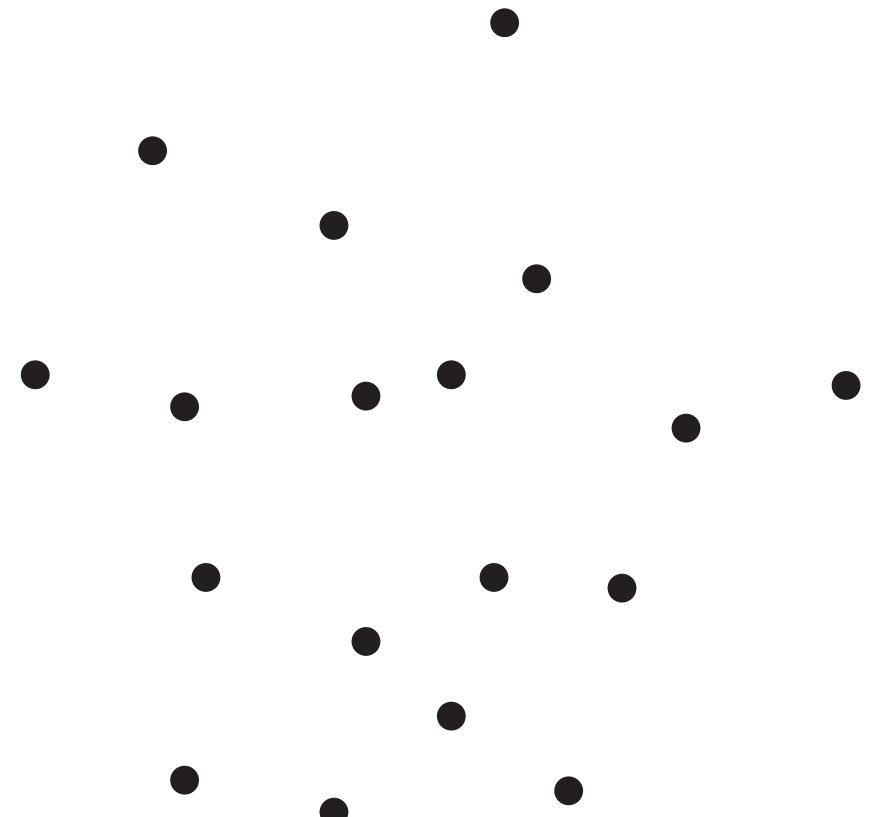
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CONVEX HULL IN 2D

Bruteforcer algorithm

Sort points by abscissae

Divide the points (x_i, y_i) into two subsets, left and right, based on the median value of the abscissae



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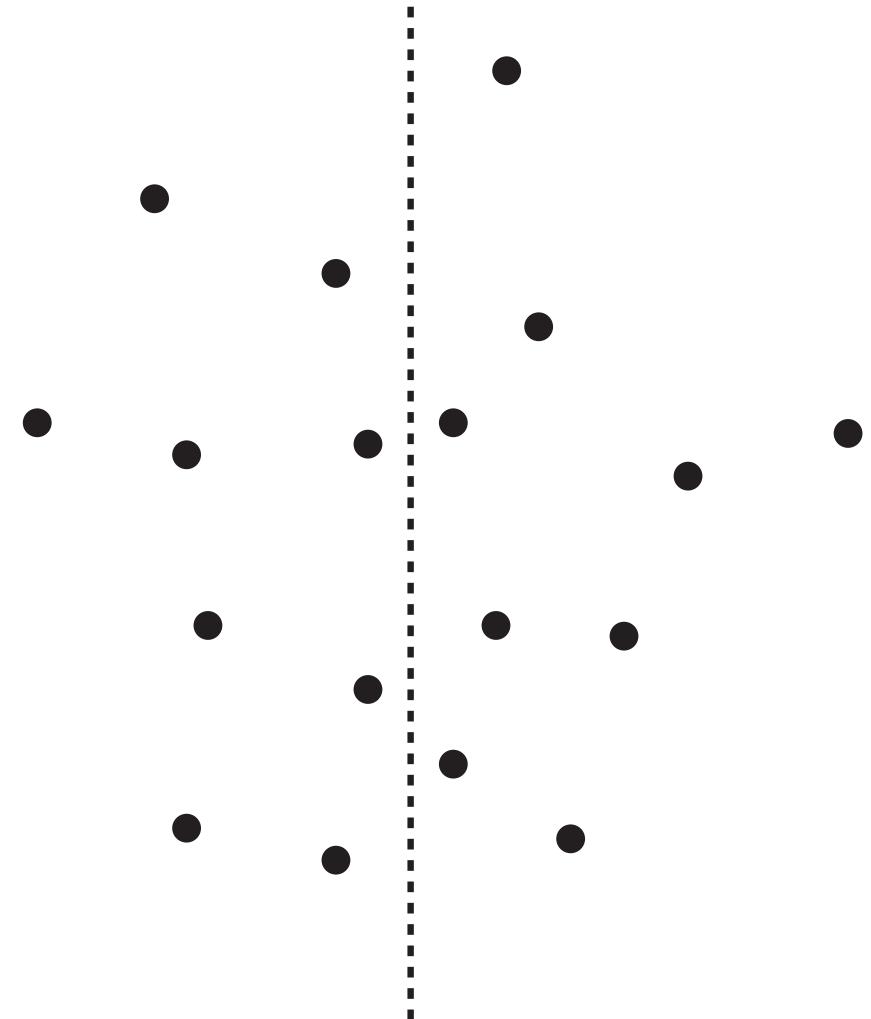
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CONVEX HULL IN 2D

Brzozowski algorithm

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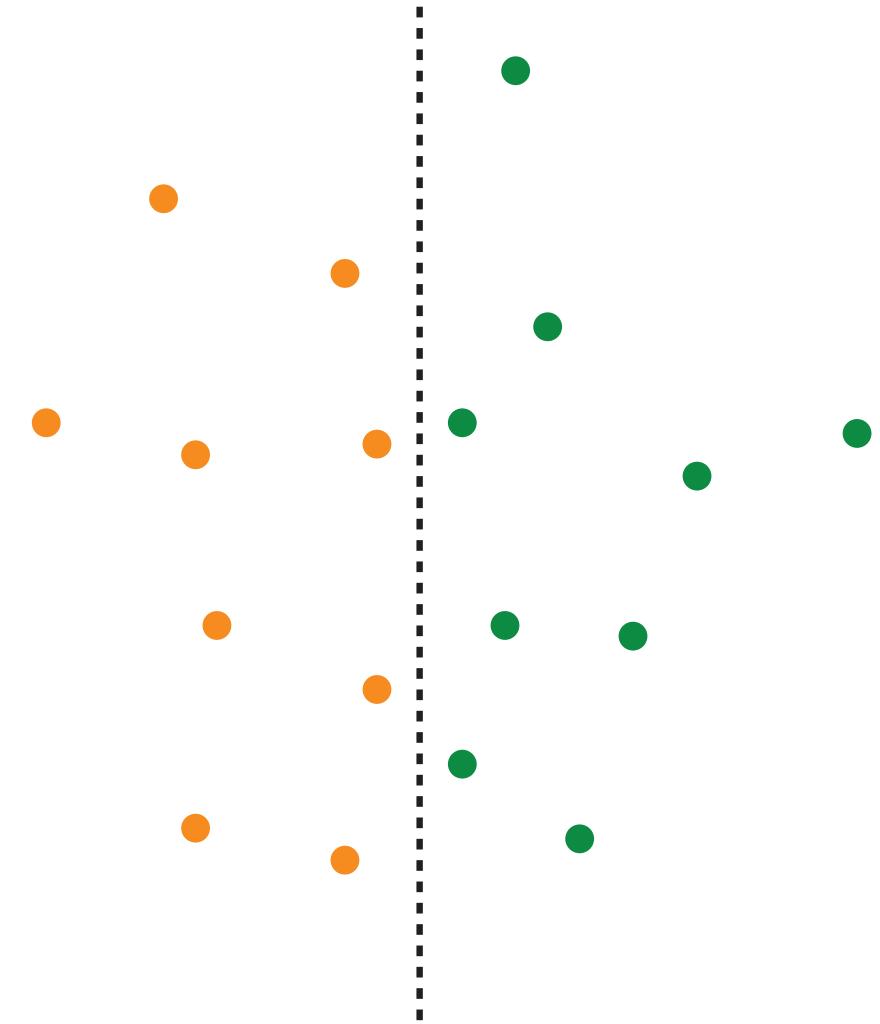
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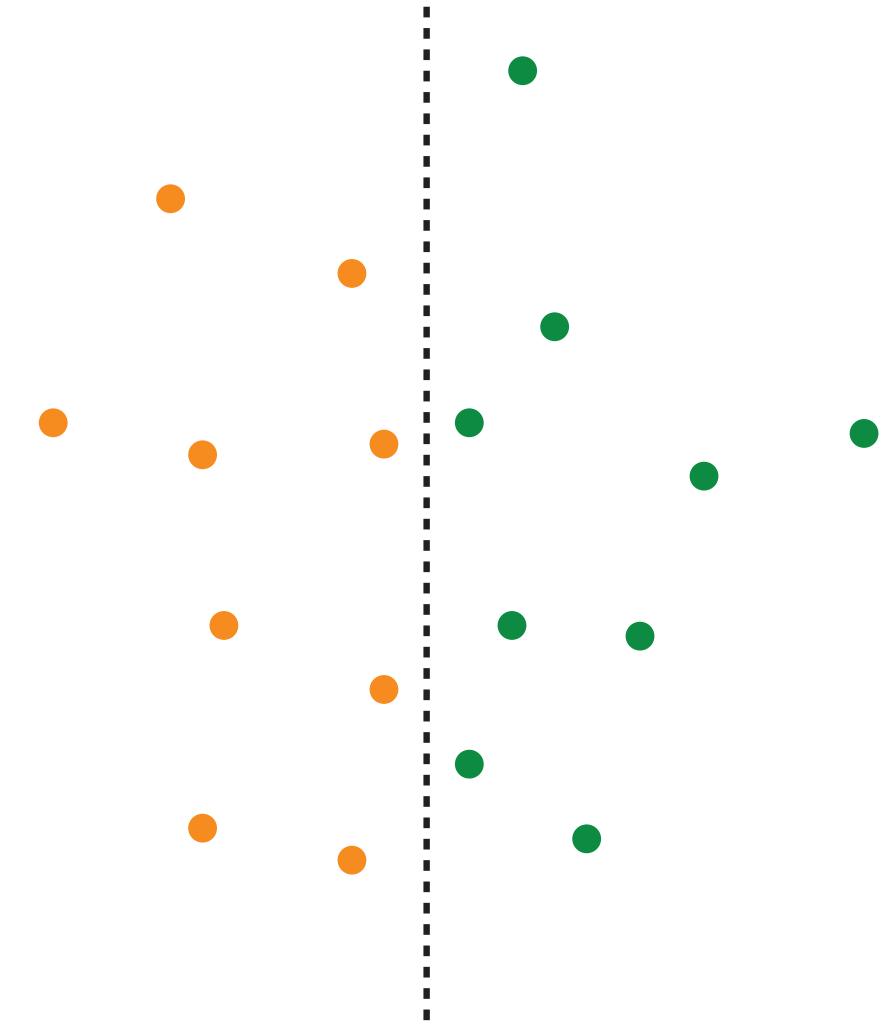
CONVEX HULL IN 2D

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compute the convex hull of the



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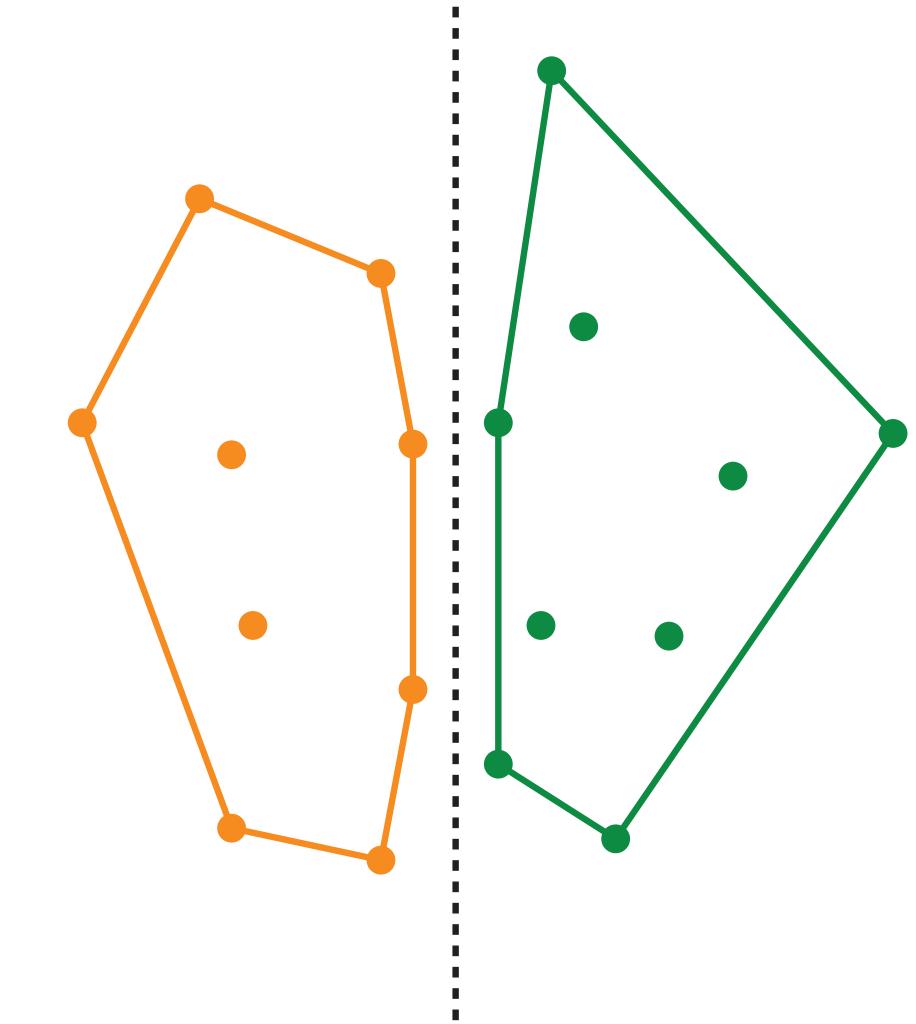
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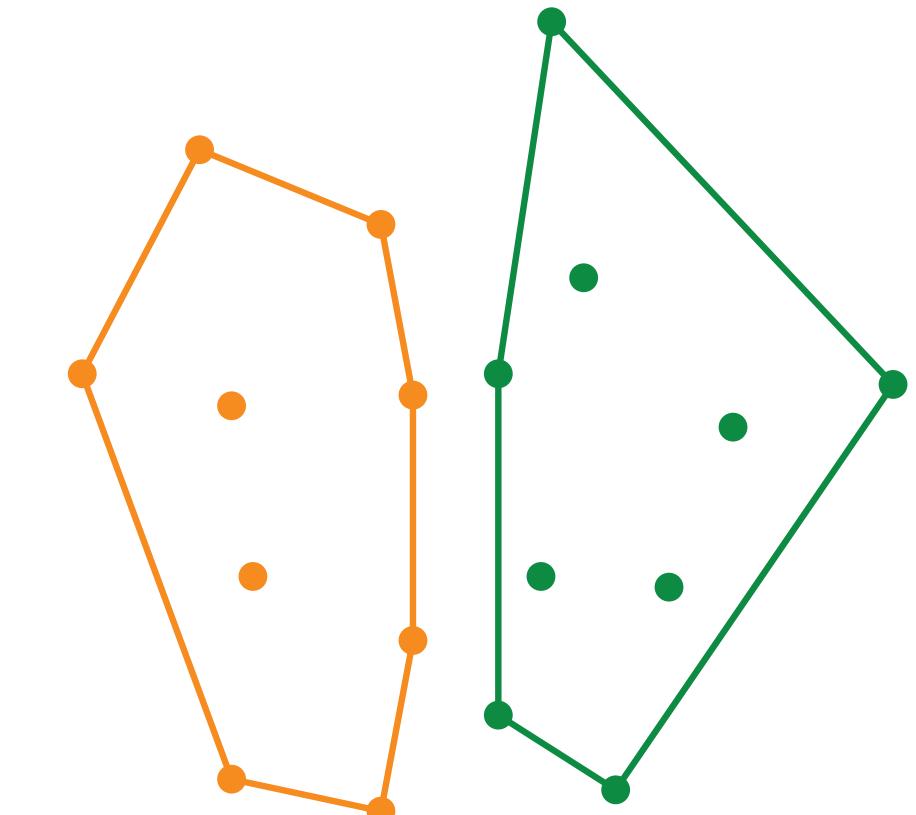
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Greedy algorithm

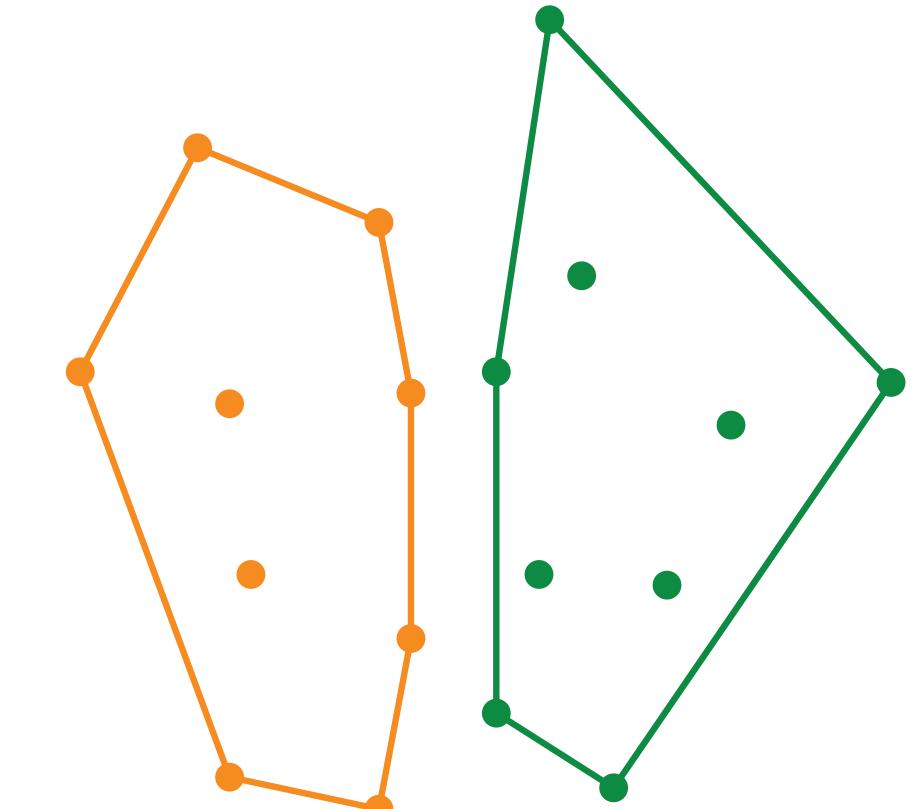
Sort points by abscissae

Divide the points (x_i, y_i) into two subsets, left and right, based on the median value of the abscissae

compute the convex hull of the

external common tangents of the two convex polygons

interior chains of the two polygons, formed by the external chains through the segments



CONVEX HULL IN 2D

Bruteforcer algorithm

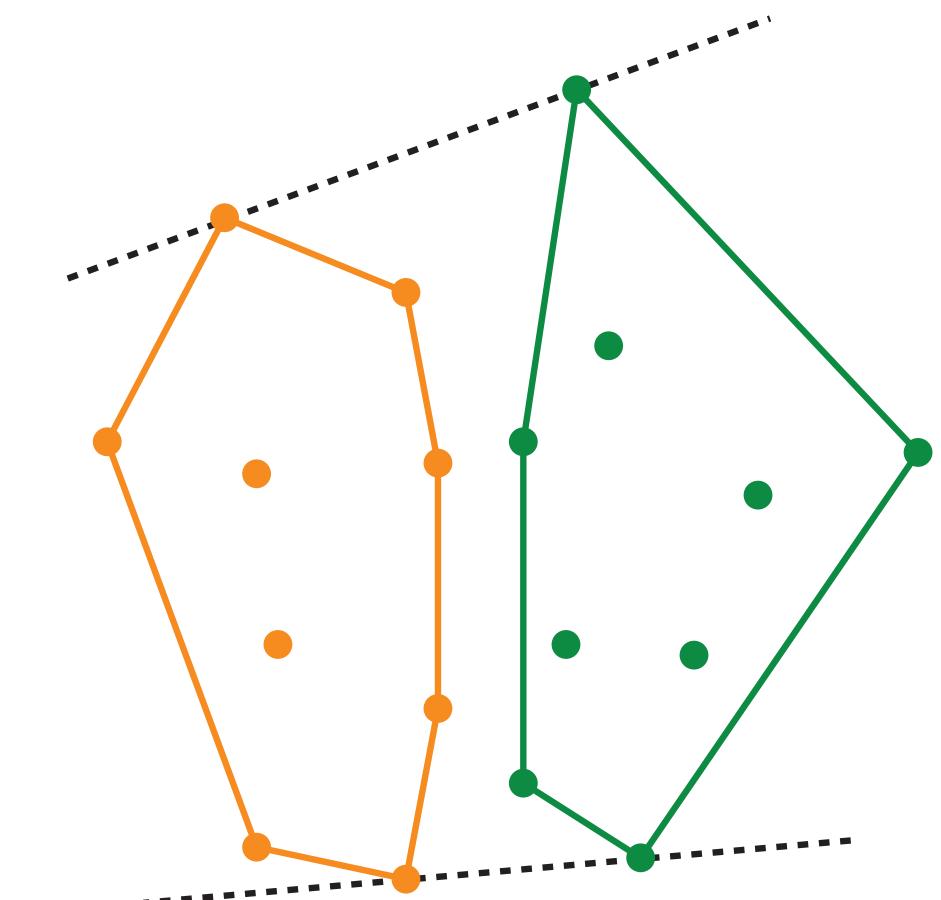
Sort points by abscissae

Divide the points (x_i, y_i) into two subsets, one for each median value of the abscissae

Divide the points into two sets and compute the convex hull of the

Divide the points into two sets and compute the external common tangents of the two convex polygons

Divide the points into two sets and compute the interior chains of the two polygons. Then, connect the exterior chains through the external common tangents segments



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CONVEX HULL IN 2D

Bruteforcer algorithm

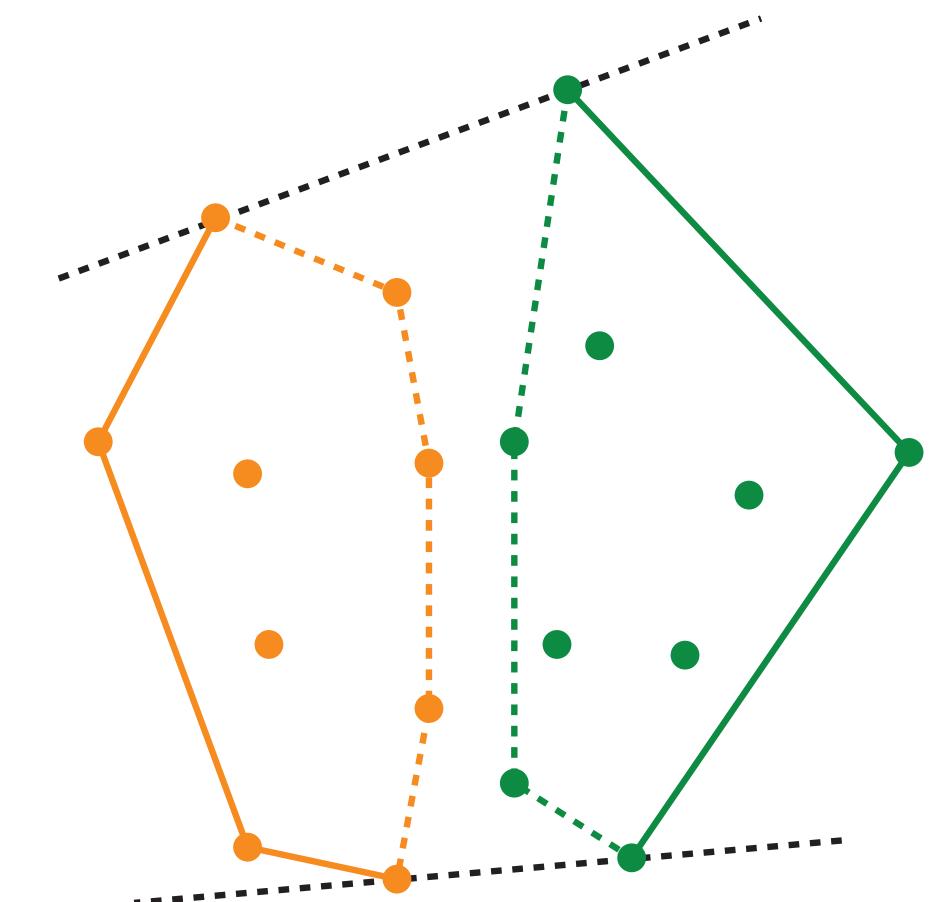
Sort points by abscissae

Divide the points (x_i, y_i) into two subsets, left and right, based on the median value of the abscissae

compute the convex hull of the

external common tangents of the two convex polygons

interior chains of the two polygons, formed by the external chains through the segments



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CONVEX HULL IN 2D

Greedy algorithm

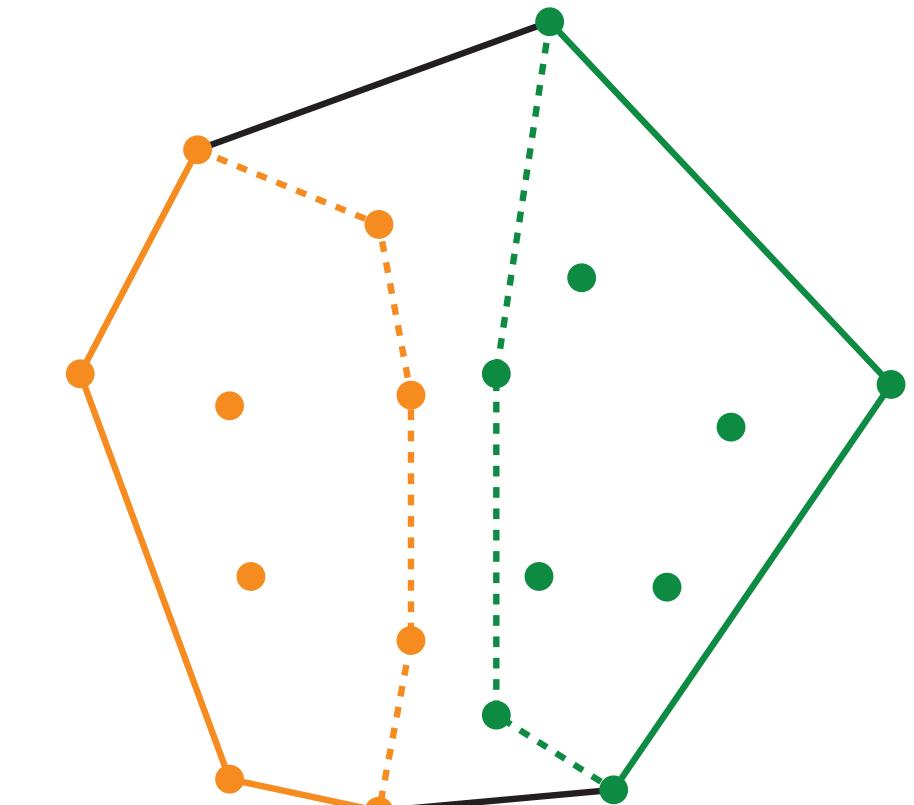
Sort points by abscissae

Divide the points (x_i, y_i) into two subsets, left and right, based on the median value of the abscissae

compute the convex hull of the

external common tangents of the two convex polygons

interior chains of the two polygons, formed by the external chains through the segments



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CONVEX HULL IN 2D

Bruteforcer algorithm

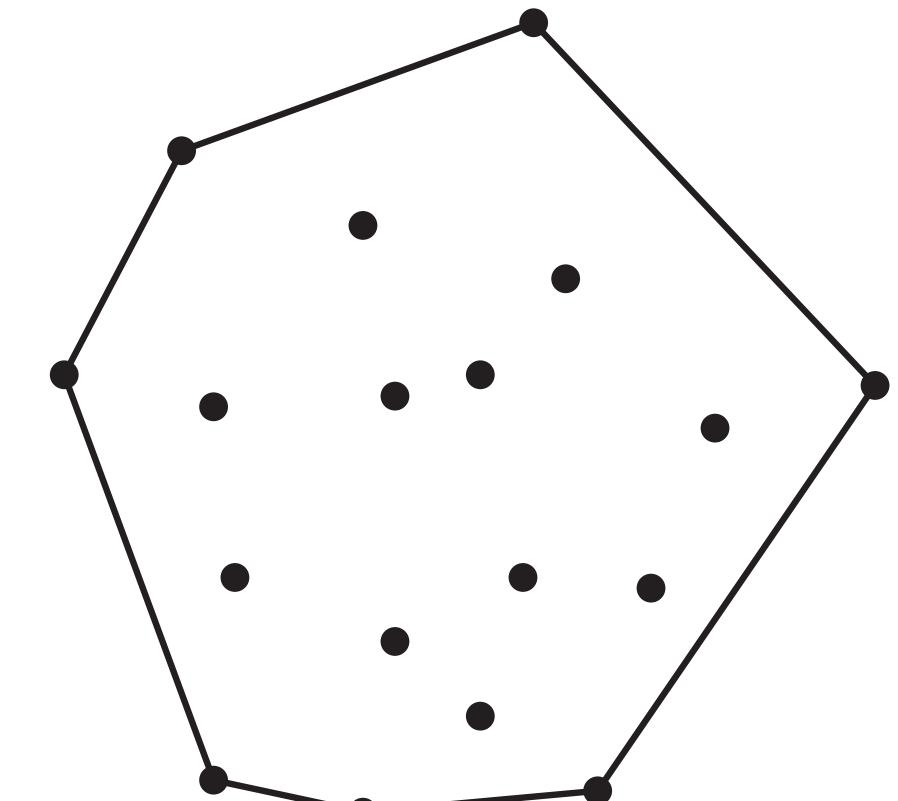
Sort points by abscissae

Divide the points (x_i, y_i) into two subsets, one for each side of the median value of the abscissae

compute the convex hull of the

external common tangents of the two convex polygons

interior chains of the two polygons in the external chains through connecting segments

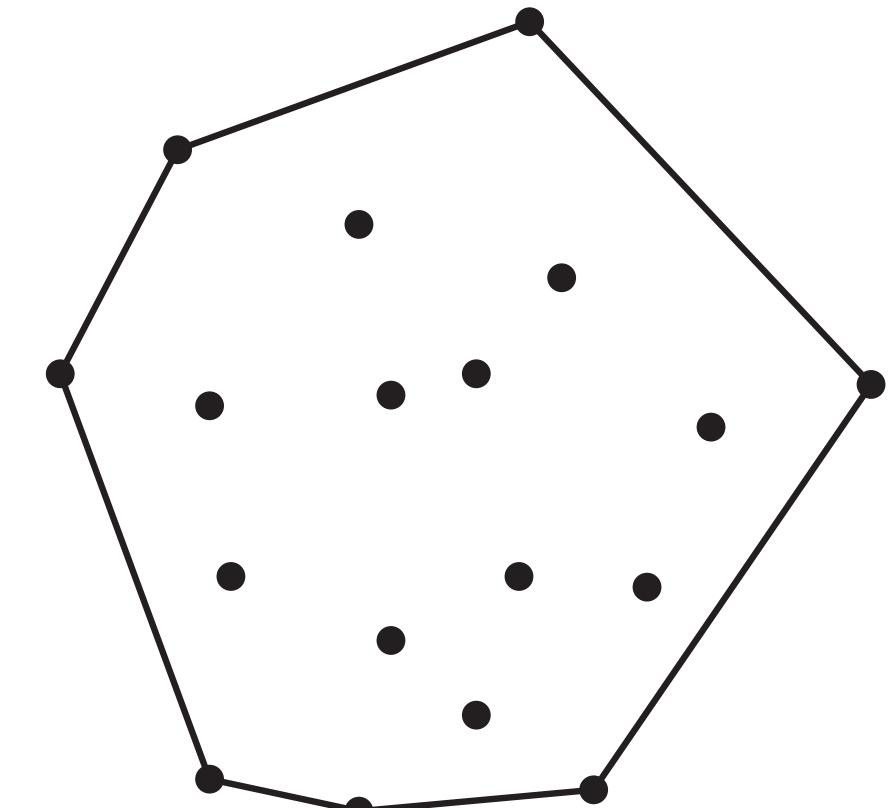


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CONVEX HULL IN 2D

Bruteforcer algorithm

$\log n$ (only once)



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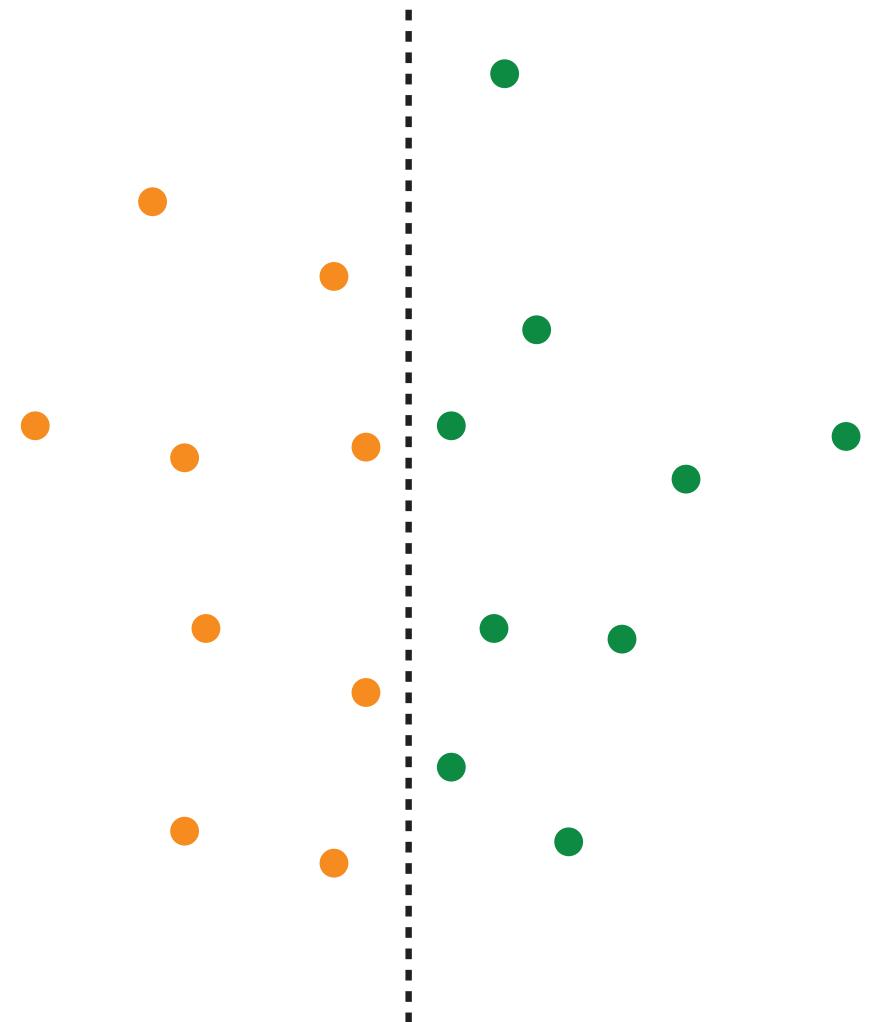
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CONVEX HULL IN 2D

Bruteforcer algorithm

$\log n$) (only once)



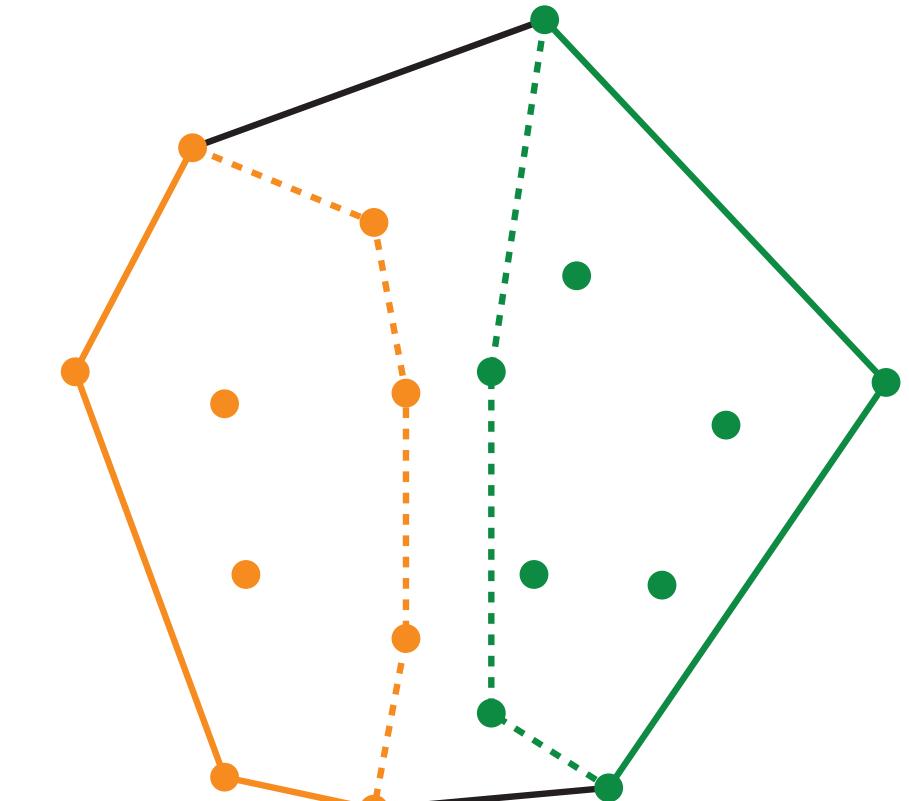
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CONVEX HULL IN 2D

Bruteforcer algorithm

$\log n$) (only once)



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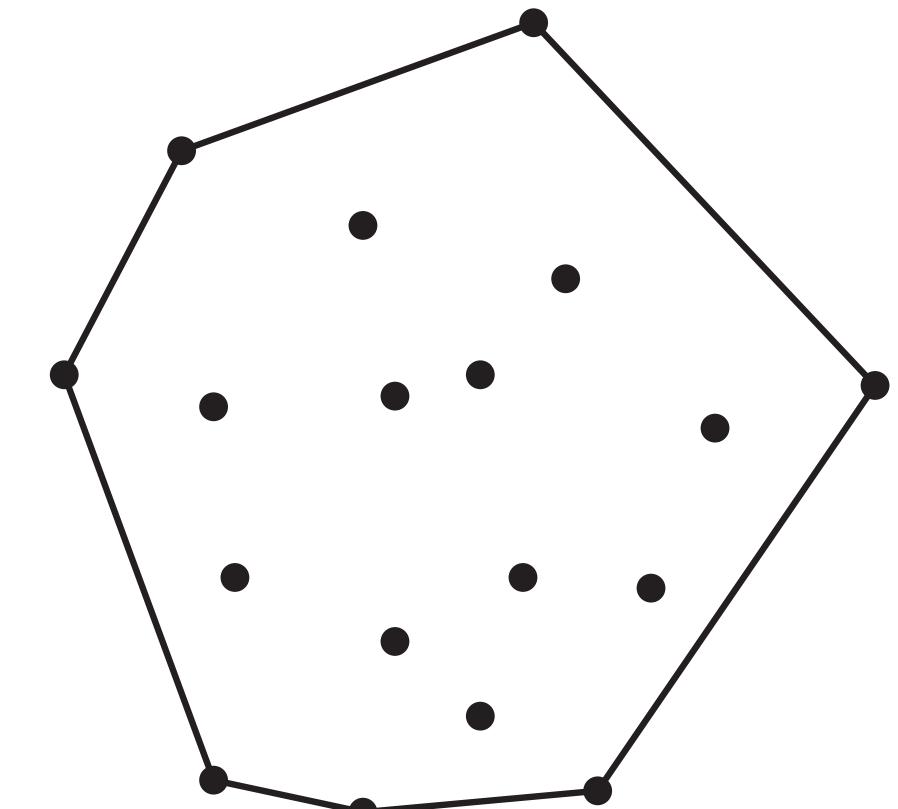
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CONVEX HULL IN 2D

Bruteforcer algorithm

$\log n)$ (only once)

$$\binom{n}{2} + O(n) = O(n \log n)$$



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CONVEX HULL IN 2D



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CONVEX HULL IN 2D



nbers
mbers

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CONVEX HULL IN 2D



nbers
mbers

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CONVEX HULL IN 2D

nbers
mbers

$$= (x_i, x_i^2)$$

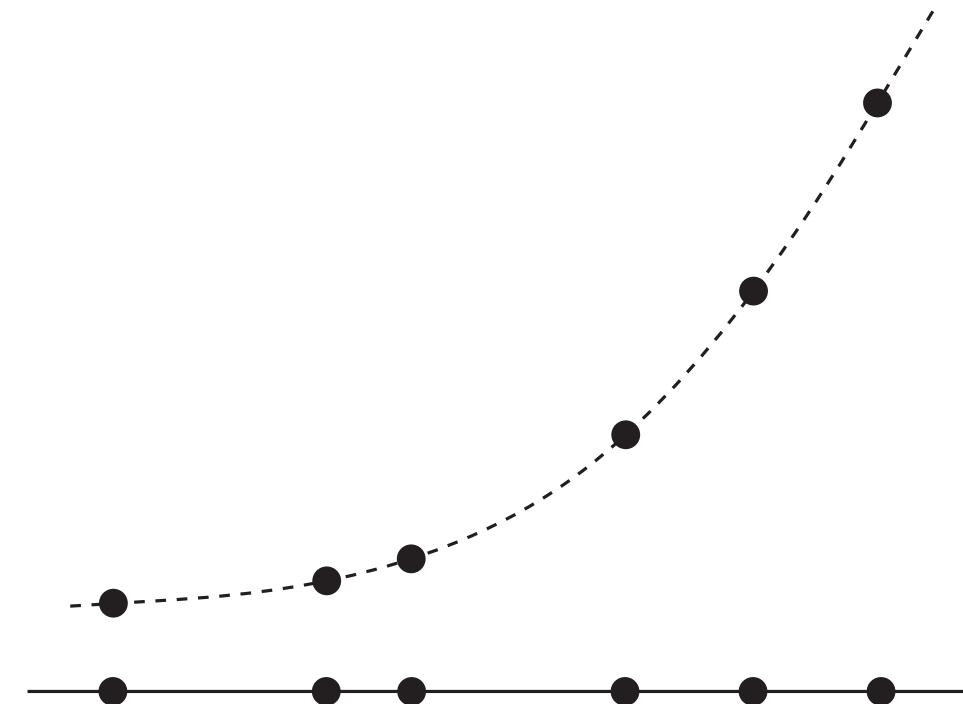


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CONVEX HULL IN 2D



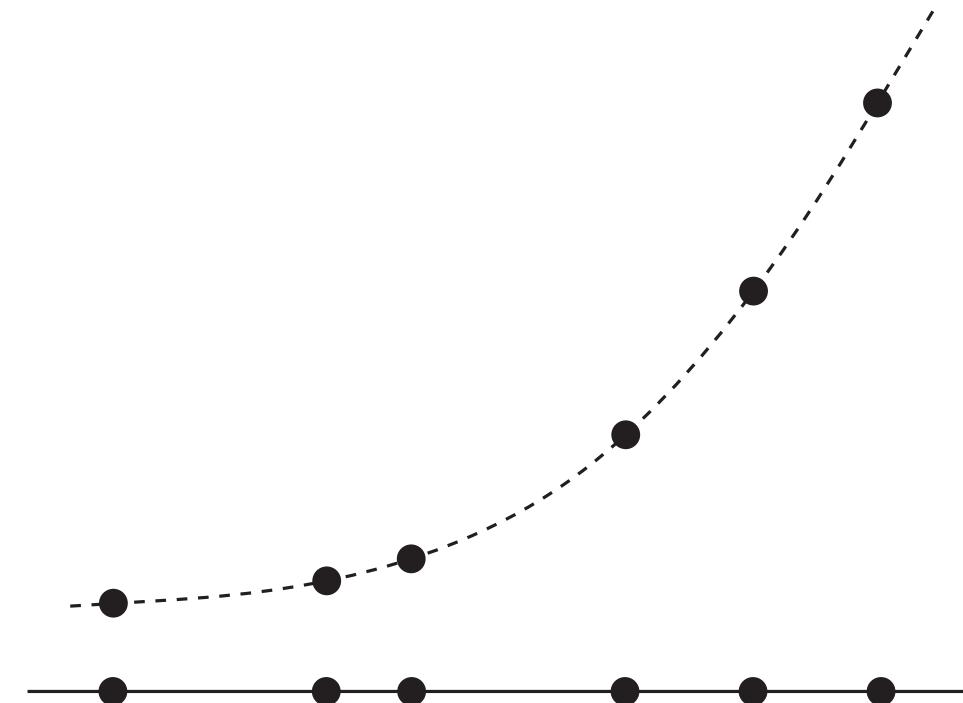
nbers
mbers

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CONVEX HULL IN 2D



nbers
mbers

$$= (x_i, x_i^2)$$

hull of the points
vertices of the convex hull

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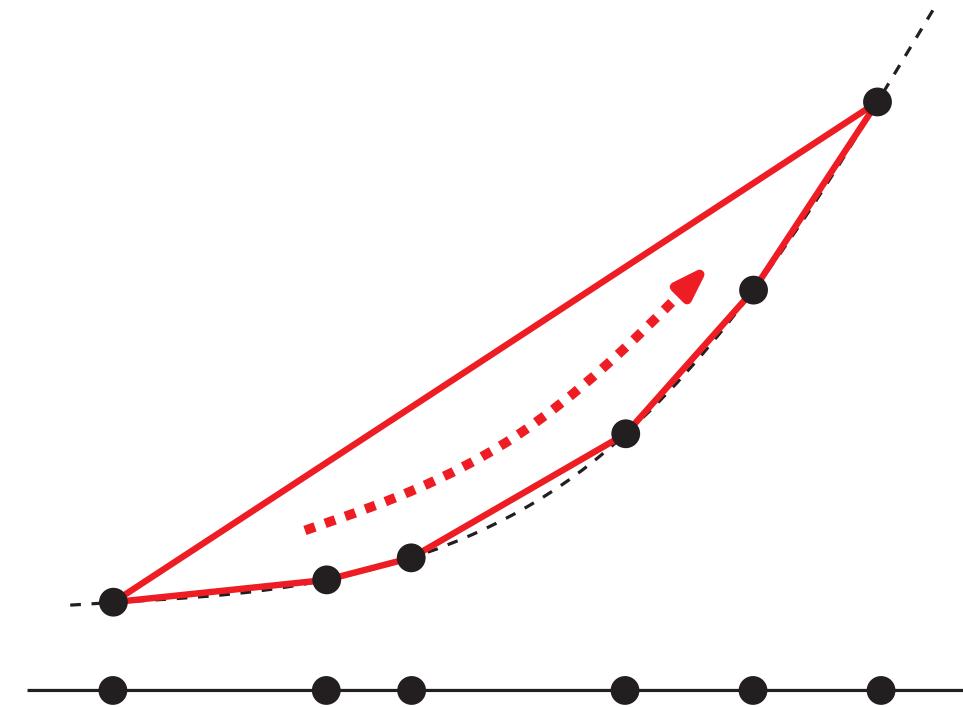
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CONVEX HULL IN 2D

nbers
mbers

$$= (x_i, x_i^2)$$

hull of the points
vertices of the convex hull



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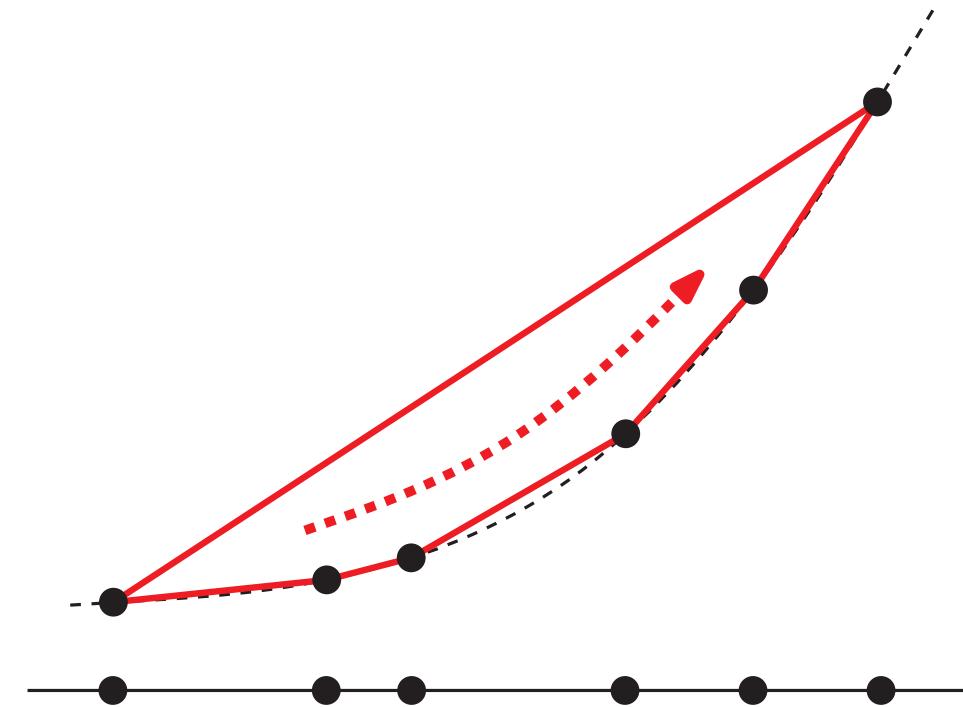
CONVEX HULL IN 2D

nbers
mbers

$$= (x_i, x_i^2)$$

hull of the points
vertices of the convex hull

the numbers
numbers x_1, \dots, x_n



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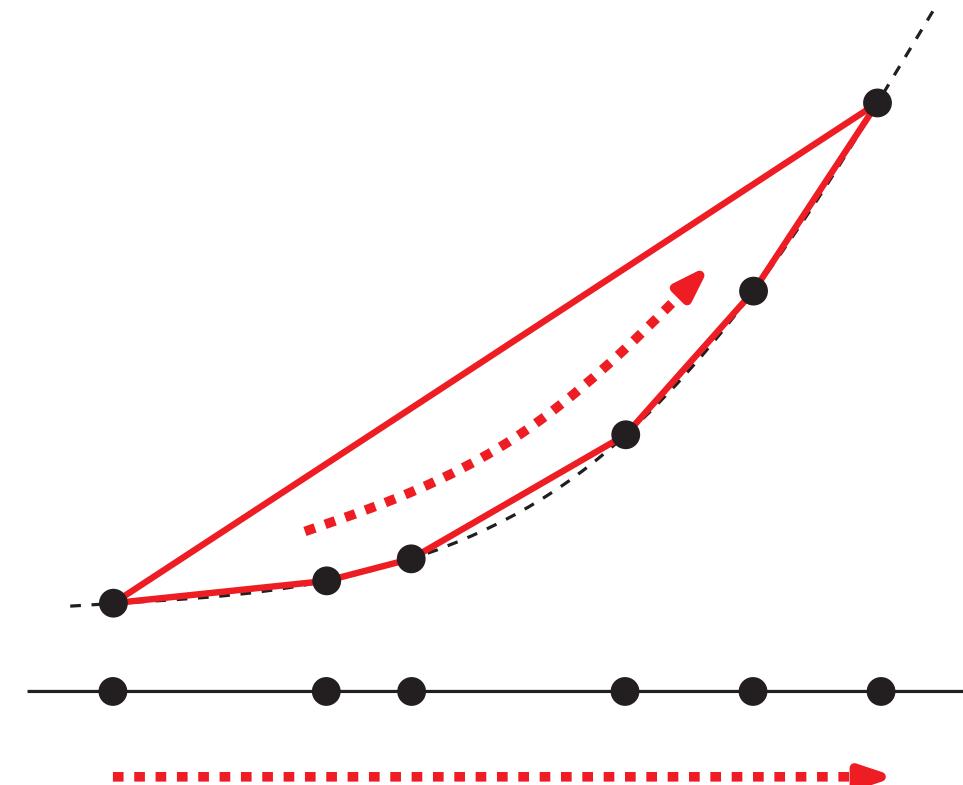
CONVEX HULL IN 2D

nbers
mbers

$$= (x_i, x_i^2)$$

hull of the points
vertices of the convex hull

the numbers
numbers x_1, \dots, x_n



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Sort

CONVEX HULL IN 2D

nbers
mbers

$O(n)$

$= (x_i, x_i^2)$

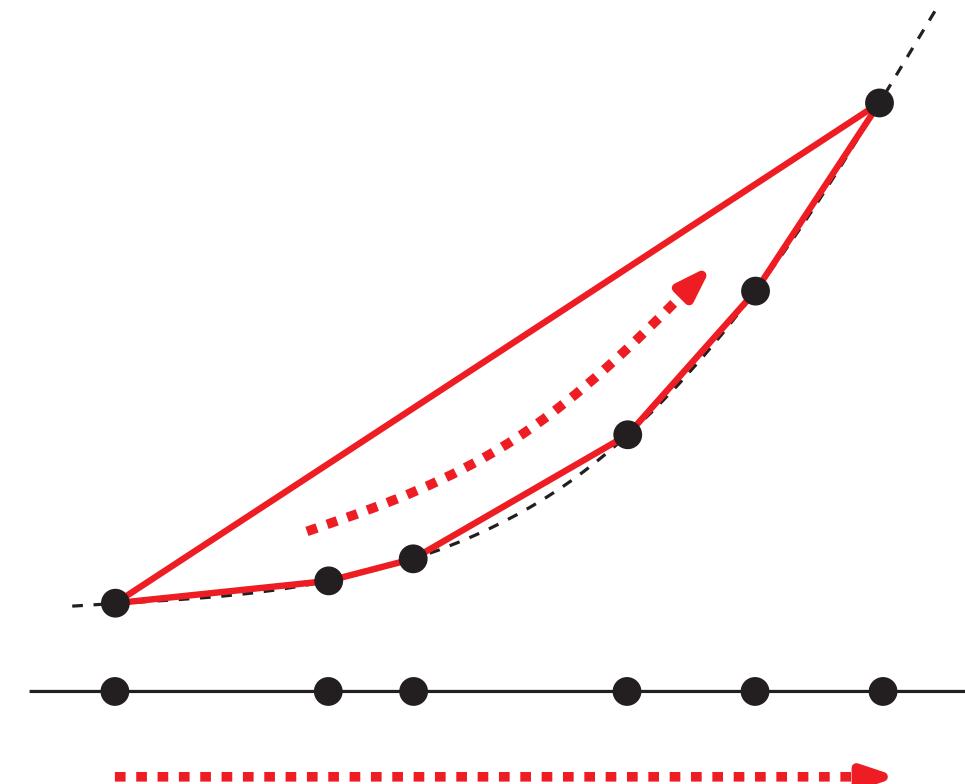
hull of the points

vertices of the convex hull

$O(n)$

the numbers

numbers x_1, \dots, x_n



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CONVEX HULL IN 2D



nbers
mbers

$O(n)$

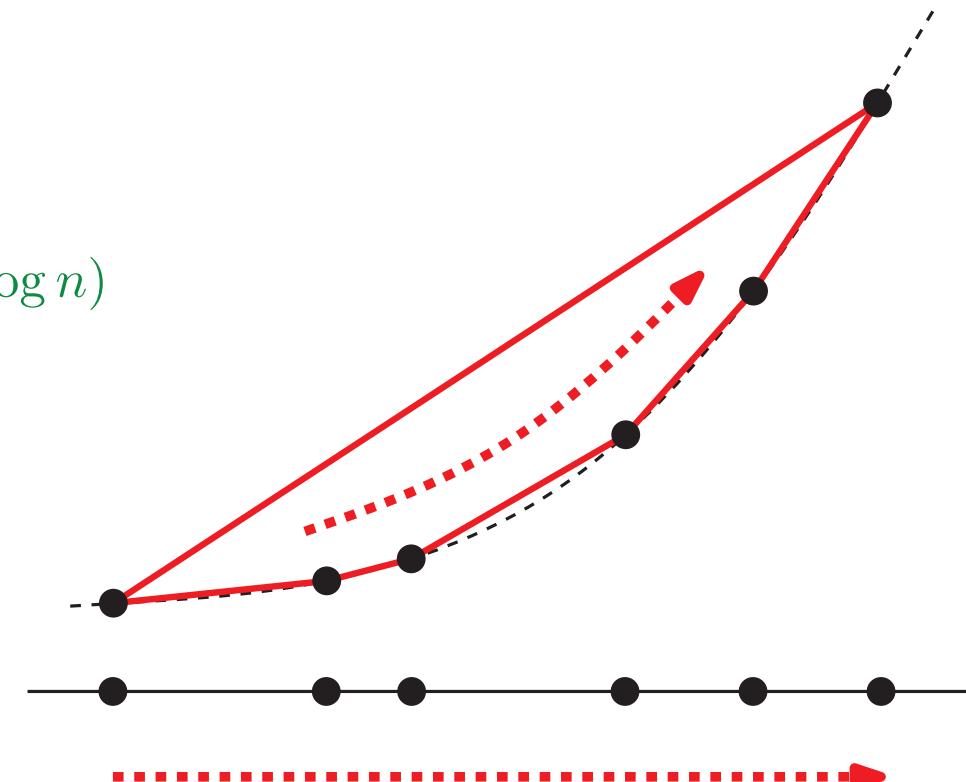
$= (x_i, x_i^2)$

hull of the points
vertices of the convex hull

$O(n)$

the numbers
numbers x_1, \dots, x_n

$\Omega(n \log n)$



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CONVEX HULL IN 2D



nbers
mbers

$O(n)$

$= (x_i, x_i^2)$

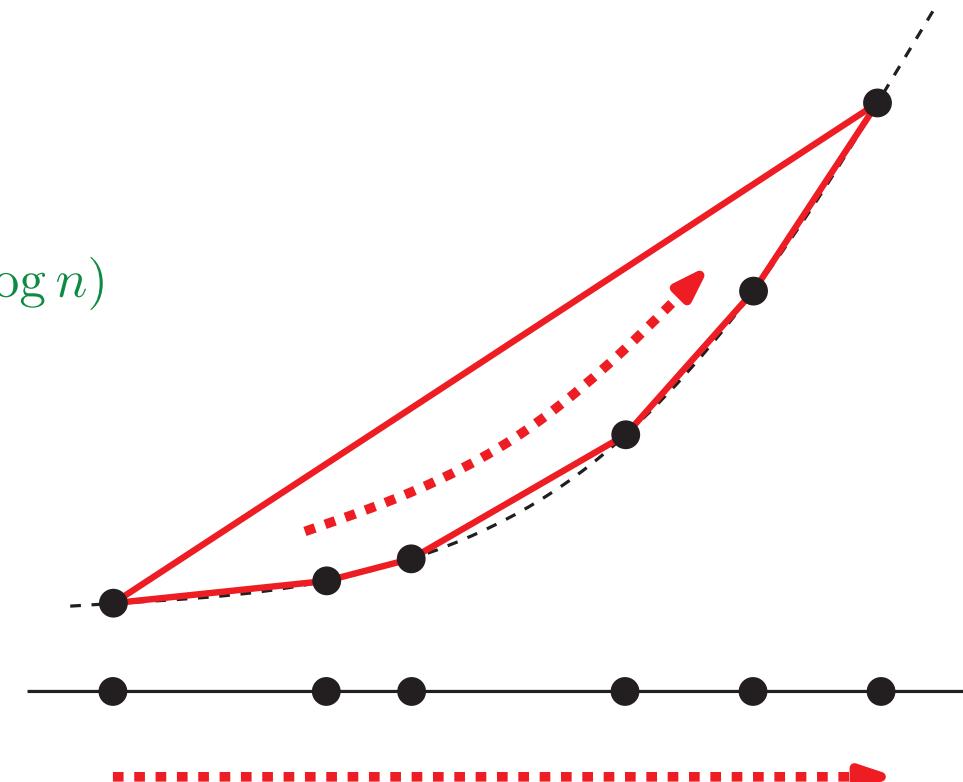
$\Omega(n \log n)$

hull of the points
vertices of the convex hull

$O(n)$

the numbers
numbers x_1, \dots, x_n

$\Omega(n \log n)$



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CONVEX HULL IN 2D

Convex hull of a simple polygon

to design an $o(n \log n)$ time algorithm by exploiting the order of the vertices
on?

for example, to apply Graham's algorithm using the order of the vertices of

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CONVEX HULL IN 2D

Ex hull of a simple polygon

to design an $o(n \log n)$ time algorithm by exploiting the order of the vertices
on?

for example, to apply Graham's algorithm using the order of the vertices of

the previous strategies extend to the 3D case?

to design an 3-dimensional gitf wrap convex hull algorithm?

to design a 3-dimensional incremental convex hull algorithm?

to design a 3-dimensional divide-and-conquer convex hull algorithm?

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CONVEX HULL IN 2D

FURTHER READING

Computational Geometry in C (2nd ed.), Cambridge University Press,

, M. Shamos, Computational Geometry: An introduction (revised ed.),
93.

...AND PLAYING

www.dma.fi.upm.es/docencia/segundociclo/geomcomp/convex.html

www.cse.unsw.edu.au/~lambert/java/3d

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