

# Métodos Matemáticos de Bioingeniería

## Grado en Ingeniería Biomédica

### Lecture 9

Marius A. Marinescu

Departamento de Teoría de la Señal y Comunicaciones  
**Área de Estadística e Investigación Operativa**  
Universidad Rey Juan Carlos

22 de marzo de 2021

# Outline

## 1 The Chain Rule

## Example 1 (One dimension)

- Let

$$f(x) = \sin x$$

$$x(t) = t^3 + t$$

- We may then construct the **composite function**

$$(f \circ x)(t) = f(x(t)) = \sin(t^3 + t)$$

- The **chain rule** tells us how to find the derivative of  $f \circ x$  with respect to  $t$

$$(f \circ x)'(t) = \frac{d}{dt}(\sin(t^3 + t)) = (\cos(t^3 + t))(3t^2 + 1)$$

- Since  $x = t^3 + t$ , we can see it as

$$(f \circ x)'(t) = \frac{d}{dx}(\sin x) \cdot \frac{d}{dt}(t^3 + t) = f'(x) \cdot x'(t)$$

## The Chain Rule in One Variable

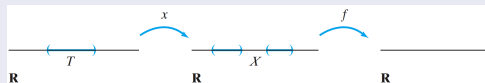
- In general, suppose  $X$  and  $T$  are open subsets of  $\mathbb{R}$ .
- Suppose we define functions

$$f : X \subseteq \mathbb{R} \rightarrow \mathbb{R}$$

$$x : T \subseteq \mathbb{R} \rightarrow \mathbb{R}$$

- Suppose that the composite function makes sense

$$f \circ x : T \subseteq \mathbb{R} \rightarrow X \subseteq \mathbb{R} \rightarrow \mathbb{R}$$



This means that the range of the function  $x$  must be contained in  $X$ , the domain of  $f$

### Theorem 5.1: The Chain Rule in One Variable

- Let  $X$  and  $T$  be open subsets of  $\mathbb{R}$
- We define functions

$$f : X \subseteq \mathbb{R} \rightarrow \mathbb{R}$$

$$x : T \subseteq \mathbb{R} \rightarrow \mathbb{R}$$

$$f \circ x : X \subseteq \mathbb{R} \rightarrow \mathbb{R}$$

- Suppose  $x$  is differentiable at  $t_0 \in T$ , and
- Suppose  $f$  is differentiable at  $x_0 = x(t_0) \in X$
- Then, **the composite**  $f \circ x$  is **differentiable** at  $t_0$ , and

$$(f \circ x)'(t_0) = f'(x_0)x'(t_0)$$

## The Chain Rule in Two Variables

- Assume  $f : X \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}$  is a  **$C^1$  function** of two variables.
- Assume  $\mathbf{x} : T \subseteq \mathbb{R} \rightarrow \mathbb{R}^2$  is a differentiable vector-valued function of a single variable and the range of  $\mathbf{x}$  is contained in  $X$ .
- Then **the composition**  $f \circ \mathbf{x} : T \rightarrow \mathbb{R}$  is differentiable at any point  $t_0$ , and,

$$\frac{df}{dt}(t_0) = \frac{\partial f}{\partial x}(\mathbf{x}_0) \frac{dx}{dt}(t_0) + \frac{\partial f}{\partial y}(\mathbf{x}_0) \frac{dy}{dt}(t_0)$$

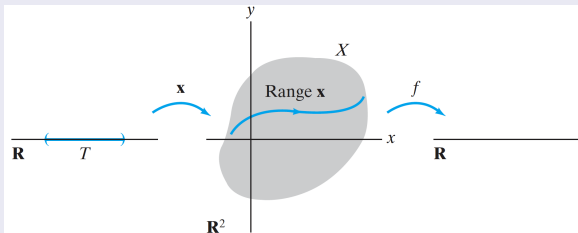
where  $\mathbf{x}_0 = \mathbf{x}(t_0)$ .

Notice the mixture of ordinary and partial derivatives appearing in the formula

## The Chain Rule in Two Variables

- It helps to think of
  - $\mathbf{x}$  as describing a **parametrized curve** in  $\mathbb{R}^2$ , and
  - $f$  as a sort of “**temperature function**” on  $X$
- The composite  $f \circ \mathbf{x}$  is then the **restriction** of  $f$  to the **curve**.

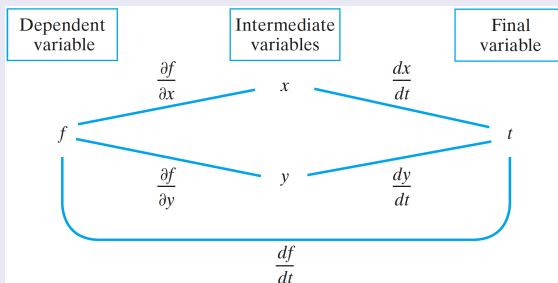
Is the function that measures the temperature  
along just the curve.



## Proposition 5.2

$$\frac{df}{dt}(t_0) = \frac{\partial f}{\partial x}(\mathbf{x}_0) \frac{dx}{dt}(t_0) + \frac{\partial f}{\partial y}(\mathbf{x}_0) \frac{dy}{dt}(t_0)$$

- We can construct an appropriate “variable hierarchy” diagram



- At the intermediate level,  $f$  depends on two variables,  $x$  and  $y$ .
- On the final or composite level,  $f$  depends on just a single independent variable  $t$ .



## Example 2

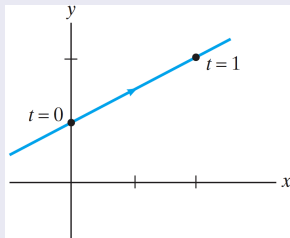
- Let,

$$f(x, y) = \frac{(x + y^2)}{(2x^2 + 1)}$$

- Suppose  $f$  is a temperature function on  $\mathbb{R}^2$ , and

$$\mathbf{x}(t) = (2t, t + 1)$$

- that is a line given in parametric equations,  $\mathbf{x}$ :



## Example 2

- Then

$$f \circ \mathbf{x}(t) = f(\mathbf{x}(t)) = \frac{2t + (t + 1)^2}{8t^2 + 1} = \frac{t^2 + 4t + 1}{8t^2 + 1}$$

- $f \circ \mathbf{x}$  is the temperature function along the line, and by the quotient rule the **rate of change** of the temperature (per unit change in  $t$ ) is:

$$\frac{df}{dt} = \frac{4 - 14t - 32t^2}{(8t^2 + 1)^2}$$

## Example 2 (board)

$$f(x, y) = \frac{(x + y^2)}{(2x^2 + 1)}$$

$$\mathbf{x}(t) = (2t, t + 1)$$

- On the other hand, all the hypotheses of [Proposition 5.2](#) are satisfied, and so

$$\frac{\partial f}{\partial x} = \frac{1 - 2x^2 - 4xy^2}{(2x^2 + 1)^2}$$

$$\frac{\partial f}{\partial y} = \frac{2y}{2x^2 + 1}$$

$$\mathbf{x}'(t) = \left( \frac{dx}{dt}, \frac{dy}{dt} \right) = (2, 1)$$

## Example 2

$$f(x, y) = \frac{(x + y^2)}{(2x^2 + 1)}, \quad \mathbf{x}(t) = (2t, t + 1)$$

$$\frac{\partial f}{\partial x} = \frac{1 - 2x^2 - 4xy^2}{(2x^2 + 1)^2}, \quad \frac{\partial f}{\partial y} = \frac{2y}{2x^2 + 1}$$

$$\mathbf{x}'(t) = \left( \frac{dx}{dt}, \frac{dy}{dt} \right) = (2, 1)$$

- Therefore, applying the chain rule and substituting  $(x, y)$  by  $(2t, t + 1)$ :

$$\begin{aligned} \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} &= \frac{1 - 2x^2 - 4xy^2}{(2x^2 + 1)^2} \cdot 2 + \frac{2y}{2x^2 + 1} \cdot 1 \\ &= \frac{2(1 - 8t^2 - 8t(t + 1)^2)}{(8t^2 + 1)^2} + \frac{2(t + 1)}{8t^2 + 1} = \frac{2(2 - 7t - 16t^2)}{(8t^2 + 1)^2} \end{aligned}$$

## The Chain Rule when $\mathbf{x}$ is a multidimensional path

- **Proposition 5.2** is easy to generalize to the case where  $f$  is a function of  $n$  variables.
- Suppose  $\mathbf{x} : T \subseteq \mathbb{R} \rightarrow \mathbb{R}^n$  and  $f : X \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ .
- The appropriate chain rule formula in this case is,

$$\frac{df}{dt}(t_0) = \frac{\partial f}{\partial x_1}(\mathbf{x}_0) \frac{dx_1}{dt}(t_0) + \frac{\partial f}{\partial x_2}(\mathbf{x}_0) \frac{dx_2}{dt}(t_0) + \cdots + \frac{\partial f}{\partial x_n}(\mathbf{x}_0) \frac{dx_n}{dt}(t_0)$$

- It can also be written by using matrix notation,

$$\frac{df}{dt}(t_0) = \begin{bmatrix} \frac{\partial f}{\partial x_1}(\mathbf{x}_0) & \frac{\partial f}{\partial x_2}(\mathbf{x}_0) & \cdots & \frac{\partial f}{\partial x_n}(\mathbf{x}_0) \end{bmatrix} \begin{bmatrix} \frac{dx_1}{dt}(t_0) \\ \frac{dx_2}{dt}(t_0) \\ \vdots \\ \frac{dx_n}{dt}(t_0) \end{bmatrix}$$

## The Chain Rule when $\mathbf{x}$ is a multidimensional path

- It can also be written by using matrix notation

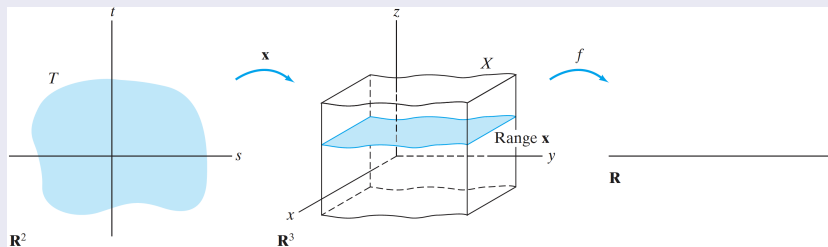
$$\frac{df}{dt}(t_0) = \begin{bmatrix} \frac{\partial f}{\partial x_1}(\mathbf{x}_0) & \frac{\partial f}{\partial x_2}(\mathbf{x}_0) & \cdots & \frac{\partial f}{\partial x_n}(\mathbf{x}_0) \end{bmatrix} \begin{bmatrix} \frac{dx_1}{dt}(t_0) \\ \frac{dx_2}{dt}(t_0) \\ \vdots \\ \frac{dx_n}{dt}(t_0) \end{bmatrix}$$

- Thus, we have shown

$$\frac{df}{dt}(t_0) = Df(\mathbf{x}_0)D\mathbf{x}(t_0) = \nabla f(\mathbf{x}_0) \cdot \mathbf{x}'(t_0)$$

## The Chain Rule when $\mathbf{x}$ is a surface

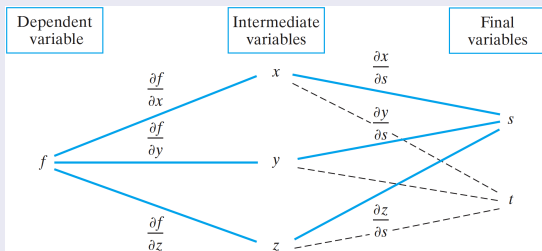
- Suppose  $X$  is open in  $\mathbb{R}^3$  and  $T$  is open in  $\mathbb{R}^2$ .
- Suppose  $f : X \subseteq \mathbb{R}^3 \rightarrow \mathbb{R}$  and  $\mathbf{x} : T \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}^3$  are such that the range of  $\mathbf{x}$  is contained in  $X$ .
- Then, the composite  $f \circ \mathbf{x} : T \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}$  can be formed:



- The range of  $\mathbf{x}$ ,  $\mathbf{x}(T)$ , is just a **surface** in  $\mathbb{R}^3$ .
- So  $f \circ \mathbf{x}$  can be thought of as an appropriate **"temperature function"** restricted to this surface.

## The Chain Rule when $\mathbf{x}$ is a surface

- Let use  $\mathbf{x} = (x, y, z)$  to denote the vector variable in  $\mathbb{R}^3$  and  $\mathbf{t} = (s, t)$  for the vector variable in  $\mathbb{R}^2$ .
- We can write a chain rule formula from the next hierarchy diagram:





## The Chain Rule when $\mathbf{x}$ is a surface

- The following formulas hold:

$$\frac{\partial f}{\partial s} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial s}$$

$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial t} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial t}$$

### Example 3

- Suppose

$$f(x, y, z) = x^2 + y^2 + z^2 \quad \text{and} \quad \mathbf{x}(s, t) = (s \cos t, e^{st}, s^2 - t^2)$$

- Then

$$h(s, t) = f \circ \mathbf{x}(s, t) = s^2 \cos^2 t + e^{2st} + (s^2 - t^2)^2$$

$$\frac{\partial h}{\partial s} = \frac{\partial(f \circ \mathbf{x})}{\partial s} = 2s \cos^2 t + 2te^{2st} + 4s(s^2 - t^2)$$

$$\frac{\partial h}{\partial t} = \frac{\partial(f \circ \mathbf{x})}{\partial t} = -2s^2 \cos t \sin t + 2se^{2st} - 4t(s^2 - t^2)$$

## Example 3

$$f(x, y, z) = x^2 + y^2 + z^2 \quad \text{and} \quad \mathbf{x}(s, t) = (s \cos t, e^{st}, s^2 - t^2)$$

- On the other hand

$$\begin{aligned} \frac{\partial f}{\partial x} &= 2x, & \frac{\partial f}{\partial y} &= 2y, & \frac{\partial f}{\partial z} &= 2z \\ \frac{\partial x}{\partial s} &= \cos t, & \frac{\partial y}{\partial s} &= te^{st}, & \frac{\partial z}{\partial s} &= 2s \\ \frac{\partial x}{\partial t} &= -s \sin t, & \frac{\partial y}{\partial t} &= se^{st}, & \frac{\partial z}{\partial t} &= -2t \end{aligned}$$

- So for example,

$$\begin{aligned} \frac{\partial h}{\partial s} &= \frac{\partial(f \circ \mathbf{x})}{\partial s} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial s} \\ &= 2x(\cos t) + 2y(te^{st}) + 2z(2s) \\ &= 2s \cos t(\cos t) + 2e^{st}(te^{st}) + 2(s^2 - t^2)(2s) \\ &= 2s \cos^2 t + 2te^{2st} + 4s(s^2 - t^2) \end{aligned}$$

## The Chain Rule in Multiple Variables

$$\mathbf{f} : X \subseteq \mathbb{R}^m \rightarrow \mathbb{R}^p, \quad \mathbf{x} : T \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m, \quad h = \mathbf{f} \circ \mathbf{x} : T \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^p$$

$$\text{Then, } \frac{\partial h_i}{\partial t_j} = \sum_{k=1}^m \frac{\partial f_i}{\partial x_k} \frac{\partial x_k}{\partial t_j}, \quad \text{for } i = 1, 2, \dots, p \text{ and } j = 1, \dots, n$$

- Knowing that:
  - the  $ij$ th entry of the matrix  $D\mathbf{h}(\mathbf{t})$  is  $\partial h_i / \partial t_j$
  - the  $ik$ th entry of the matrix  $D\mathbf{f}(\mathbf{x})$  is  $\partial f_i / \partial x_k$
  - the  $kj$ th entry of the matrix  $D\mathbf{x}(\mathbf{t})$  is  $\partial x_k / \partial t_j$
- We see that this formula expresses the following equation of matrices

$$D\mathbf{h}(\mathbf{t}) = D(\mathbf{f} \circ \mathbf{x})(\mathbf{t}) = D\mathbf{f}(\mathbf{x})D\mathbf{x}(\mathbf{t})$$

A very similar expression to  
the chain rule in one variable

### Example 4

- Suppose  $\mathbf{f} : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  and  $\mathbf{x} : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  are given by

$$\mathbf{f}(x_1, x_2, x_3) = (x_1 - x_2, x_1 x_2 x_3)$$

$$\mathbf{x}(t_1, t_2) = (t_1 t_2, t_1^2, t_2^2)$$

- Then  $\mathbf{f} \circ \mathbf{x} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is given by

$$\mathbf{f} \circ \mathbf{x}(t_1, t_2) = (t_1 t_2 - t_1^2, t_1^3 t_2^3)$$

- So that

$$D(\mathbf{f} \circ \mathbf{x})(\mathbf{t}) = \begin{bmatrix} t_2 - 2t_1 & t_1 \\ 3t_1^2 t_2^3 & 3t_1^3 t_2^2 \end{bmatrix}$$

## Example 4

- Suppose  $\mathbf{f} : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  and  $\mathbf{x} : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  are given by

$$\mathbf{f}(x_1, x_2, x_3) = (x_1 - x_2, x_1 x_2 x_3)$$

$$\mathbf{x}(t_1, t_2) = (t_1 t_2, t_1^2, t_2^2)$$

- On the other hand

$$D\mathbf{f}(\mathbf{x}) = \begin{bmatrix} 1 & -1 & 0 \\ x_2 x_3 & x_1 x_3 & x_1 x_2 \end{bmatrix} \quad \text{and} \quad D\mathbf{x}(\mathbf{t}) = \begin{bmatrix} t_2 & t_1 \\ 2t_1 & 0 \\ 0 & 2t_2 \end{bmatrix}$$

- So that, after substituting for  $x_1, x_2,$  and  $x_3$ , the product matrix is

$$\begin{aligned} D\mathbf{f}(\mathbf{x})D\mathbf{x}(\mathbf{t}) &= \begin{bmatrix} t_2 - 2t_1 & t_1 \\ x_2 x_3 t_2 + 2x_1 x_3 t_1 & x_2 x_3 t_1 + 2x_1 x_2 t_2 \end{bmatrix} \\ &= \begin{bmatrix} t_2 - 2t_1 & t_1 \\ t_1^2 t_2^3 + 2t_1^2 t_2^3 & t_1^3 t_2^2 + 2t_1^3 t_2^2 \end{bmatrix} \end{aligned}$$

### Theorem 5.3: The (general) Chain Rule

- Suppose  $X$  is an open set in  $\mathbb{R}^m$  and  $T$  is an open set in  $\mathbb{R}^n$ .
- Suppose functions  $\mathbf{f} : X \subseteq \mathbb{R}^m \rightarrow \mathbb{R}^p$  and  $\mathbf{x} : T \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$  are defined so that  $\text{range } \mathbf{x} \subseteq X$ .
- Suppose  $\mathbf{x}$  is differentiable at  $\mathbf{t}_0 \in T$  and  $\mathbf{f}$  is differentiable at  $\mathbf{x}_0 = \mathbf{x}(\mathbf{t}_0)$ .
- Then, the composite  $\mathbf{f} \circ \mathbf{x}$  is differentiable at  $\mathbf{t}_0$ , and

$$D(\mathbf{f} \circ \mathbf{x})(\mathbf{t}_0) = D\mathbf{f}(\mathbf{x}_0)D\mathbf{x}(\mathbf{t}_0)$$

### Remark

- [Theorem 5.3](#) requires  $\mathbf{f}$  only to be differentiable at the point in question, not to be of class  $C^1$ .
- [Theorem 5.3](#) includes all the special cases of the chain rule we have discussed.

## Example 5

- Let  $\mathbf{f} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be defined by

$$\mathbf{f}(x, y) = (x - 2y + 7, 3xy^2)$$

- Suppose that  $\mathbf{g} : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  is differentiable at  $(0, 0, 0)$ .
- Suppose also that we know that

$$\mathbf{g}(0, 0, 0) = (-2, 1) \text{ and } D\mathbf{g}(0, 0, 0) = \begin{bmatrix} 2 & 4 & 5 \\ -1 & 0 & 1 \end{bmatrix}$$

- We use this information to determine  $D(\mathbf{f} \circ \mathbf{g})(0, 0, 0)$ .
- Regarding [Theorem 5.3](#),  $\mathbf{f} \circ \mathbf{g}$  must be differentiable at  $(0, 0, 0)$ , and

$$D(\mathbf{f} \circ \mathbf{g})(0, 0, 0) = D\mathbf{f}(\mathbf{g}(0, 0, 0))D\mathbf{g}(0, 0, 0) = D\mathbf{f}(-2, 1)D\mathbf{g}(0, 0, 0)$$



## Example 5

$$\mathbf{f}(x, y) = (x - 2y + 7, 3xy^2)$$

$$\mathbf{g}(0, 0, 0) = (-2, 1) \text{ and } D\mathbf{g}(0, 0, 0) = \begin{bmatrix} 2 & 4 & 5 \\ -1 & 0 & 1 \end{bmatrix}$$

- Since we know  $\mathbf{f}$  completely, it is easy to compute that

$$D\mathbf{f}(x, y) = \begin{bmatrix} 1 & -2 \\ 3y^2 & 6xy \end{bmatrix} \text{ so that } D\mathbf{f}(-2, 1) = \begin{bmatrix} 1 & -2 \\ 3 & -12 \end{bmatrix}$$

- Thus

$$D(\mathbf{f} \circ \mathbf{g})(0, 0, 0) = \begin{bmatrix} 1 & -2 \\ 3 & -12 \end{bmatrix} \begin{bmatrix} 2 & 4 & 5 \\ -1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 4 & 3 \\ 18 & 12 & 3 \end{bmatrix}$$

We did not need to know anything about the differentiability of  $\mathbf{g}$  other than at the point  $(0, 0, 0)$