



Escola d'Enginyeria de Telecomunicació
i Aeroespacial de Castelldefels
UNIVERSITAT POLITÈCNICA DE CATALUNYA

Aerodynamics (AER)

LESSON 1: INTRO TO AERODYNAMICS - GENERAL EQUATIONS -

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CONTENTS

LESSON 1: INTRO – GENERAL EQUATIONS

- Introduction
- General Eq. of the fluid motion: Navier-Stokes Eq.:
 - continuity equation
 - Newton's 2nd Principle
 - energy equation
 - orders of magnitude of the various terms
- Simplifications in conventional aeronautics
- Irrotational motion and velocity potential:
 - from Euler Eq. to Euler-Bernoulli Eq. and Bernoulli Eq.
 - differential Eq. for the velocity potential

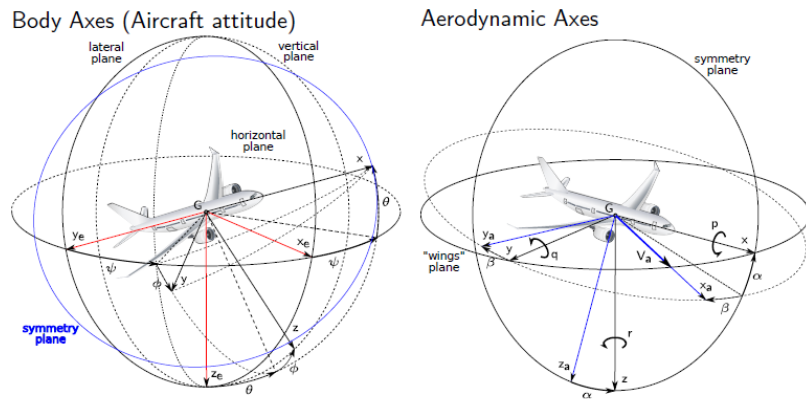
INTRO – GENERAL EQUATIONS

INTRODUCTION

- **Global objective** → to calculate aerodynamic forces on aircraft in horizontal motion in steady atmosphere ($V_w = 0$)
- **Wind reference frame:**
 - bonded to aircraft (origin in CG or elsewhere in symmetry plane)
 - x_w -axis → along direction of incident flow
 - z_w -axis → contained in vertical plane, opposite to gravity
 - y_w -axis → chosen such that we have a dextrogyre reference frame
- **Forces:** drag $F_x = D$, lift $F_z = L$, & lateral force $F_y = Q$
- **Hypotheses:** constant mass, rigid body, symmetric aircraft, etc.
- **Fluid properties:** $\rho, T, p \quad \vec{V} = (U_\infty + u_x)\bar{i} + u_y\bar{j} + u_z\bar{k}$

INTRO – GENERAL EQUATIONS

IMPORTANT REFERENCE FRAMES



- ▶ ψ : yaw angle or rumb
- ▶ θ : pitch angle
- ▶ ϕ : roll angle

- ▶ α : angle of attack
 - ▶ β : sideslip angle
- (Mellibovsky, F.P., *Flight Principles*, 2016)

INTRO – GENERAL EQUATIONS

Origin: Gravity Centre.

Earth Axes:

- ▶ z_e : Vertical axis. Oriented by local gravitational acceleration vector.
- ▶ x_e : Latitude axis. South-North direction.
- ▶ y_e : Longitude axis. West-East direction.

Body Axes:

- ▶ x : Fuselage (roll) axis. Forward pointing, aligned with the fuselage.
- ▶ z : Belly (yaw) axis. In the airplane symmetry plane.
- ▶ y : Right wing (pitch) axis. Completing a direct orthonormal basis, aligned with the right wing.

Aerodynamic Axes:

- ▶ x_a : Oriented by the aerodynamic velocity vector.
- ▶ z_a : In the airplane symmetry plane.
- ▶ y_a : Completes a direct orthonormal basis.

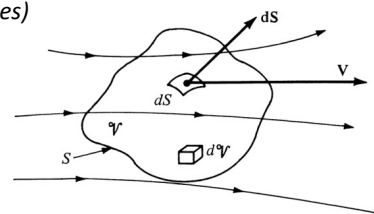
(Mellibovsky, F.P., *Flight Principles*, 2016)

INTRO – GENERAL EQUATIONS

GENERAL EQUATIONS OF THE FLUID MOTION (1)

In aerodynamics, **media satisfy the continuum hypothesis**:

The fluid is treated as a continuum by viewing it at a coarse enough scale that the airfoil surface cannot distinguish the individual molecular collisions. One can then assign a local average flow velocity at a point by averaging over the much faster, violently fluctuating molecular velocities. Similarly, one defines a locally averaged density, pressure, etc. These locally averaged quantities then vary smoothly all over the fluid domain on the macroscopic scale (except when crossing shock waves)



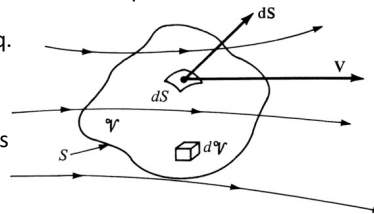
(Anderson, J.D., *Fundamentals of Aerodynamics*, 2001)

INTRO – GENERAL EQUATIONS

GENERAL EQUATIONS OF THE FLUID MOTION (2)

In aerodynamics, **continuous media satisfy:**

- **Law of mass conservation** → Continuity Eq.
- **Newton's 2nd Principle** → Momentum conservation Eqs.
- **1st Law of Thermodynamics** → Energy Eq.
- **2nd Law of Thermodynamics**
- **Constitutive laws** → secondary principles that characterize the media:
 - Ex. 1: State Eqs. for fluids
 - Ex. 2: Hooke's Law for linear elastic solids
 - Ex. 3: Navier-Stokes' Law of viscosity, valid for many viscous fluids



(Anderson, J.D., *Fundamentals of Aerodynamics*, 2001)

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CONTINUITY EQUATION (1)

“The net mass flux through the surface of the control vol. is equal to the temporal variation of the mass inside the control vol.”

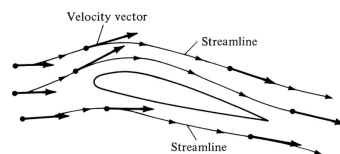
• **Integral formulation** →
$$\frac{d}{dt} \int_D \rho dv + \int_S \rho \vec{V} \cdot \vec{n} ds = 0$$

Gauss-Ostrogradski (Divergence) Theorem

$$\int_D \nabla \cdot (\rho \vec{V}) dv =$$

• **Differential formulation** →
$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{V}) = \frac{D\rho}{Dt} + \rho \nabla \cdot \vec{V} = 0$$

$$\frac{D\rho}{Dt} = \frac{\partial \rho}{\partial t} + \vec{V} \cdot \nabla \rho$$



INTRO – GENERAL EQUATIONS

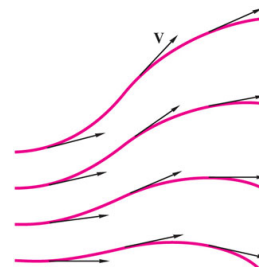
CONTINUITY EQUATION (2)

The substantive or Stokes derivative: $\frac{D\rho}{Dt} = \frac{\partial\rho}{\partial t} + \vec{V} \cdot \nabla\rho$

“A derivative taken with respect to a moving coordinate system, also called the Lagrangian derivative, substantive derivative (Tritton 1989), or Stokes derivative (Kaplan 1991, pp. 189-191).”

- Contribution due to temporal variation (non-stationary problem) $\frac{\partial\rho}{\partial t}$

- Contribution due to variation along the streamline (non-uniform problem) $\vec{V} \cdot \nabla\rho$



Please, note the difference between **streamline** & **particle trajectory**

(White, F.M., *Fluid Mechanics*, 6th ed., Boston, USA: McGraw-Hill, 2003, p. 866)

INTRO – GENERAL EQUATIONS

NEWTON’S 2nd PRINCIPLE (1)

“The temporal variation of momentum of the fluid inside a control vol. is equal to the sum of the external forces acting on the vol.”

- Integral formulation

$$\frac{d}{dt} \int_D \rho \vec{V} dv + \int_S \rho \vec{V} (\vec{V} \cdot \vec{n}) ds = - \int_S p \vec{n} ds + \int_S \vec{n} \cdot \tau' ds + \int_D \rho \vec{F}_m dv$$

- Differential formulation

$$\frac{\partial\rho}{\partial t} + \nabla \cdot (\rho \vec{V}) = 0 \quad \longrightarrow \quad \rho \frac{D\vec{V}}{Dt} = -\nabla p + \nabla \cdot \tau' + \rho \vec{F}_m$$

(we simplify with the Continuity Eq.)

Gauss-Ostrogradski
Theorems

INTRO – GENERAL EQUATIONS

NEWTON'S 2nd PRINCIPLE (2)

“The temporal variation of momentum of the fluid inside a control vol. is equal to the sum of the external forces acting on the vol.”

- Differential formulation

$$\rho \frac{D\vec{V}}{Dt} = -\nabla p + \nabla \cdot (\tau') + \rho \overline{F_m}$$

Note: For a viscous fluid, it is necessary to model the dissipative action of viscosity through the **viscous stress tensor** → e.g., **Navier-Stokes model**

$$\tau' = \zeta(\nabla \cdot \vec{V})I + \mu \left[(\nabla \vec{V} + \nabla \vec{V}^T) - \left(\frac{2}{3}\right)(\nabla \cdot \vec{V})I \right]$$

INTRO – GENERAL EQUATIONS

ENERGY EQUATION

“In a control vol., there is balance between the temporal variation of total energy & the work produced by external forces plus the heat received from the exterior, per unit time”

- Differential formulation – version 1 (from the 1st Law of Thermodynamics)

$$de = dw + dq \longrightarrow \rho \frac{De}{Dt} = \nabla \cdot (k\nabla T) - p\nabla \cdot \vec{V} + \Phi_v - \nabla \cdot \overline{q_r} + Q_{rq}$$

- Differential formulation – version 2 (we combine the Continuity Eq. & the 2nd Law of Thermodynamics with the previous expression)

$$de = Tds - pdv \longrightarrow \rho T \frac{Ds}{Dt} = \nabla \cdot (k\nabla T) + \Phi_v - \nabla \cdot \overline{q_r} + Q_{rq}$$

$$\Phi_v = \nabla \cdot (\tau' \cdot \vec{v})$$

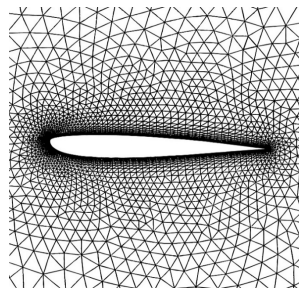
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HOW TO SOLVE THE FLUID PROBLEM?

No general analytical (exact) solution satisfies the Navier-Stokes Eqs.

Particular cases allow simplifications: procedure:

- is there any term negligible compared to the others? If so → eliminate it!
- are new Eqs. solvable analytically? only in some simple cases → yes! 😊
in most cases → still no! 😞

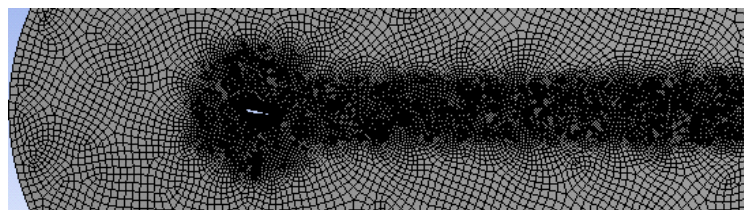


Then, we use numerical methods (the fluid domain is discretized into multiple cells and we solve the Navier-Stokes Eqs. or simplified versions in, e.g., the nodes of these cells):

computational fluid dynamics (CFD)

INTRO – GENERAL EQUATIONS

ORDER OF MAGNITUDE OF TERMS IN EQS.



Newton's 2nd Principle: orders of magnitude:

- pressure term → rel. to inverse of M^2
- viscous term → rel. to inverse of Re
- mass or vol. forces → rel. to inverse of Fr
- non-stationary term → rel. to St

$$M = U_\infty/a$$

$$Re = \rho U_\infty L/\mu$$

$$Fr = U_\infty^2/gL$$

$$St = fL/U_\infty = t_v/t_c$$

$$\rho \frac{D\vec{V}}{Dt} = -\nabla p + \nabla \cdot \tau' + \rho \vec{F}_m$$

INTRO – GENERAL EQUATIONS

SIMPLIFICATIONS IN CONVENTIONAL AERONAUTICS

Newton's 2nd Principle: which terms can we simplify?

- **pressure term** → the term we want to compute, as important as the most important term ($M \approx 1$) → **reaction** that equilibrates the **other terms**
- **viscous term** → negligible if $Re \gg 1$, **except in boundary layer (BL) & wake**
- **mass or vol. forces** → negligible if $Fr \gg 1$, i.e., if the flight is due to **dynamic effects** & not **static effects** (**buoyancy forces/Archimedes' Principle**)
 - **exceptions** → not negligible for balloons & dirigibles (Zeppelins)

$$\rho \frac{D\bar{V}}{Dt} = \underbrace{-\nabla p}_{\text{pressure}} + \underbrace{\nabla \cdot \tau'}_{\text{viscous}} + \underbrace{\rho \bar{F}_m}_{\text{mass forces}} \xrightarrow{Re, Fr \gg 1; M \approx 1} \boxed{\rho \frac{D\bar{V}}{Dt} = -\nabla p}$$

(Euler Eq.)

$$\frac{D\bar{V}}{Dt} = \frac{\partial \bar{V}}{\partial t} + \bar{V} \cdot \nabla \bar{V} = \frac{\partial \bar{V}}{\partial t} + \frac{1}{2} \nabla (\bar{V} \cdot \bar{V}) - \bar{V} \times (\nabla \times \bar{V}) = -\frac{1}{\rho} \nabla p$$

INTRO – GENERAL EQUATIONS

SIMPLIFICATIONS IN CONVENTIONAL AERONAUTICS

Energy Eq.: orders of magnitude + which terms can we simplify?

- **heat flux from radiation** → negligible
- **heat flux from chemical reaction** → negligible
 - **exception** → not negligible in re-entry of spacecraft ($M > 5$)

$$\rho T \frac{Ds}{Dt} = \nabla \cdot (k \nabla T) + \Phi_v - \underbrace{\nabla \cdot \bar{q}_r}_{\text{radiation}} + \underbrace{Q_{rq}}_{\text{chem. reaction}} \longrightarrow \rho T \frac{Ds}{Dt} = \nabla \cdot (k \nabla T) + \Phi_v$$

- **heat flux from conduction** → negligible if $Pr \cdot Re \gg 1$ $Pr = \mu c_p / k \approx 1$
- **Rayleigh dissipation function** → negligible if $Re/M^2 \gg 1$

$$\rho T \frac{Ds}{Dt} = \underbrace{\nabla \cdot (k \nabla T)}_{\text{conduction}} + \underbrace{\Phi_v}_{\text{viscous}} \longrightarrow \rho T \frac{Ds}{Dt} = 0 \longrightarrow \boxed{\frac{Ds}{Dt} = \frac{\partial s}{\partial t} + \bar{V} \cdot \nabla s = 0}$$

Note: If entropy is constant in the infinite upwind, this constant is the same for all the stream lines, **except** in **boundary layer (BL) & shock waves**

INTRO – GENERAL EQUATIONS

SIMPLIFICATIONS IN CONVENTIONAL AERONAUTICS

Energy Eq. (simplification):

Barotropic relation → unique relation between p & ρ , independent of T :

- incompressible (e.g., liquids) → $\rho = \text{constant}$; independent of p & T
- compressible → only in **isentropic (adiabatic & reversible)** problems:

$$s = \text{constant} \rightarrow \text{E.g.: perfect gases} \rightarrow \frac{p}{\rho^\gamma} = ct$$

State Eq. (constitutive Eq.):

- incompressible (e.g., $M < 0.3$) → $\rho = ct$
- compressible: perfect gases model → $\frac{p}{\rho} = R'T$ $R' = \frac{R}{M}$

INTRO – GENERAL EQUATIONS

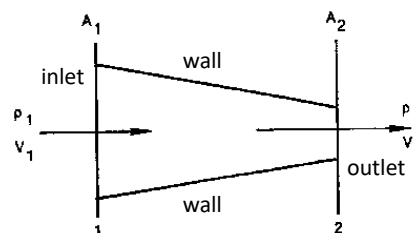
CONTINUITY EQUATION – EXERCISE

“The net mass flux through the surface of the control vol. is equal to the temporal variation of the mass inside the control vol.”

- **Integral formulation** → $\frac{d}{dt} \int_D \rho dv + \int_S \rho \vec{V} \cdot \vec{n} ds = 0$

- **Ex.:** uniform stationary problem (non-porous walls):

- case 1: with viscosity
- case 2: without viscosity
- case 3: with porous walls

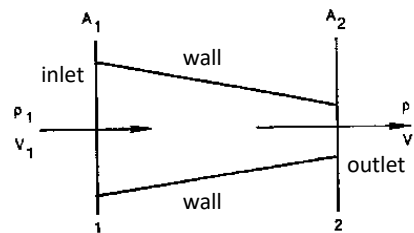


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CONTINUITY EQUATION – QUESTION

For an air flow in a duct with $St \ll 1$ and $M \ll 1$, if the inlet cross sectional area A_1 is twice as large as that of the outlet A_2 , the inlet airflow velocity:

- is twice the outlet airflow velocity
- is equal to the outlet airflow velocity
- is half the outlet airflow velocity
- We don't have enough information to choose
- None of the others



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19

INTRO – GENERAL EQUATIONS

IRROTATIONAL MOTION & VELOCITY POTENTIAL

Circulation & Stokes Theorem: $\Gamma = \oint_C \vec{v} \cdot d\vec{l} = \int_S (\nabla \times \vec{v}) \cdot \vec{n} ds$

Circulation null (global vorticity null) \rightarrow irrotational motion

Velocity potential: $\Phi = \Phi(x, y, z, t) \longrightarrow \vec{v} = \nabla\Phi$

Conditions for the velocity potential to exist:

- Bjerknes-Kelvin Theorem:** If viscosity & conduction are negligible, mass forces are derived from a potential (e.g., are negligible), & fluid is barotropic \rightarrow **circulation is constant**
- If velocity is uniform & stationary (constant) in the infinite (i.e., aircraft flies in steady atmosphere) \rightarrow **circulation is null**
- As circulation is constant = 0 \rightarrow **global vorticity must be null** for all the fluid field \rightarrow we have **irrotational motion & velocity potential**

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20

INTRO – GENERAL EQUATIONS

EULER-BERNOULLI EQUATION

Euler Eq. particularized for irrotational flow:

$$\frac{\partial \vec{V}}{\partial t} + \frac{1}{2} \nabla(\vec{V} \cdot \vec{V}) - \vec{V} \times (\nabla \times \vec{V}) = -\frac{1}{\rho} \nabla p$$

$$\nabla \times \vec{V} = 0$$

$$\Phi = \Phi(x, y, z, t)$$

$$\vec{V} = \nabla \Phi$$

• incompressible $\rightarrow \rho = ct$

• perfect gases $\rightarrow \frac{p}{\rho^\gamma} = ct$

(Euler-Bernoulli Eq.)

$$\frac{\partial \Phi}{\partial t} + \frac{1}{2} |\nabla \Phi|^2 + \int \frac{dp}{\rho} = C(t)$$

$$\frac{\partial \Phi}{\partial t} + \frac{1}{2} |\nabla \Phi|^2 + \frac{p}{\rho} = C'(t)$$

$$\frac{\partial \Phi}{\partial t} + \frac{1}{2} |\nabla \Phi|^2 + \frac{a^2}{\gamma - 1} = C''(t)$$

INTRO – GENERAL EQUATIONS

BERNOULLI EQUATION

Euler-Bernoulli Eq. particularized for stationary flow:

• incompressible \rightarrow

$$\frac{1}{2} \rho_\infty |\nabla \Phi|^2 + p = \frac{1}{2} \rho_\infty U_\infty^2 + p_\infty$$

• perfect gases \rightarrow

$$\frac{1}{2} |\nabla \Phi|^2 + \frac{a^2}{\gamma - 1} = \frac{1}{2} U_\infty^2 + \frac{a_\infty^2}{\gamma - 1}$$

(Bernoulli Eq.)

$$a = \sqrt{\gamma R' T} = \sqrt{\gamma \frac{p}{\rho}} \quad R' = \frac{R}{M}$$

INTRO – GENERAL EQUATIONS

PROCEDURE TO FULFIL OUR OBJECTIVE

To compute the aerodynamic forces (ρ distrib.) on the airfoil:

1. compute **velocity potential** from differential Eq. for velocity potential
2. then compute **velocity field** from velocity potential
3. then compute **pressure field** by application of Bernoulli Eq.:

$$\frac{1}{2} \rho_{\infty} |\nabla\Phi|^2 + p = \frac{1}{2} \rho_{\infty} U_{\infty}^2 + p_{\infty}$$

INTRO – GENERAL EQUATIONS

DIFFERENTIAL EQ. FOR VELOCITY POTENTIAL

We obtain the **differential Eq. for the velocity potential** by **eliminating ρ & V** from the **Continuity Eq. + Euler-Bernoulli Eq.**

recall that this is **only for potential flow** \rightarrow i.e., Bjerknes-Kelvin Theorem must apply & properties in the infinite are uniform & stationary

Further simplification is possible if we can also assume:

- $St \ll 1 \rightarrow$ **stationary** problem
- **low speed: $M < 0.30$** \rightarrow compressibility effects **neglected: $\rho = ct$**

$$\frac{D\rho}{Dt} + \rho \nabla \cdot \vec{V} = 0 \xrightarrow{\rho = ct} \nabla \cdot \vec{V} = 0 \xrightarrow{\vec{V} = \nabla\Phi} \nabla \cdot (\nabla\Phi) = \Delta\Phi = 0$$

(Laplace Eq.)

$$\Delta\Phi = \frac{\partial^2\Phi}{\partial x^2} + \frac{\partial^2\Phi}{\partial y^2} + \frac{\partial^2\Phi}{\partial z^2} = 0$$

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EXERCISE 1.0 – CONTINUITY EQUATION



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25



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**THANKS FOR YOUR ATTENTION
ANY QUESTION?**

INTRO – GENERAL EQUATIONS

MACH NUMBER (1)

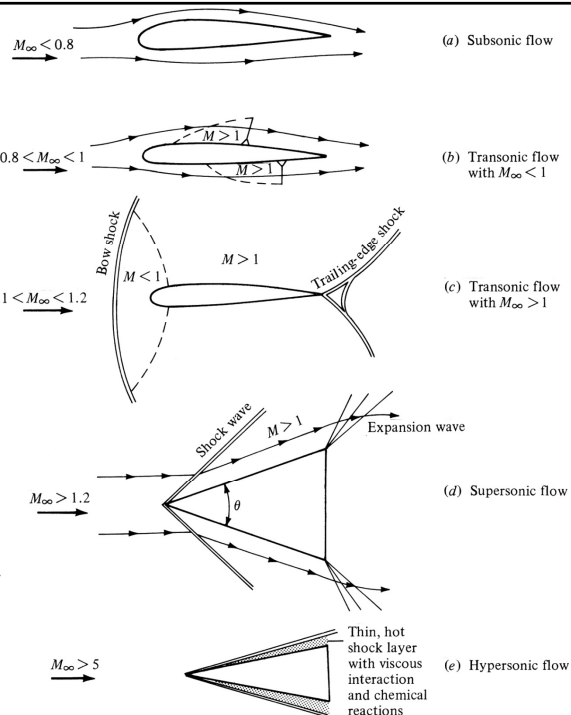
Mach number M : ratio flow velocity-to-speed of sound:

$$M = \frac{U_\infty}{a} \qquad a = \sqrt{\gamma R' T} = \sqrt{\gamma \frac{p}{\rho}} \qquad R' = \frac{R}{M}$$

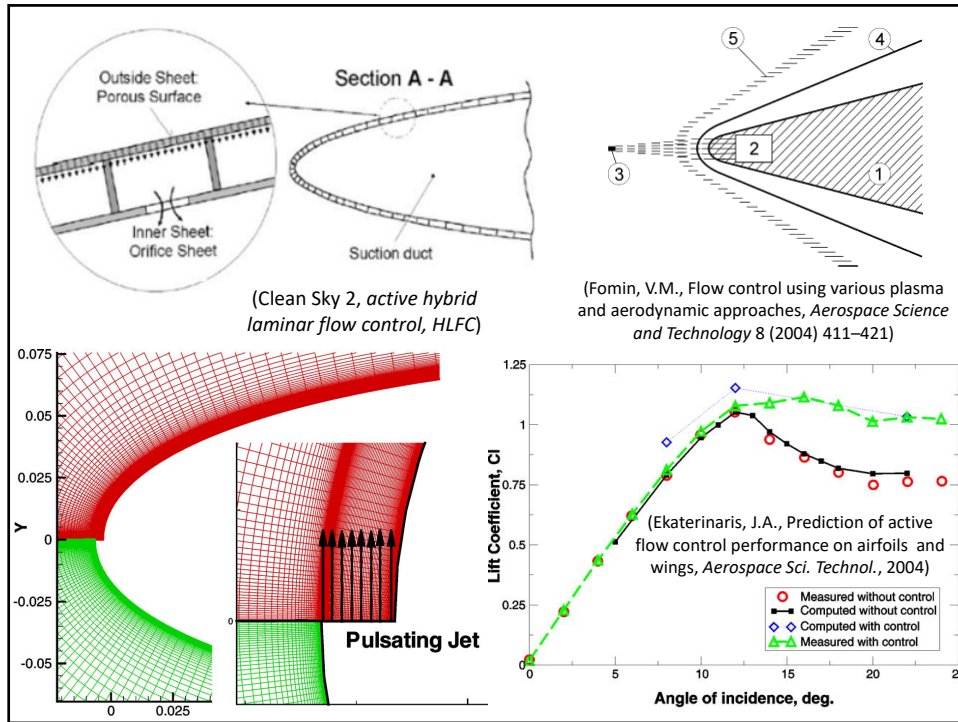
- uncompressible/low subsonic $M < 0.30$ (or 0.40 or 0.50)
- compressible/high subsonic $0.30 < M < 0.75$
- transonic $0.75 < M < 1.20$
- sonic regime $M = 1.00$
- supersonic $1.20 < M < 5.00$
- Hypersonic $M > 5.00$

GENERAL EQS.

MACH NUMBER (2)



(Anderson, J.D., *Fundamentals of Aerodynamics*, 2001)



Parameter	Definition	Qualitative ratio of effects	Importance
Reynolds number	$Re = \frac{\rho UL}{\mu}$	$\frac{\text{Inertia}}{\text{Viscosity}}$	Almost always
Mach number	$Ma = \frac{U}{a}$	$\frac{\text{Flow speed}}{\text{Sound speed}}$	Compressible flow
Froude number	$Fr = \frac{U^2}{gL}$	$\frac{\text{Inertia}}{\text{Gravity}}$	Free-surface flow
Weber number	$We = \frac{\rho U^2 L}{\gamma}$	$\frac{\text{Inertia}}{\text{Surface tension}}$	Free-surface flow
Rossby number	$Ro = \frac{U}{\Omega_{\text{rot}} L}$	$\frac{\text{Flow velocity}}{\text{Coriolis effect}}$	Geophysical flows
Cavitation number (Euler number)	$Ca = \frac{p - p_v}{\rho U^2}$	$\frac{\text{Pressure}}{\text{Inertia}}$	Cavitation
Prandtl number	$Pr = \frac{\mu c_p}{k}$	$\frac{\text{Dissipation}}{\text{Conduction}}$	Heat convection
Eckert number	$Ec = \frac{U^2}{c_p T_0}$	$\frac{\text{Kinetic energy}}{\text{Enthalpy}}$	Dissipation
Specific-heat ratio	$k = \frac{c_p}{c_v}$	$\frac{\text{Enthalpy}}{\text{Internal energy}}$	Compressible flow
Strouhal number	$St = \frac{\omega L}{U}$	$\frac{\text{Oscillation}}{\text{Mean speed}}$	Oscillating flow
Roughness ratio	$\frac{\epsilon}{L}$	$\frac{\text{Wall roughness}}{\text{Body length}}$	Turbulent, rough walls
Grashof number	$Gr = \frac{\beta \Delta T g L^3 \rho^2}{\mu^2}$	$\frac{\text{Buoyancy}}{\text{Viscosity}}$	Natural convection
Rayleigh number	$Ra = \frac{\beta \Delta T g L^3 \rho^2 c_p}{\mu k}$	$\frac{\text{Buoyancy}}{\text{Viscosity}}$	Natural convection
Temperature ratio	$\frac{T_w}{T_0}$	$\frac{\text{Wall temperature}}{\text{Stream temperature}}$	Heat transfer
Pressure coefficient	$C_p = \frac{p - p_\infty}{\frac{1}{2} \rho U^2}$	$\frac{\text{Static pressure}}{\text{Dynamic pressure}}$	Aerodynamics, hydrodynamics
Lift coefficient	$C_L = \frac{L}{\frac{1}{2} \rho U^2 A}$	$\frac{\text{Lift force}}{\text{Dynamic force}}$	Aerodynamics, hydrodynamics
Drag coefficient	$C_D = \frac{D}{\frac{1}{2} \rho U^2 A}$	$\frac{\text{Drag force}}{\text{Dynamic force}}$	Aerodynamics, hydrodynamics
Friction factor	$f = \frac{h_f}{(V^2/2g)(L/d)}$	$\frac{\text{Friction head loss}}{\text{Velocity head}}$	Pipe flow
Skin friction coefficient	$c_f = \frac{\tau_{w0}}{\rho V^2/2}$	$\frac{\text{Wall shear stress}}{\text{Dynamic pressure}}$	Boundary layer flow

(White, F.M., *Fluid Mechanics*, 6th ed., Boston, USA: McGraw-Hill, 2003, p. 866)